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SE-330 MANUAL

NEUTRAL-GROUNDING-RESISTOR MONITOR

REVISION 10-J-062215



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1. GENERAL

1.1 MODERN RESISTANCE-GROUNDED SYSTEMS

A high-resistance-grounded system uses a neutralgrounding resistor (NGR) with a low let-through current to limit ground-fault current. This is an improvement over low-resistance or solidly-grounded systems because, in those systems, a ground-fault flash hazard exists and a ground fault can result in substantial point-of-fault damage. High-resistance grounding eliminates these problems and modern ground-fault protection operates reliably at low current levels. Furthermore, the probability of an arc-flash incident is significantly reduced in a high-resistance-grounded system.

NGR selection depends on system charging current and whether the system is an alarm-only or a tripping system. Alarm-only systems are usually restricted to system voltages up to 5 kV with NGR let-through currents of 5 A or less. Occasionally, alarm-only systems up to 15 kV and up to 10 A are used; however, they are not common because a ground fault on such a system tends to escalate to a phase-to-phase fault before the ground fault can be located and cleared. Consult CEC 10-1102, NEC 250.36, and NEC 250.186 for application details.

System charging current is the capacitive current that flows to ground when a bolted ground fault occurs. This current can be calculated or measured. For small systems, the magnitude of charging current can be conservatively estimated as $\frac{1}{2}$ A per 1,000 kVA on low-voltage systems and 1 A per 1,000 kVA on medium-voltage systems.

In an alarm-only system or in a tripping system without selective coordination, choose an NGR with a let-through current larger than the system charging current and set the pick-up current of ground-fault devices at or below 50% of the NGR let-through current.

In a tripping system with selective coordination, use ground-fault devices with a definite-time characteristic to achieve time coordination. Use the same pick-up current for all ground-fault devices—this value must be larger than the charging current of the largest feeder. Select an NGR with a let-through current between five and 10 times the pick-up current of the ground-fault devices.

Do not use a grounding transformer with a low-voltage resistor:

- The combined cost of a transformer and a low-voltage resistor is more than the cost of a resistor rated for line-to-neutral voltage.
- A transformer saturated by a ground fault through a rectifier can make ground-fault protection inoperative.
- Transformer inrush current up to 12 times rated current can cause a ground-fault voltage larger than expected.
- A parallel transformer winding makes it difficult to monitor NGR continuity.

• A transformer can provide the inductance necessary to cause ferroresonance if the NGR opens.

Following these guidelines will reduce the flash hazard, reduce point-of-fault damage, achieve reliable groundfault protection, and ensure a stable system not subject to ferroresonance.

1.2 SE-330 NGR MONITORING

The SE-330 is a microprocessor-based neutralgrounding-resistor monitor that detects NGR failures and ground faults in resistance-grounded systems. The SE-330 measures NGR resistance, NGR current, and transformer or generator neutral-to-ground voltage. The components required to monitor an NGR are an SE-330, a 20- or 100-k Ω ER-series sensing resistor, and a current transformer (CT).

Power-circuit elements, other than neutral-connected NGR's, that purposefully connect the power system to ground are often not compatible with SE-330 NGR monitoring. These elements include single-phase grounding transformers, grounded-wye-primary potential transformers (PT's), and grounded-wye-primary power transformers.

The SE-330 continuously measures NGR resistance in an unfaulted system. It will trip on resistor fault if NGR resistance varies from its calibrated value. When a ground fault occurs, voltage is present on the neutral and NGR current will flow if the NGR is healthy. The SE-330 will trip on ground fault if fault current exceeds the GF TRIP LEVEL setting for an interval equal to the GF TRIP TIME setting. However, if the NGR fails open during a ground fault, it is possible for fault resistance to satisfy the NGR resistance measurement. To detect this double-fault condition, the SE-330 measures neutral voltage. If neutral voltage exceeds the V_N TRIP LEVEL setting and if NGR current is less than 5% of the current transformer (CT) rating, the SE-330 will trip on resistor fault. If the resistor-fault circuit is tripped and the neutral voltage exceeds the V_N TRIP LEVEL setting for an interval greater than the GF TRIP TIME setting, the ground-fault circuit will also trip.

Ground-fault current is sensed by a CT with a 1- or 5-A secondary, or by a CT (EFCT-x or SE-CS30-x) with a 50-mA secondary. The trip level of the ground-fault circuit is adjustable from 2 to 100% of the CT rating and trip time is adjustable from 0.1 to 10.0 seconds.

The SE-330 has four output relays. Relay K1 can be assigned a trip or a pulsing function. Relays K2 and K3 provide ground-fault and resistor-fault indication. K4 is a solid-state relay that provides UNIT HEALTHY indication. When relay K1 is assigned the trip function, it will operate on either a resistor fault or ground fault, and it can be set to operate in the fail-safe or non-fail-safe mode for undervoltage or shunt-trip applications. When the pulsing function is selected, relay K1 is used to control a contactor to assist in locating faults.

Additional features include LED trip indication, trip memory, front-panel and remote reset, 4-20-mA analog output, trip event recorder, USB local communications, microSD[™] data logging, and optional network communications.

The SE-330 provides additional features over the SE-330 legacy model (revision 04 or less):

- When the trip level is set to MEM, the ground-fault trip setting is defined by an internal non-volatile memory variable. Range is 2 to 100% in 1% increments of the CT-primary rating.
- Indication relays can be set to fail-safe or non-failsafe.
- The number of trip records has been increased to 100 and includes date and time stamping.
- A microSD[™] card interface can be used for longterm data logging and firmware updates. A microSD[™] card and a microSD-to-SD adapter is included. See Section 4.1.
- For ease of connection to new devices, the RS-232 interface has been replaced by a Mini B USB port.
- Dual Ethernet ports are available with support for fiber-optic and RJ45 interfaces.
- The IEC 61850 protocol has been added.

2. OPERATION

2.1 SETTINGS

2.1.1 GF TRIP TIME

GF TRIP TIME (definite time) is adjustable from 0.1 to 10.0 seconds. Time-coordinated ground-fault protection requires this setting to be longer than the trip times of downstream ground-fault devices.

A trip-time accumulator provides a ground-fault memory function for detection of intermittent faults. The accumulated time increases when a ground fault is detected and decreases when a ground fault is not detected. A trip will eventually occur when the time for fault current above the trip level is greater than the time for fault current below the trip level.

2.1.2 GF TRIP LEVEL

The SE-330 uses a Discrete-Fourier Transform (DFT) Algorithm to measure the fundamental component of NGR current.

Choose an NGR let-through current and a ground-fault trip level according to the guidelines in Section 1.1. Set the ground-fault trip level as a percentage (2 to 100) of the CTprimary rating. When the GF Trip Level is set to MEM, the ground-fault setting stored in non-volatile memory is used. This parameter must be set using a PC running the SE-MON330 software connected to the USB interface. The setting range is 2 to 100% of CT primary rating in 1% increments. The default value is 15%. Inputs are provided for 5-, 1-, and 0.05-A-secondary CT's. Typical values for 5-, 15-, and 25-A tripping systems are shown in Table 1. Ground-fault trip levels for selected CT's are shown in Table 2. For other systems, refer to the NGR Monitor Set-Point Assistant at www.littelfuse.com/ relayscontrols. The Set-Point Assistant is included with the SE-MON330 software.

2.1.3 V_N TRIP LEVEL

The SE-330 uses a DFT algorithm to measure the fundamental component of neutral voltage (V_N) .

If neutral voltage is greater than the V_N TRIP LEVEL setting for the duration of the resistor-fault trip time and ground-fault current is less than 5% of the CT rating, the SE-330 will trip on resistor fault. If the resistor-fault circuit is tripped and the neutral voltage exceeds the V_N TRIP LEVEL setting for an interval greater than the GF TRIP TIME setting, the ground-fault circuit will also trip.

The V_N TRIP LEVEL range is 20 to 2,000 V with switch S5 in the 20-k Ω (Vx1) position, and the range is 100 to 10,000 V with switch S5 in the 100-k Ω (Vx5) position. Calculate the voltage across the NGR when NGR current is equal to the pick-up current of the ground-fault circuit. Set the V_N TRIP LEVEL at the next largest value. See Fig. 1 and Section 2.1.5.5.

Typical values for 5-, 15-, and 25-A tripping systems are shown in Table 1. For an NGR resistance greater than 2 $k\Omega$, use a 100- $k\Omega$ sensing resistor. For other systems, refer to the NGR Monitor Set-Point Assistant at www.littelfuse.com/relayscontrols.

NOTE: A resistor-fault trip is held off if the ground-fault current is above 5% of the CT rating.



| SYSTEM VOLTAGE | NEUTRAL-G RESIS | NEUTRAL-GROUNDING RESISTOR | | SENSING RESISTOR | | V _N TRIP LEVEL |
|-------------------|----------------------|-------------------------------|----------|--------------------------------------|-----------|------------------------------|
| (VOLTS) | CURRENT (AMPERES) | RESISTANCE (OHMS) | MODEL | RESISTANCE (SWITCH S5 SETTING) | (AMPERES) | (VOLTS) |
| 480 | 5 | 55 | ER-600VC | 20 kΩ | 1.0 | 60 |
| 600 | 5 | 69 | ER-600VC | 20 kΩ | 1.0 | 100 |
| 2,400 | 5 | 277 | ER-5KV | 20 kΩ | 1.0 | 340 |
| 4,160 | 5 | 480 | ER-5KV | 20 kΩ | 1.0 | 800 |
| 480 | 15 | 18 | ER-600VC | 20 kΩ | 3.0 | 60 |
| 600 | 15 | 23 | ER-600VC | 20 kΩ | 3.0 | 100 |
| 2,400 | 15 | 92 | ER-5KV | 20 kΩ | 3.0 | 340 |
| 4,160 | 15 | 160 | ER-5KV | 20 kΩ | 3.0 | 800 |
| 7,200 | 15 | 277 | ER-15KV | 100 kΩ | 3.0 | 170x5=850 |
| 14,400 | 15 | 554 | ER-15KV | 100 kΩ | 3.0 | 340x5=1,700 |
| 4,160 | 25 | 96 | ER-5KV | 20 kΩ | 5.0 | 800 |
| 7,200 | 25 | 166 | ER-15KV | 100 kΩ | 5.0 | 170x5=850 |
| 14,400 | 25 | 332 | ER-15KV | 100 kΩ | 5.0 | 340x5=1,700 |
| 25,000 | 25 | 577 | ER-25KV | 100 kΩ | 5.0 | 800x5=4,000 |
| 35,000 | 25 | 808 | ER-35KV | 100 kΩ | 5.0 | 1,200x5=6,000 |

TABLE 1. TYPICAL VALUES FOR TRIPPING SYSTEMS

TABLE 2. GROUND-FAULT TRIP LEVELS FOR SELECTED CT'S

| GF TRIP LEVEL ⁽¹⁾ | EFCT-x 5:0.05 | SE-CS30-x 30:0.05 | 50:1 50:5 | 100:1 100:5 | 200:1 200:5 | 400:1 400:5 |
|---------------------------------|------------------|----------------------|--------------|----------------|----------------|----------------|
| (%) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) |
| 2 | 0.10 | 0.60 | * | * | * | * |
| 4 | 0.20 | 1.20 | * | * | * | 16 |
| 6 | 0.30 | 1.80 | * | * | 12 | 24 |
| 8 | 0.40 | 2.40 | * | 8 | 16 | 36 |
| 10 | 0.50 | 3.00 | 5 | 10 | 20 | 40 |
| 20 | 1.00 | 6.00 | 10 | 20 | 40 | 80 |
| 40 | 2.00 | 12.0 | 20 | 40 | 80 | 160 |
| 60 | 3.00 | 18.0 | 30 | 60 | 120 | 240 |
| 80 | 4.00 | 24.0 | 40 | 80 | 160 | 320 |
| 100 | 5.00 | 30.0 | 50 | 100 | 200 | 400 |

⁽¹⁾ When set to MEM, range is 2 to 100% in 1% increments.

* Setting not recommended.

2.1.4 PULSE-PERIOD ADJUSTMENT

Pulse period is the cycle time of relay K1 when the SE-330 is configured for pulsing operation. Pulse period is adjustable from 1.0 to 3.0 seconds with a fixed duty cycle of 50%. For example, with the 1.0-s setting, relay K1 will alternately be energized for 0.5 seconds and deenergized for 0.5 seconds when pulsing is enabled.

See Section 2.3 for detailed pulsing operation information.

NOTE: For pulsing configuration, set switch S1 to K1 = PULSING and install an external pulse-enable switch.

2.1.5 CONFIGURATION SETTINGS

Eight configuration switches (S1 to S8) and a calibration button are located behind the access cover on the front panel. See Fig. 1.



FIGURE 1. Configuration Switches.

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2.1.5.1 Relay K1 Function (S1)

Set switch S1 to K1 = TRIP to assign the trip function to relay K1 and to activate switch S2. Relay K1 will change state when a resistor-fault or ground-fault trip occurs.

Set switch S1 to K1 = PULSING to configure relay K1 for pulsing operation. See Section 2.3.

2.1.5.2 TRIP-RELAY MODE AND TRIP-MEMORY MODE (S2)

Set switch S2 to select the operating mode of trip relay K1. In the non-fail-safe mode, relay K1 energizes and its contact closes when a trip occurs. The non-fail-safe mode can be used to trip shunt-trip circuit breakers. In the non-fail-safe mode, SE-330 trips are reset when supply voltage is cycled.

In the fail-safe mode, relay K1 energizes and its contact closes if there are no trips. Contacts open if there is a trip, a loss of supply voltage, or a processor failure. In the fail-safe mode, SE-330 trips are not reset when supply voltage is cycled.

NOTE: Switch S2 does not affect the operating modes of relays K2, K3, and K4.

NOTE: Switch S2 only affects relay K1 operating mode when K1 is assigned the trip function (switch S1 set to K1 = TRIP). Trip memory is enabled when K1 is set to the fail-safe mode, regardless of the switch S1 setting.

2.1.5.3 GROUND-FAULT-TRIP LATCH (S3)

Set switch S3 to select latching or non-latching ground-fault-circuit operation. Non-latching operation defeats ground-fault-trip memory. See Sections 2.1.5.2 and 2.4.

2.1.5.4 RESISTOR-FAULT-TRIP LATCH (S4)

Set switch S4 to select latching or non-latching resistor-fault-circuit operation. Non-latching operation defeats resistor-fault-trip memory. See Sections 2.1.5.2 and 2.4

2.1.5.5 SENSING-RESISTOR SELECTION (S5)

Set switch S5 to the resistance of the sensing resistor. For the ER-600VC, ER-5KV, and ER-5WP, select 20 k Ω . For the ER-15KV, ER-25KV, and ER-35KV, select 100 k Ω . Switch S5 sets the resistor-fault trip value and the V_N TRIP LEVEL range. See Section 2.1.3.

2.1.5.6 FREQUENCY (S6)

Set switch S6 to 50 or 60 Hz to tune the digital filter to the line frequency of the monitored system.

2.1.5.7 UPGRADE MODE (S8)

The microSDTM card is used for firmware upgrades. See Section 4.1.2 for upgrade instructions.

NOTE: An upgrade causes an SE-330 restart and this may cycle the output relays.

2.1.6 RESISTOR-FAULT TRIP TIME

The resistor-fault trip time can be adjusted from 12 (default) to 60 seconds using the SE-MON330 software or via network communications.

2.1.7 RESISTOR-FAULT TRIP LEVEL

The resistor-fault trip level can be adjusted using the SE-MON330 software or via network communications. See Section 6.1.

2.1.8 GEO-MAGNETIC FILTER

A low-frequency ground current can be caused by the Earth's magnetic field and from charged clouds passing overhead during a thunderstorm. In some rare conditions, this can cause a false resistor-fault trip. Enabling the geomagnetic filter and increasing the resistor-fault trip time can help counteract these effects.

A trip time of 30 seconds is recommended when the geo-magnetic filter is enabled.

The geo-magnetic filter is disabled by default, but can be enabled using the SE-MON330 software or via network communications.

2.2 CALIBRATION

The SE-330 measures the resistance change of the NGR relative to the NGR-resistance value determined at the time of calibration. When the resistance change is greater than a threshold amount (500 Ω for 20-k Ω systems, 2,500 Ω for 100-k Ω systems), a resistor-fault trip occurs. Calibrate the SE-330 on new installations, if the NGR is changed, or if the sensing resistor is changed.

NOTE: If the SE-330 is not calibrated and is supplied from the load side of the breaker (non-fail-safe mode), calibrate within the resistor-fault trip time after power-up or it may trip and interrupt its supply. See Section 2.1.6.

The CALIBRATION button is located behind the access cover on the front panel, and it is recessed to prevent inadvertent activation.

NOTE: Calibration must be performed with the SE-330 connected to the sensing resistor and NGR of the installed system.

To calibrate, press and hold the CALIBRATION button until the green CALIBRATED LED turns off and returns to on (if the LED is already off, press and hold until the LED turns on). Calibration takes approximately two seconds. If calibration is not successful, a resistor-fault trip occurs, the RESISTOR FAULT TRIP LED will be on, the CALIBRATED LED will be off, and the DIAGNOSTIC LED will flash the calibration-error code. See Section 2.8.

The SE-330 may be calibrated remotely using the SE-MON330 software with the USB interface or the communications options.

If latching resistor fault (switch S4) is selected, the calibration-error code flashes until RESET is pressed even if the CALIBRATED LED is on.

The calibration value is stored in non-volatile memory.

2.3 PULSING OPERATION

If switch S1 is set to K1 = PULSING, pulsing occurs when terminal 16 is connected to terminal 17. Relay K1 operates at a 50% duty cycle and cycle time is adjustable from 1.0 to 3.0 seconds. When terminals 16 and 17 are not connected, K1 is not energized and its contact is open.

Relay K1 can be used to control a contactor rated for use at the line-to-neutral voltage. The contactor causes changes in neutral-to-ground resistance by adding or shorting portions of the NGR. See Section 3.5. Pulsing ground-fault current appears as zero-sequence current upstream from the fault.

Pulsing ground-fault current is distinguishable from charging current and noise, and it can be traced with a clip-on ammeter or current probe. If pulsing current is detected on a cable or conduit, the fault is downstream. Systematic testing allows faults to be located without isolating feeders or interrupting loads.

Stop pulsing when a fault is located.

2.4 TRIP INDICATION AND RESET

Red LED's and indication relays indicate ground-fault and resistor-fault trips. The indication relays K2 (GF) and K3 (RF) operate in fail-safe or non-fail-safe mode. The default is non-fail-safe mode. In this mode, the relays are energized when a fault occurs. The relay mode setting is stored in non-volatile memory and can be set using the SE-MON330 software or network communications.

When a trip occurs with latching operation selected, the SE-330 remains tripped until reset with the front panel button or the remote-reset input. See Sections 2.1.5.3 and 2.1.5.4. Terminals 15 and 16 are provided for remote reset as shown in Fig. 3. The reset circuit responds only to a momentary closure so that a jammed or shorted button does not prevent a trip. The front-panel RESET button is inoperative when terminal 15 is connected to terminal 16. If non-latching operation is selected, trips and corresponding indication automatically reset when the fault clears and power-up trip memory is defeated even when configuration switch S2 is set to fail-safe. The maximum automatic reset time is 2.8 s.

The red DIAGNOSTIC LED annunciates latched calibration-error and remote trips. See Section 2.8.

When supply voltage is applied with switch S2 set to FAIL-SAFE, the SE-330 returns to its state prior to loss of supply voltage unless switch S3 or S4 is set to nonlatching. When supply voltage is applied with switch S2 set to NON-FAIL-SAFE, SE-330 trips are reset. When a local, remote, or network reset is issued, both trip LED's will flash if they are off.

Resistor-fault-trip reset can take up to one second. Resistor-fault trip-memory trip can take up to three seconds after SE-330 power up.

2.5 REMOTE OPERATION

Relays K2 and K3 can be used for remote indication, and terminals 15 and 16 are provided for remote reset. RK-332 Remote Indication and Reset components are shown in Fig. 19. Connect them as shown in Fig. 3. RK-332 components are not polarity sensitive.

Indication relays can be set to fail-safe or non-fail-safe operation using the SE-MON330 software or network communications. The default mode is non-fail-safe. In non-fail-safe mode, relays energize on fault.

Network-enabled SE-330's can be remotely tripped and reset by the network master. The red DIAGNOSTIC LED indicates a network-initiated trip. See Section 2.8. Refer to the appropriate SE-330 communications manual.

2.6 RELAY K1 LED

The yellow RELAY K1 LED follows the state of relay K1 and is on when K1 is energized (contact closed).

2.7 UNIT HEALTHY OUTPUT

UNIT HEALTHY relay K4 is energized when the processor is operating. It can be ordered with N.O. or N.C. contacts. See Section 7.

NOTE: The K4 output changes state momentarily during a processor reset.

NOTE: K4-contact rating is 100 mA maximum.

2.8 DIAGNOSTIC LED

The DIAGNOSTIC LED is used to annunciate trips without individual LED indication. The number of short LED pulses between pauses indicates the cause of the trip. See Section 5.



2.9 ANALOG OUTPUT

An isolated 4–20-mA output indicates NGR current with full-scale output corresponding to the CT rating. An internal 24-Vdc supply allows the analog output to be connected as a self-powered output. Power from an external supply is required for loop-powered operation. See Fig. 2. A PGA-0520 analog meter can be panelmounted to display the NGR current. See Fig. 20 and Section 7.



FIGURE 2. Analog-Output Connections.

3. INSTALLATION

3.1 SE-330

Outline and panel-cutout dimensions for the SE-330 are shown in Fig. 4. To panel mount the SE-330, insert it through the panel cutout and secure it with the four included 8-32 locknuts and flat washers.

If an optional SE-IP65CVR-G Hinged Cover is used, follow the included installation instructions. See Figs. 6 and 7.

All connections to the SE-330 are made with plug-in, wire-clamping terminal blocks. Each plug-in terminal block can be secured to the SE-330 by two captive screws for reliable connections.

Outline dimensions and mounting details for surface mounting the SE-330 are shown in Fig. 5. Fasten the optional surface-mount adapter to the mounting surface and make connections to the adapter terminal blocks. Follow Fig. 5 instructions to mount or remove the SE-330.

Ground terminal 7 (G) and connect terminal 6 (R) to the sensing-resistor R terminal.

Use terminal 1 (L1) as the line terminal on ac systems, or the positive terminal on dc systems. Use terminal 2 (L2/N) as the neutral terminal on ac systems or the negative terminal on dc systems. Connect terminal 3 (\oplus) to ground. Connect terminal 4 (SPG) to terminal 5 (SPGA).

NOTE: Disconnect terminal 1 (L1) and terminal 2 (L2/N) before performing dielectric strength testing of the control panel.



FIGURE 3. SE-330 Connection Diagram.





FIGURE 4. SE-330 Outline and Panel-Mounting Details.





FIGURE 5. SE-330 Outline and Surface-Mounting Details.





FIGURE 6. SE-IP65CVR-G Weatherproof Cover Outline.





FIGURE 7. SE-IP65CVR-G Weatherproof Cover Installation.

3.2 SENSING RESISTOR

Outline and mounting details for the ER-600VC, ER-5KV, ER-5WP, ER-15KV, ER-25KV, and ER-35KV sensing resistors are shown in Figs. 8, 11, 12, 13, 14, and 15. Install the NGR and the sensing resistor near the transformer or generator. When installed outdoors, a sensing resistor must be installed in a suitable enclosure. An optional SE-MRE-600 Moisture-Resistant Enclosure is available for applications which may expose an ER-600VC to moisture. See Figs. 9 and 10. The weather-protected ER-5WP shown in Fig. 12 is an ER-5KV with moisture-resistant terminal covers. Use an ER-5WP in applications in which it might be exposed to The ER-15KV, ER-25KV, and ER-35KV moisture. include moisture-resistant terminal covers. Use suitable water-tight fittings. Ground sensing-resistor terminal G. Pass the sensing-resistor-to-neutral conductor and the NGR-to-neutral conductor through the ground-fault-CT window as shown in Fig. 3. Separately connect sensingresistor terminal N and the NGR to the neutral to include neutral connections in the monitored loop. Alternately, if the NGR connection to system neutral need not be monitored, connect terminal N to the NGR neutral terminal.

If a ground fault in the sensing-resistor conductor is unlikely, a minimal loss of protection will result if it does not pass through the ground-fault-CT window. See Note 3 in Fig. 3.

NOTE: Voltage at terminal N rises to line-to-neutral voltage when a ground fault occurs. The same clearances are required for sensing resistors as for NGR's.

NOTE: A parallel ground path created by moisture can result in a false resistor-fault trip. Moisture sources include wind-driven rain or snow, and condensation. Sensing-resistor terminal R and its connection to SE-330 terminal R, including interposing terminal blocks, must remain dry.

NOTE: The neutral-to-sensing-resistor-terminal-N connection is not a neutral conductor as defined in Canadian Electrical Code Section 10-1108 and National Electrical Code Section 250.36(B). It is not required to be 8 AWG (8.36 mm^2) or larger. Since current through this conductor is always less than 250 mA, a 14 AWG (2.08 mm^2) conductor insulated to the system voltage is more than sufficient.



FIGURE 8. ER-600VC Sensing Resistor.

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FIGURE 10. ER-600VC Installed in SE-MRE-600.





FIGURE 11. ER-5KV Sensing Resistor.





FIGURE 12. ER-5WP Sensing Resistor.









FIGURE 14. ER-25KV Sensing Resistor.





FIGURE 15. ER-35KV Sensing Resistor.



3.3 GROUND-FAULT CT

Select and install a ground-fault CT that will provide the desired trip level. Typically, the CT-primary rating should be approximately equal to the NGR let-throughcurrent rating. This provides an appropriate GF TRIP LEVEL setting range and analog-output scaling. See Sections 2.1.2 and 2.9.

Outline and mounting details for the EFCT- and SE-CS30-series current sensors are shown in Figs. 16, 17, and 18. Ground-fault-CT connections and the typical ground-fault-CT location are shown in Fig. 3.

For SE-325 replacement applications, the existing CT200 current sensor will typically have to be replaced. However, where replacement is not necessary or possible, the CT200 can be connected to either the 1- or 5-A input. This CT has a 200:5 current ratio. If connected to the 1-A input, the ground-fault trip level will be a percentage of 40 A. See Section 2.1.2.

The accuracy of a typical current sensor, including the CT200, decreases below 5% of its current rating. CTprimary current-injection testing is recommended to verify trip levels below 5% of the CT-primary rating. See Section 9.4. Littlfuse Startco current sensors are designed for use at low levels and respond linearly to 2% current rating.

NOTE: The current-sensor insulation class is of no consequence if its secondary is grounded and the conductors through its window are insulated for the system voltage. Medium-voltage systems may require a bushing-type CT.



FIGURE 16. EFCT-1 Ground-Fault Current Sensor.

FIGURE 17. SE-CS30-70 Ground-Fault Current Sensor.

FIGURE 18. EFCT-26 and SE-CS30-26 Ground-Fault Current Sensors.

Littelfuse STARTCO SE-330 Neutral-Grounding-Resistor Monitor

FIGURE 19. RK-332 Remote Indication and Reset.

FIGURE 20. PGA-0520 Analog Percent Current Meter.

3.4 ISOLATED GROUND CONNECTION

An isolated ground bed can prevent a ground potential rise (GPR) from being transferred to remote equipment. If the G terminals on the sensing resistor and the SE-330 are connected to an isolated ground, the SE-330 will be exposed to the GPR. If the GPR is greater than the terminal-block rating, the SE-330 must be isolated from station ground and precautions must be taken with the power supply and the trip contacts. See Technical Note RG-1 "NGR Monitoring with Isolated Ground Beds" at www.littelfuse.com/relayscontrols.

A configuration which allows an SE-330 to be connected to station ground is shown in Fig. 21. The SE-330 monitors the series combination of the NGR and the two ground beds. This configuration is acceptable provided the series resistance of the NGR and the ground beds is within the NGR calibration range and groundbed- resistance changes remain within the trip range. See Section 6.1.

FIGURE 21. Simplified Isolated-Ground Connection.

3.5 PULSING CONNECTION

Set switch S1 to K1 = PULSING and use an external switch as shown in Fig. 22 to use relay K1 to control a pulsing contactor. Relays K2 and K3 can be used for tripping and can be configured in the fail-safe or non-fail-safe mode using the SE-MON330 software.

4. DATA INTERFACES

4.1 SD CARD

The SE-330 supports microSD[™] data storage. The microSD[™] card port is located on the front panel just below the USB port. The microSD[™] card is used for long-term data logging of measured values and for firmware upgrades.

4.1.1 DATALOGGING

When a microSD[™] card is installed, the SE-330 looks for a directory called "Datalogging". If this directory exists, data logging will automatically start after the card is indexed (indexing may take several minutes depending on the size of the card and the number of files).

The log is updated every two seconds and it includes measured values, configuration parameters, and trip status. A new log file is created at the start of each day. If previous log files exist and the microSD[™] card has less than 20 MB of free space, the oldest datalogging file will automatically be deleted before a new file is created.

The red DIAGNOSTIC LED may indicate an SD Card error. See Section 5. Approximately 3 GB of data is generated per year of logging.

4.1.2 FIRMWARE UPGRADE

Firmware upgrades are performed using a microSD[™] card in conjunction with configuration switch S8. See Section 2.1.5.7.

To upgrade the SE-330 firmware, insert a microSD[™] card containing the firmware upgrade file (.S19 format) and set switch S8 to UPGRADE within 30 s. If S8 is switched to UPGRADE after 30 s, the upgrade process will not occur. If the microSD[™] card is inserted after S8 is switched to UPGRADE, switch S8 to RUN and then back to UPGRADE. The SE-330 evaluates firmware upgrade files found in the base directory of the microSD[™] card and uses the first valid file.

Ensure that the DIAGNOSTIC LED is off before beginning the firmware upgrade process.

The red DIAGNOSTIC LED blinks rapidly while the firmware upgrade is running and the SE-330 will restart when the upgrade is complete. If the upgrade is not successful, the DIAGNOSTIC LED will indicate an SD Upgrade Error. See Section 5. Set switch S8 back to RUN for normal operation. If a firmware upgrade fails, the existing firmware is not overwritten.

A record of the upgrade can be found in "upgrade_log_<SN>.txt" on the microSDTM card. This file is updated each time an upgrade is performed.

NOTE: The included microSDTM card has a temperature rating of -25 to 85° C (-13 to 140° F). For applications colder than -25°C (-13°F), use an Industrial-Grade microSDTM card.

NOTE: The maximum recommended microSDTM card storage capacity is 4 GB.

4.2 USB INTERFACE

Use the SE-MON330 software (version 3.5 or newer) to access set-points, measured values, and trip records through the mini B USB interface located on the front panel. The following data can be viewed:

- Front-panel and configuration-switch settings
- Neutral voltage and neutral current
- Resistance change from the calibrated value
- Trip status
- Trip records, 100 date and time stamped
- Firmware version and serial number

The following values can be viewed and adjusted:

- Ground-fault trip setting (when front-panel GF Trip Level is set to MEM)
- K2 ground-fault relay output operating mode
- K3 resistor-fault relay output operating mode
- Clock settings
- Trip records can be cleared
- Remote calibration
- Resistor-fault trip time
- Resistor-fault trip level
- Geo-magnetic filter

Ensure the real-time clock is set to the correct time prior to normal operation. Trip records and on-board datalogging information include date and time readings from the clock. Refer to the SE-MON330 software help file.

4.3 NETWORK COMMUNICATIONS

The optional communications interfaces include a single CAN port and dual Ethernet ports supporting cable, fiber⁽¹⁾, or both cable and fiber. Protocols include:

- DeviceNet over CAN (ordering option 1)
- EtherNet/IP over cable or fiber (ordering options 3, 4, and 5)
- Modbus TCP over cable or fiber (ordering options 3, 4, and 5)
- IEC 61850 over cable or fiber (ordering options 6, 7, and 8)

Refer to the appropriate SE-330 communicationsinterface manual for details.

⁽¹⁾ Uses the plug-in style SC connector.

5. **TROUBLESHOOTING**

| PROBLEM | DIAGNOSTIC LED | SOLUTION |
|--------------------------------------|---------------------------|--|
| | FLASH CODE ⁽¹⁾ | |
| POWER LED off. | | Check if supply voltage is present on terminals 1 and 2. If present, |
| | | an overvoltage may have caused the power supply to shutdown. |
| | | Cycle supply voltage. If POWER LED remains off, return unit for |
| DOWED LED flock of | | repair. |
| POWER LED flashes. | | problem persists, consult Littelfuse Startco. |
| Calibration-Error Trip | 1 L - 1 S - 1 L | The total resistance of the NGR and sensing-resistor circuit is |
| DIAGNOSTIC LED flash code | | outside the calibration range. Verify that switch S5 is set to match |
| | | the resistance of the sensing resistor, check the resistance of the |
| | | sensing-resistor tests |
| | | Repeat the calibration procedure after the open or shorted condition |
| | | has been corrected. |
| | | GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : ON, K1:Trip |
| Remote Trip | 1 L - 2 S - 1 L | The SE-330 was tripped by a signal from network communications. |
| DIAGNOSTIC LED flash code | | Press RESET to clear the trip. |
| | | GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| A/D-Converter-Error Trip | 1 L - 4 S - 1 L | An A/D-converter error was detected. Press RESET to clear the |
| DIAGNOSTIC LED flash code | | trip. If the problem persists, consult Littelfuse Startco. |
| | | GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : ON, K1:Trip |
| SD Card | 1 L - 5 S - 1 L | SD Card is full or a write error occurred. Delete files or use a |
| DIAGNOSTIC LED flash code | | different microSD TM card. CE LED ⁽²⁾ : No Change RE LED ⁽²⁾ : No Change K1: No Change |
| Watchdog Trip | 11 68 11 | A watchdog trip results in a processor reset. During reset UNIT |
| DIAGNOSTIC LED flash code | 11-03-11 | HEALTHY relay K4 will be de-energized After a reset UNIT |
| | | HEALTHY relay K4 will be energized. Press RESET to clear the |
| | | trip. If the problem persists, consult Littelfuse Startco. |
| | | GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| CPU Trip | 1 L - 7 S - 1 L | The CPU has detected a system fault. Press RESET to clear the |
| DIAGNOSTIC LED flash code | | trip. |
| | 4.1. 0.0. 4.1 | GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| Non-Volatile Memory Error Trip | 1 L - 8 S - 1 L | An error was detected in the Non-Volatile Memory. Press RESET |
| DIAGNOSTIC LED flash code | | to clear the trip. If the problem persists, consult Littelfuse Startco. $CE \perp ED^{(2)}$: ON $PE \perp ED^{(2)}$: ON $K1$: Trip |
| SD Ungrada Error | 11-98-11 | An error occurred during the flash-memory ungrade procedure |
| DIAGNOSTIC LED flash code | 11-75-11 | Ensure that the firmware upgrade file is correct or use a different |
| | | microSD TM card. |
| | | GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : No Change, K1:No Change |
| DIAGNOSTIC LED = Solid Red | | SE-330 processor failed to start. Cycle supply. If problem persists, |
| | | consult Littelfuse Startco. K1: De-energized. |
| Pressing RESET does not clear trips. | | Trip condition is still present. Locate and correct. |
| | | The RESET button is disabled if remote-reset terminals 15 and 16 |
| | | are connected. Replace shorted remote-reset switch or issue Reset |
| | | command from the communications network. |
| UNIT HEALTHY relay K4 momentarily | | Occurs when processor is reset. |
| No analog_output current | | The output at terminals 10 and 20 requires a voltage source. |
| | | Fig. 2 for analog-output connections. See Section 9.3 for the |
| | | analog-output tests. |

NOTES: ⁽¹⁾ L = long pause, S = short flash. ⁽²⁾ When LED is on, corresponding indication relay is energized when in the non-fail-safe mode or de-energized when in the fail-safe mode.

6. TECHNICAL SPECIFICATIONS

6.1 SE-330

| Supply: | |
|---|------------------------------|
| Option 0 | 30 VA, 120 to 240 Vac |
| | (+10, -45%), 50/60 Hz; |
| | 20 W, 110 to 250 Vdc |
| | (+10, -25%) |
| Option 2 | 20 W, 48 Vdc |
| | (+50, -25%); |
| | 35 VA, 48 Vac |
| | (+10, -45%), 50/60 Hz |
| Power-Up Time | 3 s at 120 Vac |
| AC Measurements | . Discrete Fourier |
| | Transform. 16 samples |
| | per cycle, 50 or 60 Hz |
| Resistor-Fault Circuit: | |
| Neutral-To-Ground Voltage | Trip Levels ⁽¹⁾ : |
| ER-600VC or ER-5KV | 20; 60; 100; 130; 170; 200; |
| | 340; 800; 1,200; 1,700; |
| | 2,000 Vac |
| ER-15KV to ER-35KV | 100; 300; 500; 650; 850; |
| | 1,000; 1,700; 4,000; 6,000; |
| | 8,500; 10,000 Vac |
| Accuracy | 10% of setting |
| 3 dB Frequency Response | : |
| S6 = 50 Hz | 25 to 85 Hz |
| S6 = 60 Hz | 30 to 90 Hz |
| NGR Calibration Range: | |
| ER-600VC, ER-5KV, or | |
| ER-5WP | 0 to 2 kQ |
| FR-15KV to FR-35KV | 0 to 10 kO |
| Trin Resistance $V_{\rm M} = 0^{\circ}$ | |
| FR-600VC FR-5KV or | |
| FR-5WP | |
| $Range^{(5)}$ | 250 to $750-\Omega$ change |
| Kange | $\pm 200 \text{ O}$ |
| D - C14 | $\pm 200 \Omega$ |
| ER-15KV to ER-35KV: | 500-12 change |
| Range ⁽⁵⁾ | 1 25 to 3 75-kQ change |
| | $+1 k\Omega$ |
| Default | $2.5 k\Omega$ change |
| Neutral-To-Ground DC-Vol | tage Rejection: |
| FR-600VC FR-5KV or | lage Rejection. |
| ER-5WP | 25 Vdc |
| $ER_{-3}KV$ to $ER_{-3}KV$ | 125 Vdc |
| Trin Time | 12 to 60 s + 1 s |
| Trip Hold Off Level | 5% of CT-Primary Rating |
| Trip Mode | Latching/Non-Latching |
| | uching won-Latening |
| Ground-Fault Circuit: | |
| Trip Level | 2 4 6 8 10 20 40 60 |
| | 80 100% of CT-Primary |
| | Rating or 2 to 100% using |
| | MEM parameter |
| Trip Time | 0.1. 0.2. 0.3. 0.4. 0.5. 0.7 |
| r | 1.0, 2.0, 3.0, 5.0, 10.0 s |
| | |

| Trip-Level Accuracy | Maximum of 1% of CT- Primary Rating or 3% of |
|----------------------------------|---|
| Trin-Time Accuracy | 10% of Setting 20 ms |
| | minimum |
| 3 dB Frequency Response: | |
| S6 = 50 Hz | .25 to 85 Hz |
| S6 = 60 Hz | .30 to 90 Hz |
| Maximum CT lead resistanc | e: |
| EFCT & SE-CS30 | .5Ω |
| Other CT's | . Consult CT Curve. |
| CT-Input Burden: | |
| 5-A Input | .< 0.01 Ω |
| I-A Input | .< 0.05 Ω |
| EFC1 Input Thermal Withstand: | .< 10.22 |
| 1-A and 5-A Inputs | |
| Continuous | 2 x CT Rating |
| 1-Second | 20 x CT Rating |
| EFCT Input: | |
| Continuous | . 10 x CT Rating |
| 1-Second | .25 x CT Rating |
| Measurement Range | .25 x CT-Primary Rating |
| Trip Mode | .Latching/Non-Latching |
| Pulsing Circuit: | |
| Pulse Period | . 1.0 to 3.0 s, |
| | 0.2-s increments |
| Duty Cycle | . 50% |
| Time Accuracy | .10% of Setting |
| Trip/Pulsing Relay K1 Contacts | : |
| Configuration | .N.O. (Form A) |
| Operating Mode | . Fail-Safe or Non-Fail-Safe |
| CSA/UL Contact Ratings | .8 A resistive 250 Vac, 5 A |
| | resistive 30 Vdc |
| Supplemental Contact Rating | gs: |
| Make/Carry 0.2 s | .30 A |
| Break: | |
| dc | .75 W resistive, |
| | 35 W inductive |
| | (L/R = 0.04 s) |
| ac | . 2,000 VA resistive, |
| | 1,500 VA inductive (DE = 0.4) |
| Subject to maximums of 9 | (PF = 0.4) |
| at 30 Vdc and 0.4 A resist | ive at 250 Vdc |
| at 50 v de, and 0.4 A resist | ive at 250 vide. |
| GE (K2) and RE (K3) Relay Co | ntacts. |
| Configuration | NO and NC (Form C) |
| Operating Mode | .Non-Fail-Safe or Fail-Safe |
| CSA/UL Contact Ratings | .8 A resistive 250 Vac, |
| | 8 A resistive 30 Vdc |
| Supplemental Contact Rating | gs: |
| Make/Carry 0.2s | .20 A |
| Break: | |
| dc | .50 W resistive, 25 W |
| | inductive $(L/R = 0.04 \text{ s})$ |

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| ac | 2,000 VA resistive, $1,500$ | Depth | 132 mm (5.2") |
|-----------------------------|---------------------------------|------------------------------|--|
| Subject to menimum of | VA inductive (PF = 0.4) | Chinging Waight | 2.01-(4.41h) |
| subject to maximums of | ative at 150 Vac, 8 A resistive | Snipping weight | 2.0 kg (4.4 lb) |
| at 30 v dc, and 0.4 A res | istive at 150 v dc. | Environment | |
| Unit Healthy Output KA (Opt | (a, 0) | Operating Temperature | -40 to 60° C (-40 to 140° F) |
| Configuration | $NO(Form \Lambda)$ | Storage Temperature | -55 to 80°C (-67 to 176°F) |
| Operating Mode | Closed when Healthy | Humidity | 85% Non-Condensing |
| Defining Mode | 100 mA 250 V (as ar ds) | IP Rating | IP30 |
| Cl ID it | 100 mA, 230 v (ac of uc) | Surge Withstand | ANSI/IEEE C37 90 1- |
| Closed Resistance | 30 to 50 Ω | Suige Whistand | 1989 (Oscillatory and Fast |
| | 1) | | Transient) |
| Unit Healthy Output K4 (Opt | (on 1): | FMC Tests | Transferit) |
| Configuration | N.C. (Form B) | Verification tested in accor | dance with FN 60255-26:2013 |
| Operating Mode | Open when Healthy | vermeation tested in accor | dance with Erv 00255-20.2015. |
| Ratings | 100 mA, 250 V (ac or dc) | Radiated and Conducted | |
| Closed Resistance | 25 to 50 Ω | Emissions | CISDD 11.2000 |
| | | | CISPR 11.2009, |
| Auto-reset time | 2.8 s maximum | | CISPR 22.2008, |
| | | | EN 55022:2010 |
| 4-20-mA Analog Output: | | | Class A |
| Туре | Self Powered and | | |
| | Loop Powered | Current Harmonics and | |
| Range | 4 to 22 mA | Voltage Fluctuations | IEC 61000-3-2 |
| Loop Voltage | 8 to 36 Vdc | | and IEC 61000-3-3 |
| Load | 500 Ω (maximum with | | Class A |
| | 24-Vdc supply) | | |
| Isolation | 120 Vac | Electrostatic Discharge | IEC 61000-4-2 |
| Parameter | NGR Current 20 mA = | | ± 6 kV contact discharge |
| i ulullotoi | CT Primary Current | | (direct and indirect) |
| | C1 Triniary Current | | \pm 8 kV air discharge |
| USB Communications: | | | |
| Baud Rate | 12 Mbit/s | Radiated RF Immunity | IEC 61000-4-3 |
| Protocol | USB Device | | 10 V/m, 80-1,000 MHz, |
| Connactor | Mini D | | 80% AM (1 kHz) |
| Connector | | | 10 V/m, 1.0 to 2.7 GHz, |
| SD Mamary Card | | | 80% AM (1 kHz) |
| SD Memory Card. | Ston dand Crada | | |
| Type | Standard Grade | Fast Transient | IEC 61000-4-4 |
| Form Factor | microSD ^{IM(9)} | | Zone B |
| Format | FA132 | | $\pm 2 \text{kV}$ (power supply |
| Capacity | 512 MB to 4 GB | | port) $\pm 1 \text{ kV}$ (all other |
| | (microSD ^{IM} and | | ports) |
| - · - | microSDHC ^{IM}) | | porta) |
| Operating Temperature: | | Surge Immunity | IEC 61000-4-5 |
| Standard Grade | | Surge minutery | Zone B |
| (Included) | 25 to 85°C (-13 to 140°F) | | + 1 kV differential mode |
| Industrial Grade | 40 to 85°C (-40 to 140°F) | | $\pm 2 kV$ common mode |
| | | | $\pm 2 \text{ k v}$ common mode |
| Terminal-Block Ratings | 10 A, 300 Vac, 12 AWG | Conducted DE Luminitie | IEC (1000 4 (|
| | (2.5 mm^2) | Conducted RF Immunity | IEC 61000-4-6 |
| | | | 10 V, 0.15-80 MHz, |
| PWB Conformal Coating | MIL-1-46058 qualified, | | 80% AM (1 kHz) |
| 5 | UL QMJU2 recognized | | |
| | | Magnetic Field | |
| Mounting Configurations | Panel Mount and Optional | Immunity | IEC 61000-4-8 |
| | Surface Mount | | 50 Hz and 60 Hz |
| Dimensions. | - diffuer friendt | | 30 A/m and 300 A/m |
| Height | 213 mm (8 4") | | |
| Width | 99 mm (3.9") | | |
| · · IMUII | | | |

| $ \begin{array}{c} \mbox{Zone A: differential mode} \\ 100 Vrms \\ \mbox{Zone A: common mode} \\ 300 Vrms \\ \mbox{Zone A: common mode} \\ 300 Vrms \\ \mbox{Zone A: common mode} \\ 300 Vrms \\ \mbox{Zone A: common mode} \\ \mbox{Zon A: common mode} \\ \mbox{Zon A: common mode} \\ \mbox{Zon A: common mode} \\ \mbox{Zone A: common mode} \\ \mbox{Zon A: common mode} \\ \mbox{Zon A: conmon mode} \\ Zone A: common $ | Power Frequency ⁽⁴⁾ | IEC 61000-4-16 | 6.2 SENSING RESISTORS | | | |
|--|---|-----------------------------------|-----------------------------|--|-----------------|-----------|
| $\begin{array}{c} 100 \text{ Vms} \\ Zonc A: common mode \\ 300 \text{ Vms} \\ Zonc A: common mode \\ 300 \text{ Vms} \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ (lice-to-line) \\ \hline \\ 200 \text{ Voltage Interruption \\ \hline \\ (lice-to-line) \\ \hline \\ 200 \text{ Vac} \\ $ | | Zone A: differential mode | Environment: | | | |
| Zone A: common mode 300 Vrms 1 MHz Burst | | 100 Vrms | Operating Temperature | 40 to 60°C (-40 to 140°F) | | |
| $\begin{array}{c} 300 \ \mathrm{Vms} \\ \hline 300 \ \mathrm{Vms} \\ \hline 300 \ \mathrm{Vms} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{MHz} \ \mathrm{Burst} \dots \ \mathrm{Extended Operating} \\ \hline 1 \ \mathrm{Mus} $ | | Zone A: common mode | Storage Temperature | 55 to 80°C (-67 to 176°F) | | |
| Temperature-55 to $60^{\circ}C (-67 to 140^{\circ}F)^{(3)}$ 1 MHz BurstIEC 61000-4-18 ± 1 kV differential mode (line-to-line) ± 2.5 kV common modeTemperature | | 300 Vrms | Extended Operating | | | |
| 1 MHz BurstIEC 61000-4-18 $[40^{\circ}\text{F}]^{(3)}$ +1 kV differential mode (line-to-line)+2.5 kV common mode $[40^{\circ}\text{F}]^{(3)}$ *2.5 kV common mode*2.5 kV common mode $[40^{\circ}\text{F}]^{(3)}$ *2.5 kV common mode*2.5 kV common mode $[600 \text{ Vac}$ *2.5 kV common mode*2.5 kV common mode $[600 \text{ Vac}$ *2.5 kV common mode $[600 \text{ Vac}$ $[600 \text{ Vac}$ Waxinuum Voltage $[20 \text{ Vac}$ $[600 \text{ Vac}$ 0% for 0.5, 1, 2.5, 5 cycles (60 Hz) $[600 \text{ Vac}$ $[600 \text{ Vac}$ 1EC 61000-4-17EC 61000-4-17 $[EC 61000 -4-17]$ Level 4, 15% of rated de value $[600 \text{ Vac}$ $[600 \text{ Vac}$ $[Certification$ CSA, Canada and USA $[600 \text{ Vac}$ $[600 \text{ Vac}$ $[Certification$ CSA, Canada and USA $[600 \text{ Vac}$ $[600 \text{ Vac}$ $[Certification$ $[CSA, Canada and USA[600 \text{ Vac}[600 \text{ Vac}[Certification[CSA, Canada and USA[Certification][Certification][Certification][Certification[CSA, Canada and USA[Certification][Certifica$ | | | Temperature | 55 to 60°C (-67 to | | |
| $ \begin{array}{c} \pm 1 kV \ differential mode \ (linet-to-line) \\ \pm 2.5 kV \ common mode \\ \hline kV \ oltage \ Interruption \\ \pm 2.5 kV \ common mode \\ \hline kV \ oltage \ Interruption \\ \pm 2.5 kV \ common mode \\ \hline kV \ oltage \ Interruption \\ \hline kV \ oltage \ I$ | 1 MHz Burst | IEC 61000-4-18 | | $140^{\circ}\text{F})^{(1)}$ | | |
| $ \begin{array}{c} (\operatorname{line-to-line}) \\ \pm 2.5 \mathrm{kV} \mathrm{common\ mode} \\ \hline \\ \end{array} \\ \begin{array}{c} \operatorname{Voltage\ Interruption} & \operatorname{IEC\ 61000-4-11}, \\ \operatorname{IEC\ 61000-4-29} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 50 \mathrm{ms\ (dc)} \\ 0\% \mathrm{for\ 10,\ 20,\ 30,} \\ 12 \mathrm{for\ mal\ common\ 10} \\ 0\% \mathrm{for\ 11,\ 10,\ 31,\ 10,\ 32\ 1nset} \\ \end{array} \\ \begin{array}{c} \mathrm{certification} \mathrm{cSA,\ Canada\ and\ USA} \\ \hline \\ \begin{array}{c} \mathrm{for\ 10,\ 10,\ 10,\ 50,\ 11,\ 10,\ 32\ 1nset} \\ \mathrm{for\ 12,\ 50,\ 11,\ 10,\ 32\ 1nset} \\ \end{tabular} \end{tabular} \end{tabular} \\ \end{tabular} $ | | ± 1 kV differential mode | | | | |
| $ \begin{array}{c} \pm 2.5 \text{ kV common mode} \\ \pm 2.5 \text{ kV common mode} \\ \hline \\ \text{Voltage Interruption} & \text{IEC } 61000-4-11, \\ \text{IEC } 61000-4-29, \\ 0\% \text{ for } 10, 20, 30, \\ 50 \text{ ms} (dc) \\ 0\% \text{ for } 10, 20, 30, \\ 50 \text{ ms} (dc) \\ 0\% \text{ for } 10, 21, 5, \\ 5 \text{ cycles } (60 \text{ Hz}) \\ \text{IEC } 61000-4-17 \\ \text{Level } 4, 15\% \text{ of rated } dc \\ value \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ \text{Certification} & \text{CSA}, \text{ Canada and USA} \\ \hline \\ \hline \\ Constrange Boundary on the sequence of t$ | | (line-to-line) | ER-600VC: | | | |
| Voltage InterruptionIEC 61000-4-11, IEC 61000-4-29 0% for 10, 20, 30, 50 ms (dc) 0% for 0.5, 1, 2.5, 5 cycles (60 Hz) IEC 61000-4-17 Level 4, 15% of rated dc valueMaximum Current30 mA ResistanceCertificationCSA, Canada and USA 420 Vac.Continuous 600 Vac.60 minutes onf 60 vac.CertificationCSA, Canada and USA $\underbrace{\mathbb{O}}_{c}$ use c use c use c use c use c useER-5KV:Maximum Current2,500 Vac Maximum CurrentCertificationCSA, Canada and USA $\underbrace{\mathbb{O}}_{c}$ use c us | | ± 2.5 kV common mode | Maximum Voltage | 600 Vac | | |
| Voltage InterruptionIEC 61000-4-17 IEC 61000-4-29 0% for 10, 20, 30, 50 ms (dc) 0% for 10, 51, 1, 25, 5 cycles (60 Hz) IEC 61000-4-17 Level 4, 15% of rated dc valueResistance $20 k\Omega$ for minutes of, 60 minutes off Shipping WeightCertificationCSA, Canada and USA $60 Vac.60 minutes offminutes offCertificationCSA, Canada and USA60 Vac.60 minutes offminutes offV UL ListedV minutes 0V minutes00 Vac.00 Vac.V UL Listed10 -32 Insert20 k\OmegaminutesV UL Listed10 -32 Insert5.0 kg (11 lb)V US Sisters00 Vac.00 Vac.V US Sisters00 Vac.10 Vac.V US Sisters00 Vac.00 Vac.V US Sis$ | | | Maximum Current | 30 mA | | |
| $ \begin{array}{c} 1 \text{ Hermal:} \\ 0\% \text{ for } 10, 20, 30, \\ 50 \text{ ms (dc)} \\ 0\% \text{ for } 0, 51, 2.5, \\ 5 \text{ cycles (60 \text{ Hz})} \\ 1 \text{ EC } 61000-4.17 \\ 1 \text{ Level } 4, 15\% \text{ of rated dc} \\ value \\ \end{array} $ $ \begin{array}{c} \text{Certification} \\ \hline \text{Certification} \\ $ | Voltage Interruption | IEC 61000-4-11, | Resistance | 20 kΩ | | |
| $\begin{array}{c} 0\% \mbox{ for 10, 20, 30, $50 ms (dc) \\ 0\% \mbox{ for 0, 5, 1, 2.5, $5 cycles (60 Hz) \\ EC 6 1000-4.17 \\ Level 4, 15\% \mbox{ of rated dc} \\ value \\ \hline \\ Certification$ | | IEC 61000-4-29 | Thermal: | | | |
| $\begin{array}{c} 50 \text{ ms} (dc) \\ 90 \text{ mo} (0, 5, 1, 2.5, 5 \\ 5 \text{ cycles} (60 \text{ Hz}) \\ \text{IEC} 61000-4-17 \\ \text{Level 4}, 15\% \text{ of rated dc} \\ value \\ \hline \\ \hline \\ \text{Certification} \\ \hline \\ Certific$ | | 0% for 10, 20, 30, | 420 Vac | Continuous | | |
| $\begin{array}{c} 0.9\% \mbox{ tor } 0.5, 1, 2.5, \\ 5 \ cycles (60 \mbox{ Hz}) \\ IEC 61000-4-17 \\ Level 4, 15\% \mbox{ of rated dc} \\ value \\ \hline \\ \end{tabular} \label{eq:starse} \label{eq:starse} \\ \end{tabular} \label{eq:starse} \label{eq:starse} \\ \end{tabular} \label{eq:starse} \label{eq:starse} \\ \end{tabular} \label{eq:starse} \labe$ | | 50 ms (dc) | 600 Vac | 6 minutes on, | | |
| S cycles (60 Hz) IEC 61000-4-17 Level 4, 15% of rated dc value $Certification \dots CSA, Canada and USA$ $\underbrace{\mathbb{C}_{value} : III 53428}_{0} : UL Listed \underbrace{\mathbb{C}_{value} : III 53428}_{0} : UL Listed ::IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII$ | | 0% for 0.5, 1, 2.5, | | 60 minutes off | | |
| Lec 61000-4-17 Level 4, 15% of rated dc value Certification | | 5 cycles (60 Hz) | Shipping Weight | 300 g (0.7 lb) | | |
| Level 4, 15% of rated dc value Level 4, 15% of rated dc value Certification | | IEC 61000-4-17 | | | | |
| ValueMaximum Voltage2,500 VacCertificationCSA, Canada and USA \mathbb{C}_{05} \mathbb{C}_{15} \mathbb{C}_{125} \mathbb{C} | | Level 4, 15% of rated dc | ER-5KV: | | | |
| CertificationCSA, Canada and USAMaximum Current125 mAResistance20 kQTorque: Torque: Torque: Torcuse: Torcuse: TorCSA C22.2 No. 14 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment CE Low Voltage Directive IEC 61010-1:2010 (3rd Edition) FCC CTFR47, Part 15, Subpart B, Class A – Unintentional RadiatorsMaximum Current125 mAResistor specifications for applicable voltage limitsMaximum Current125 mAResistor specifications for applicable voltage limitsContinuousTorces CA C22.2 No. 14 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment CC CFR47, Part 15, Subpart B, Class A – Unintentional RadiatorsER-15KV:Maximum Current84 mA Resistance Resistance Torque: Terminal N: 10-32 Insert5.6 N-m (50 in-lb) OthersON The Second Fault Sensing and Relaying Equipment Class A – Unintentional RadiatorsCompliance <th <="" colspan="2" td=""><td></td><td>value</td><td>Maximum Voltage</td><td> 2,500 Vac</td></th> | <td></td> <td>value</td> <td>Maximum Voltage</td> <td> 2,500 Vac</td> | | | value | Maximum Voltage | 2,500 Vac |
| Certification CSA, Canada and USA Resistance 20 kΩ Image: Complexity of the state sensing and relation in the state sensing in the state sensing and relation in the state sensing resistor specifications for applicable voltage limits. Resistance 20 kΩ Image: Complexity of the state sensing in the state sensing resistor specifications for applicable voltage limits. Image: Complexity of the state sensing in the sensing in the state sensing in the sense sensing resistor specifications is on aplicable volt | Castification | | Maximum Current | 125 mA | | |
| Image: Fight Lip 53428 Thermal Continuous UL Listed Torque: UL distration ER-SWP: Maximum Voltage 2,500 Vac Maximum Current 125 mA Resistance 20 kΩ Thermal Continuous TorCCSA C22.2 No. 14 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment CE Low Voltage Directive EC 61010-1:2010 (3 rd Edition) FCC CFR47, Part 15, Subpart B, FCC sensing resistor specifications for applicable voltage 10 s21 minute on, I ⁽¹⁾ See sensing resistor specifications for applicable voltage 120 minutes off I ⁽¹⁾ See sensing resistor specifications for applicable voltage 1,900 Vac Continuous I ⁽¹⁾ S | Certification | CSA, Canada and USA | Resistance | 20 kΩ | | |
| Image: Second | | (S) R LR 53428 | Thermal | Continuous | | |
| UL Listed Terminal N: 10-32 Insert $\dots 5.6$ N-m (50 in-lb) Others $\dots 9.0$ N-m (80 in-lb) Shipping Weight $\dots 5.0$ kg (11 lb) Australia \mathbb{C}_{4X9}^{ES9} Subgete N11659 Australia \mathbb{C}_{5C}^{EC} FCC \mathbb{F}_{CC}^{CC} CC \mathbb{F}_{CC}^{CC} Thermal $\dots Continuous$ To:CSA C22.2 No. 14 Industrial Control Equipment UL 508 Industrial Control Equipment UL 508 Industrial Control Equipment UL 508 Industrial Control Equipment UL 508 Industrial Control Equipment CE Low Voltage Directive Equipment CE Low Voltage Directive IEC 61010-1:2010 (3 rd Edition) FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators NOTES: \mathbb{N} OTES: \mathbb{N} OTES: \mathbb{N} Compliance \dots RoHS Pending \mathbb{N} OTES: \mathbb{N} Direction for applicable voltage \mathbb{N} Maximum Voltage \mathbb{N} applicable voltage \mathbb{N} Maximum Voltage \mathbb{N} applicable voltage \mathbb{N} Maximum Voltage \mathbb{N} applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See versing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} See sensing resistor specifications for applicable voltage \mathbb{N} (\mathbb{N} Second Secon | | CUS | Torque: | | | |
| $ \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c}$ | | UL Listed | Terminal N: | | | |
| Constrained Fault Sensing arrow Fault Sensing (4759 E340899 Chers 9.0 N-m (80 in-lb) Australia Shipping Weight 5.0 kg (11 lb) Windstained Shipping Weight 5.0 kg (11 lb) N11659 Maximum Voltage 2,500 Vac N11659 Maximum Voltage 2,500 Vac N11659 Maximum Current 125 mA Resistance 20 kΩ 10-32 lnsert To:CSA C22.2 No. 14 Industrial Control Equipment Control Equipment 10-32 lnsert 5.6 N-m (50 in-lb) UL 508 Industrial Control Equipment To:CSA C22.2 No. 14 Industrial Control Equipment 10-32 lnsert 5.0 kg (11 lb) UL 1053 Ground Fault Sensing and Relaying Equipment 5.0 kg (11 lb) 10-32 lnsert 5.0 kg (11 lb) Compliance Roitsa A – Unintentional Radiators Maximum Voltage 8,400 Vac Compliance RoHS Pending 8,400 Vac 1 minute on, NOTES: 120 minutes off 1,900 Vac 10 minutes off (1) See sensing resistor specifications for applicable voltage limits. 1,900 Vac Continuous | | | 10-32 Insert | 5.6 N-m (50 in-lb) | | |
| Shipping Weight | | Ground Fault Sensing | Others | 9.0 N-m (80 in-lb) | | |
| Australia Fustmania N11659 ER-5WP: N11659 Maximum Voltage | | 4FX9 E340889 | Shipping Weight | 5.0 kg (11 lb) | | |
| N11659ER-SWP:N11659Maximum Voltage2,500 VacCE, European UnionMaximum Current125 mAFCCFCCMaximum Current125 mAFCCFCCThermalContinuousTo:CSA C22.2 No. 14 Industrial Control EquipmentUL 508 Industrial Control Equipment10-32 Insert5.6 N-m (50 in-lb)UL 508 Industrial Control Equipment0 thers9.0 N-m (80 in-lb)UL 1053 Ground Fault Sensing and RelayingEquipment5.0 kg (11 lb)EC 61010-1:2010 (3 rd Edition)FCC CFR47, Part 15, Subpart B, Class A – Unintentional RadiatorsResistance100 kQComplianceRoHS Pending120 minutes off1,900 Vac20 N-m (80 in-lb)NOTES:10 Shipping Veight1 minute on, 120 minutes off1,900 VacContinuous | | Australia | | | | |
| N11659Maximum Voltage2,500 VacCE, European UnionCE, European UnionMaximum Voltage2,500 VacCE, European UnionCE, European UnionMaximum Voltage2,500 VacFCCFCCMaximum Current125 mAFCCFCCThermalContinuousTo:CSA C22.2 No. 14 Industrial Control EquipmentTorque:Terminal N:UL 508 Industrial Control Equipment10-32 Insert5.6 N-m (50 in-lb)UL 1053 Ground Fault Sensing and RelayingShipping Weight5.0 kg (11 lb)EquipmentER-15KV:Maximum VoltageCE Low Voltage DirectiveER-15KV:IEC 61010-1:2010 (3rd Edition)Maximum VoltageFCC CFR47, Part 15, Subpart B, Class A – Unintentional RadiatorsResistanceComplianceRoHS PendingNOTES:120 minutes off(1) See sensing resistor specifications for applicable voltage1,900 Vac(1) See sensing resistor specifications for applicable voltage1,900 VacImits.Continuous | | C | ER-SWP: | 2 500 M | | |
| $\begin{array}{c} \text{Ke}, \text{European Union} \\ \textbf{Ke} \\ \text{FCC} \\ \textbf{FCC} \\ \textbf{L} \\ 10-32 \text{ Insert} \\ 0.32 \text{ Insert} \\ 0.5.6 \text{ N-m} (50 \text{ in-lb}) \\ 0 \\ 0 \\ \text{thers} \\ 9.0 \text{ N-m} (80 \text{ in-lb}) \\ 0 \\ 0 \\ \text{thers} \\ 0 \\ 0 \\ \text{thers} \\ 0 \\ 0 \\ \text{thers} \\ 0 \\ 0 \\ 0 \\ \text{thers} \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $ | | N11659 | Maximum Voltage | 2,500 Vac | | |
| FCC FCC Continuous FCC FCC Thermal Continuous To:CSA C22.2 No. 14 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment 5.6 N-m (50 in-lb) CE Low Voltage Directive Shipping Weight 5.0 kg (11 lb) ER-15KV: Maximum Voltage 8,400 Vac Maximum Current 84 mA Resistance 100 kΩ Thermal: 100 kΩ Thermal: 100 kΩ Thermal: 100 kΩ Thermal: 100 kΩ Compliance RoHS Pending 1,900 Vac 1 minute on, (1) See sensing resistor specifications for applicable voltage limits. 1,900 Vac Continuous (1) See sensing resistor specifications for applicable voltage 1,900 Vac Continuous | | CE, European Union | Maximum Current | 125 mA | | |
| FCC FCC Thermal Continuous FCC FCC FCC FCC FCC FCC FCC FCC FCC FCC FCC FCC To:CSA C22.2 No. 14 Industrial Control Equipment UL 508 Industrial Control Equipment 10-32 Insert 5.6 N-m (50 in-lb) UL 1053 Ground Fault Sensing and Relaying Equipment 5.0 kg (11 lb) Shipping Weight 5.0 kg (11 lb) EC 1010-1:2010 (3 rd Edition) FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators Resistance 100 kΩ Compliance RoHS Pending 8,400 Vac 1 minute on, 120 minutes off 1,900 Vac Continuous Torque (Terminal N) 9.0 N-m (80 in-lb) | | | Resistance | 20 κΩ | | |
| For CSA C22.2 No. 14 Industrial Control Equipment UL 508 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment CE Low Voltage Directive IEC 61010-1:2010 (3rd Edition) FCC CFR47, Part 15, Subpart B, Class A – Unintentional RadiatorsI orque: Terminal N: 10-32 Insert | | FCC | I hermal | Continuous | | |
| To:CSA C22.2 No. 14 Industrial Control Equipment UL 508 Industrial Control Equipment UL 1053 Ground Fault Sensing and Relaying Equipment CE Low Voltage Directive IEC 61010-1:2010 (3 rd Edition) FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators10-32 Insert | | | l orque: | | | |
| To:CSA C22.2 No. 14 Industrial Control Equipment 10-32 Insert | | | 10.22 In sent | 5 (N \sim (50 \sim 1b) | | |
| UL 508 Industrial Control Equipment 9.0 N-m (80 in-lb) UL 1053 Ground Fault Sensing and Relaying Shipping Weight | To:CSA C22.2 No. 14 I | ndustrial Control Equipment | 10-32 Insert | $\dots 5.6 \text{ N-m} (50 \text{ in-lb})$ | | |
| UL 1053 Ground Fault Sensing and Relaying Snipping Weight | UL 508 Industrial C | ontrol Equipment | Others | $\dots 9.0 \text{ N-m}(80 \text{ In-ID})$ | | |
| Equipment CE Low Voltage Directive IEC 61010-1:2010 (3 rd Edition) Maximum Voltage | UL 1053 Ground Fa | ult Sensing and Relaying | Snipping weight | 5.0 kg (11 lb) | | |
| CE Low Voltage Directive IEC 61010-1:2010 (3 rd Edition) FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators Maximum Voltage | Equipment | | ED $15VV$ | | | |
| IEC 61010-1:2010 (3 rd Edition) Maximum Votage | CE Low Voltage Di | rective | EK-IJKV: Movimum Voltago | 8 400 Vaa | | |
| FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators Maximum Current | IEC 61010-1:2010 (| 3 rd Edition) | Maximum Current | 8,400 vac | | |
| Class A – Unintentional Radiators ComplianceRoHS Pending NOTES: (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage (1) See sensing resistor | FCC CFR47, Part 15 | 5, Subpart B, | Desistence | 100 bO | | |
| ComplianceRoHS Pending NOTES: (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage (1) See sensing resistor specifications for applicable voltag | Class A – Unintentio | onal Radiators | Thermol: | 100 KS2 | | |
| NOTES: (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage limits. (1) See sensing resistor specifications for applicable voltage (1) See sensing resistor sp | Compliance | RoHS Pending | | 1 minuto on | | |
| ⁽¹⁾ See sensing resistor specifications for applicable voltage limits. 1,900 Vac | NOTES | č | 0,400 Vac | 120 minutes off | | |
| limits. | (1) See sensing register and | ifications for applicable voltage | 1 900 Vac | Continuous | | |
| | limits | incarons for applicable voltage | Torque (Terminal N) | 9 0 N-m (80 in-lb) | | |

Shipping Weight5.0 kg (11 lb)

- ⁽²⁾ Accuracy included for EFCT-x and SE-CS30-x current sensors only.
- sensors only.
 ⁽³⁾ microSDTM and microSDHCTM are trademarks of SD-3C, LLC.
- SD-3C, LLC.
 ⁽⁴⁾ Remote-reset and pulse-enable wiring is limited to 10 m (32').
- ⁽⁵⁾ This value can be modified using SE-MON330 software. See Section 4.2.

telfuse S

ER-25KV:

| Maximum Voltage | 14,400 Vac |
|---------------------|--------------------|
| Maximum Current | 144 mA |
| Resistance | 100 kΩ |
| Thermal: | |
| 14,400 Vac | 1 minute on, |
| | 120 minutes off |
| 2,500 Vac | Continuous |
| Torque (Terminal N) | 9.0 N-m (80 in-lb) |
| Shipping Weight | 20 kg (44 lb) |
| | |

ER-35KV:

| Maximum Voltage | |
|---------------------|-----------------|
| Maximum Current | |
| Resistance | 100 kΩ |
| Thermal: | |
| 22,000 Vac | 1 minute on, |
| | 120 minutes off |
| 3,000 Vac | Continuous |
| Torque (Terminal N) | |
| Shipping Weight | 40 kg (88 lb) |
| | |

Certification.....CSA, Canada and USA C US 8 LR 53428 UL Listed USTED Ground Fault Sensing and Relaying Equipment 4FX9 E340889 CE, European Union CE

NOTES: ⁽¹⁾ Electrical specifications have been verified at a Littelfuse lab.

6.3 CURRENT SENSORS Environment:

| vironment: | | |
|-----------------------|---------------|--------------|
| Operating Temperature | 40 to 60°C (- | 40 to 140°F) |
| Storage Temperature | 55 to 80°C (- | 67 to 176°F) |

EFCT-1:

| Current Ratio | 5:0.05 A |
|--------------------|--|
| Insulation | 600-V Class |
| Window Diameter | 82 mm (3.2") |
| Shipping Weight | 0.9 kg (2.0 lb) |
| Certifications | CSA, UL, CE |
| Compliance | RoHS, IEC 60044-1 |
| Extended Operating | |
| Temperature | 55 to 60°C (-67 to 140° F) ⁽¹⁾ |
| Supplemental | 1101) |
| Specifications: | |
| | |

Trip Level Accuracy:

| ≤1 A | .1% of CT-Primary | Rating |
|------|-------------------|--------|
| >1 A | .3% of CT-Primary | Rating |

| EFCT-26: | |
|---------------------|---|
| Current Ratio | 5:0.05 A |
| Insulation | 600-V Class |
| Window Diameter | 26 mm (1.0") |
| Shipping Weight | 0.45 kg (1.0 lb) |
| Certifications | CSA, ŬĹ, CE |
| Compliance | RoHS, IEC 60044-1 |
| Extended Operating | |
| Temperature | 55 to 60°C (-67 to |
| 1 | $(140^{\circ}F)^{(1)}$ |
| Supplemental | |
| Specifications. | |
| Trip Level Accuracy | |
| <1 A | 1% of CT-Primary Rating |
| > 1 A | 3% of CT-Primary Rating |
| - 171 | |
| SE-CS10-2.5: | |
| Current Ratio | 1,000:5 A |
| Insulation | 600-V Class |
| Window Diameter | 63 mm (2.5") |
| Shipping Weight | 0.7 kg (1.5 lb) |
| Certifications | CE |
| Compliance | IEC 60044-1 |
| I | |
| SE-CS30-26: | |
| Current Ratio | 30:0.05 A |
| Insulation | 600-V Class |
| Window Diameter | 26 mm (1.0") |
| Shipping Weight | 0.45 kg (1.0 lb) |
| Certifications | CSA, UL, CE |
| Compliance | RoHS, IEC 60044-1 |
| Extended Operating | |
| Temperature | 55 to 60°C (-67 to |
| | $140^{\circ}\text{F})^{(1)}$ |
| | |
| SE-CS30-70: | 20.0.05.4 |
| Current Ratio | 30:0.05 A |
| Insulation | 600-V Class |
| Window Diameter | 70 mm (2.77) |
| Shipping Weight | 1.2 kg (2.5 lb) |
| Certifications | CSA, UL, CE |
| Compliance | RoHS, IEC 60044-1 |
| Extended Operating | |
| Temperature | 55 to 60°C (-67 to |
| | $140^{\circ}F)^{(1)}$ |
| CT200. | |
| Current Patio | 200.5 1 |
| Insulation | 600-V Class |
| Window Diameter | $56 \text{ mm} (2.2^{\circ})$ |
| Shinning Weight | $1 k \sigma (2.2 b)$ |
| Certifications | $\frac{1}{CSA} III$ |
| Compliance | DOHS |
| Extended Operating | |
| Extended Operating | 55 to 60°C (67 to |
| remperature | 33 10 00 C (-0/ 10 1409E) ⁽¹⁾ |
| | 140 Г) |
| NOTES: | |
| | |

N((1) Electrical specifications have been verified at a Littelfuse lab.

7. ORDERING INFORMATION

| SE-330- 🗌 | | |
|-----------|---|--|
| | K4 Contact: 0 N.O. UNIT HEALTHY Contact 1 N.C. UNIT HEALTHY Contact Options: 0 No Options | |
| | Network Communications: ⁽¹⁾ 0 None 1 DeviceNet [™] 3 Ethernet (Dual RJ45) 4 Ethernet (SC Fiber & RJ45) 5 Ethernet (Dual SC Fiber) 6 IEC 61850 (Dual RJ45) 7 IEC 61850 (SC Fiber & RJ45) 8 IEC 61850 (Dual SC Fiber) Supply | |
| L | 0 Universal ac/dc Supply 48 Vdc Supply 48 Vdc Supply | |

NOTE: Please refer to the SE-330 Product Change Notice (PCN) document for updated ordering information and new revision details, available at www.littelfuse.com/se-330.

NOTE: The SE-330-SMA Surface Mount Adapter is available as an accessory only.

Sensing Resistors:

| ER-600VC | |
|----------|---------------------------|
| | 1 kVac |
| ER-5KV | |
| | 5 kVac |
| ER-5WP | |
| | 5 kVac, weather protected |
| ER-15KV | |
| | 15 kVac |
| ER-25KV | |
| | 25 kVac |
| ER-35KV | |
| | 35 kVac |
| | |

Current Sensors:

| EFCT-1 | Current Sensor, |
|-------------|-------------------------------------|
| | 5-A-primary rating, |
| | 82-mm (3.2") Window, |
| | 6 m (19.5') of 22 AWG |
| | (3.3 mm^2) shielded cable |
| | included |
| EFCT-26 | Current Sensor, |
| | 5-A-primary rating, |
| | 26-mm (1.0") Window, |
| | 6 m (19.5') of 22 AWG |
| | (3.3 mm^2) shielded cable |
| | included |
| SE-CS10-2.5 | Current Sensor, 30-A- |
| | primary rating, 63 mm |
| | (2.5") window |

| SE-CS30-26 | Current Sensor, |
|-------------------------|--|
| | 30-A-primary rating, |
| | 26-mm (1.0") window |
| SE-CS30-70 | Current Sensor. |
| | 30-A-primary rating |
| | $70 \text{ mm} (2.7^{\circ}) \text{ window}$ |
| CT200 | Comment Sames |
| C1200 | Current Sensor, |
| | 200-A-primary rating, |
| | 56-mm (2.2") window |
| 5SHT-101-E | Current Sensor, |
| | 100-A-primary rating |
| | 40-mm (1.6") window |
| 58HT 151 E | Current Sensor |
| JSH1-131-L | 150 A grimory noting |
| | 150-A-primary rating, |
| | 40-mm (1.6") window |
| 5SHT-500-Е | Current Sensor, |
| | 50-A-primary rating, |
| | 40-mm (1.6") window |
| 7SHT-301-E | Current Sensor, |
| | 300-A-primary rating |
| | 64-mm (2.5") window |
| 78HT 401 E | Current Sensor |
| /SIII-401-L | 400 A minimum matin |
| | 400-A-primary rating, |
| | $64\text{-mm}(2.5^{\prime\prime})$ window |
| | |
| Accessories: | |
| RK-332 | Remote Indication and |
| | Reset, includes two 120-V |
| | pilot lights, a reset push |
| | button and legend plates |
| SE-IP65CVR-G | Hinged transparent cover |
| 5L-11 05C V K-G | ID25 |
| | IP05 |
| SE-MRE-600 | Moisture-resistant |
| | enclosure for ER-600VC |
| PGA-0520 | Percent Analog Meter |
| SE-330-SMA | Surface Mount Adapter |
| AC300-MEM-00 | Industrial-Grade |
| | microSD [™] Card |
| | |
| Software ⁽²⁾ | |
| SE-MON330 Software | SE-330 Data Display |
| SE-MON330 Soltware | Drogroup for DC |
| | Program for PC, version |
| | 3.5 or newer |
| NGR Monitor | |
| Set-Point Assistant | Setting Guide |
| NOTES. | |

NOTES: ⁽¹⁾ Profibus models only available on legacy SE-330. ⁽²⁾ Available at www.littelfuse.com/relayscontrols.

8. WARRANTY

The SE-330 Neutral-Grounding-Resistor Monitor is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an SE-330 that is determined by Littelfuse Startco to be defective if it is returned to Littelfuse Startco, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.

9. TEST PROCEDURES

NOTE: Ensure the real-time clock is set. See Section 4.2.

9.1 RESISTOR-FAULT TESTS

Perform tests with system de-energized and supply voltage applied to the SE-330.

9.1.1 CALIBRATION AND OPEN TEST

Test Equipment: 20-k Ω and 100-k Ω , 1/4-watt, 1% calibration resistors (calibration resistors are supplied with SE-330).

Procedure:

- Remove connections to terminals 6 and 7.
- Connect the 20-k Ω resistor to terminals 6 and 7.
- Set switch S5 to the 20-k Ω position.
- Perform calibration as per Section 2.2.
- The CALIBRATED LED should be on.
- Press RESET.
- Remove the 20-k Ω resistor and wait for the resistor-fault trip time.

PASS: The SE-330 should trip on resistor fault.

- Connect the 100-k Ω resistor to terminals 6 and 7.
- Set switch S5 to the 100-k Ω position.
- Perform calibration as per Section 2.2. The CALIBRATED LED should be on.
- Press RESET.
- Remove the 100-k Ω resistor and wait for the resistor-fault trip time.

PASS: The SE-330 should trip on resistor fault.

NOTE: Resistor-fault-trip reset can take up to one second.

9.1.2 VOLTAGE TEST

Test Equipment: 0 to 120 Vac voltage source, multimeter, and ER sensing resistor.

NOTE: Use an isolation transformer if the test-voltage source does not provide dc continuity for the SE-330 resistance-measuring circuit.

NOTE: Applying the test voltage to the R and G terminals will damage the SE-330 and the ER sensing resistor. The V_N TRIP LEVEL is the trip voltage at terminal N, not terminal R.

Procedure:

- Connect the ER sensing resistor to the SE-330 and calibrate the SE-330.
- Disconnect the wire from sensing-resistor terminal N. A resistor-fault trip will occur.
- Set the voltage source to 0 V.
- Connect the voltage source between sensing resistor N and G terminals.
- Set the V_N TRIP LEVEL (VAC) to 20.
- Press RESET.
- The RESISTOR FAULT TRIP LED should be off.
- Increase the test voltage to 25 Vac for 20-kΩ sensors or 120 Vac for 100-kΩ sensors and wait for the resistorfault trip time.

PASS: The SE-330 should trip on RESISTOR FAULT. A time-delayed ground-fault trip follows the resistor-fault trip if neutral voltage persists after the resistor fault. For legacy units with firmware revision 6 or less, this does not apply.

9.2 SENSING-RESISTOR TEST

Test Equipment: Multimeter.

Procedure:

- Disconnect the sensing resistor.
- Measure the resistance between sensing-resistor terminals R and N.

PASS: Resistance should be between 19.6 and 20.4 k Ω for 20-k Ω sensing resistors. Resistance should be between 98 and 102 k Ω for 100-k Ω sensing resistors.

• Measure the resistance between sensing-resistor terminals R and G in both directions.

PASS: Resistance should be greater than 10 M Ω in both directions.

9.3 ANALOG-OUTPUT TEST

Test Equipment: Multimeter with a mAdc scale. Procedure:

• Connect the 4–20-mA output as a self-powered output as shown in Fig. 3. Measure the current from terminal 20 to terminal 21.

PASS: With no CT current, the analog output should be 4 mA.

• Output is linear to 20 mA. Output is 20 mA when CTprimary current is equal to the CT-primary rating.

9.4 GROUND-FAULT PERFORMANCE TEST

To meet the requirements of the National Electrical Code (NEC), as applicable, the overall ground-fault protection system requires a performance test when first installed. A written record of the performance test is to be retained by those in charge of the electrical installation in order to make it available to the authority having jurisdiction. A test-record form is provided for recording the date and the final results of the performance tests. The following ground-fault system tests are to be conducted by qualified personnel:

- a) Evaluate the interconnected system in accordance with the overall equipment manufacturer's detailed instructions.
- b) Verify proper installation of the ground-fault current sensor. Ensure the cables pass through the groundfault-current-sensor window. This check can be done visually with knowledge of the circuit. The connection of the current-sensor secondary to the SE-330 is not polarity sensitive.
- c) Verify that the system is correctly grounded and that alternate ground paths do not exist that bypass the current sensor. High-voltage testers and resistance bridges can be used to determine the existence of alternate ground paths.
- d) Verify proper reaction of the circuit-interrupting device in response to a simulated or controlled ground-fault current. To simulate ground-fault current, use CT-primary current injection (does not apply for bushing-type CT's). Fig. 23a shows a test circuit using an SE-400 Ground-Fault-Relay Test Unit. The SE-400 has a programmable output of 0.5 to 9.9 A for a duration of 0.1 to 9.9 seconds. Set the test current to 120% of GF TRIP LEVEL. Fig. 23b shows a test circuit using an SE-100T Ground-Fault-Relay Tester. The SE-100T provides a test current of 0.65 or 2.75 A for testing 0.5- and 2.0-A trip levels. Inject the test current through the current-sensor window for at least 2.5 seconds. Verify that the circuit under test has reacted properly. Correct any problems and re-test until the proper reaction is verified.
- e) Record the date and the results of the test on the attached test-record form.

NOTE: Do not inject test current directly into CT-input terminals 8, 9, 10, and 11.

NOTE: For accurate trip-time measurement, the fault current should not be re-applied for the time defined by the GF TRIP TIME setting to allow the trip accumulator to initialize.

FIGURE 23. Ground-Fault-Test Circuits.

| TABLE 3 | GROUND-FAULT-TEST RECORD |
|--------------|---------------------------|
| I A D L L J. | GROUND-I AULI-ILSI RECORD |

| DATE | TEST RESULTS |
|------|--------------|
| | |
| | |
| | |
| | |
| | |
| | |
| | |
| | |
| | |
| | |
| | |
| | |

Retain this record for the authority having jurisdiction.

| MANUAL RELEASE DATE | MANUAL REVISION | HARDWARE REVISION (REVISION NUMBER ON PRODUCT LABEL) | FIRMWARE REVISION |
|------------------------|--------------------|--|-------------------|
| June 22, 2015 | 10-J-062215 | 15 | 2.50 |
| May 20, 2015 | 10-I-052015 | | 2.40 |
| March 3, 2015 | 10-Н-030315 | | |
| July 7, 2014 | 10-G-070714 | 14 | 2.31 2.30 |
| April 14, 2014 | 10-F-041414 | 13 | 2.20 |
| January 8, 2014 | 10-E-010814 | 12 | |
| | | 11 | |
| November 29, 2013 | 10-D-112913 | 10A | 2.10 |
| October 8, 2013 | 10-C-100813 | | 2.08 |
| September 12, 2013 | 10-B-091213 | | 2.07 |
| August 30, 2013 | 10-A-083013 | 10 | 2.07 |

APPENDIX A SE-330 REVISION HISTORY

MANUAL REVISION HISTORY

REVISION 10-J-062215

SECTION 2

Section 2.1.7 added.

SECTION 4

SD Card approximate yearly data logging usage updated. SE-MON330 software version updated.

SECTION 6

Resistor-fault trip level ranges added.

REVISION 10-I-030315

SECTION 4

SD Card storage capacity updated.

SECTION 6

SD Card storage capacity specification updated.

REVISION 10-H-030315

SECTION 2

Sections 2.1.6 and 2.1.7 added.

SECTION 4

Section 4.2 new features added.

SECTION 6

Resistor-fault circuit trip time updated.

REVISION 10-G-070714

SECTION 6

Added CE, C-Tick, and FCC information.

REVISION 10-F-041414

APPENDIX A

Hardware revision updated.

REVISION 10-E-010814

SECTION 6

Extended operating temperatures added to all sensing resistors and SE-CS30 current sensors.

REVISION 10-D-112913

SECTION 6

CE added to sensing resistors.

SECTION 7

Ordering information updated.

REVISION 10-C-100813

SECTION 2

Section 2.8 updated.

SECTION 4

Real Time Clock note added in Section 4.2.

SECTION 5

LED and relay status added to troubleshooting solutions.

SECTION 7

Ordering information updated.

REVISION 10-B-091213

APPENDIX A

Hardware revision updated.

REVISION 10-A-083013

SECTION 1

Faceplate updated.

New features added.

SECTION 2

Communications options updated. Configuration switches updated. Indication relays explanation added. Non-volatile-memory error added.

SECTION 3

Connection drawing updated.

SECTION 4

Section heading changed to Data Interfaces. Updated with microSD[™] and USB interfaces. Upgrade procedure added.

SECTION 5

Non-volatile-memory error added. Switch S8 diagnostic LED error removed.

SECTION 6

Ground-fault circuit trip level updated. USB communications specifications added. Resistor-fault accuracy changed. microSD[™] memory card specifications added.

SECTION 7

Ordering information updated.

SE-330-SMA Surface Mount Adapter is now listed as an accessory only.

APPENDIX A

Added revision history.

HARDWARE REVISION HISTORY

HARDWARE REVISION 15

RTC circuit updated.

HARDWARE REVISION 14

Added CE and C-Tick compliance.

HARDWARE REVISION 13

Reduced ESD sensitivity of front-panel dials.

HARDWARE REVISION 12

Improved Fiber Ethernet support.

HARDWARE REVISION 11

Reduced ESD sensitivity of USB and SD card connectors.

HARDWARE REVISION 10A

Update to RTC circuit.

HARDWARE REVISION 10

Updated SE-330 platform to include USB and microSD[™] interfaces, programmable trip level (MEM) feature, and ability to add future options. Real-time clock added.

Added dual cable and fiber Ethernet ports.

FIRMWARE REVISION HISTORY

FIRMWARE REVISION 2.50

Added support for adjustable resistor-fault trip level.

Web page functionality re-enabled for Ethernet options.

FIRMWARE REVISION 2.40

Added support for geo-magnetic filter.

Added support for 12 to 60 s resistor-fault trip time.

Improved log file descriptions.

IEC 61850 GOOSE network input support now always enabled.

Improved compatibility for Modbus TCP.

Web page disabled for Ethernet options. This will be enabled in a future firmware release.

IP setting changes for Ethernet options now require power cycle to take effect.

FIRMWARE REVISION 2.31

SD Card and USB diagnostic events no longer cause a trip.

FIRMWARE REVISION 2.30

Remote calibration feature added.

FIRMWARE REVISION 2.20

Added support for EtherNet/IP protocol.

IED name now reported correctly through IEC 61850 interface.

EtherNet/IP and Modbus communications card LED status updated.

Hardware version viewable in the SE-MON330 software and through the Modbus and IEC 61850 servers.

FIRMWARE REVISION 2.10

Added support for IEC 61850 and DeviceNet protocols.

FIRMWARE REVISION 2.08

Added support for communications options.

FIRMWARE REVISION 2.07

Updated firmware to include USB and microSD[™] interfaces, datalogging, and firmware update via microSD[™]. K2 and K3 indication relays can be configured for fail-safe or non-fail-safe operation.

Trip records increased to 100 with date and time stamping.

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