

## FEATURES

High accuracy reference output voltage:  $1 V \pm 0.9\%$ Single-supply voltage operation: 2.3 V to 5.5 VRail-to-rail common-mode input voltage range Low input offset voltage across V<sub>CMR</sub>: 1 mV typical Guarantees comparator output logic low from V<sub>cc</sub> = 0.9 V to undervoltage lockout (UVLO) Operating temperature range:  $-40^{\circ}$ C to  $+125^{\circ}$ C 10-lead mini small outline package (MSOP)

## **APPLICATIONS**

Battery management/monitoring Power supply detection Window comparators Threshold detectors/discriminators Microprocessor systems

## **GENERAL DESCRIPTION**

The ADCMP395 is a dual, rail-to-rail input, low power comparator ideal for use in general-purpose applications. The device operates from a supply voltage of 2.3 V to 5.5 V and draws a minimal amount of current. The dual ADCMP395 consumes only 37.2  $\mu$ A of supply current. The low voltage and low current operation of the ADCMP395 make it ideal for battery-powered systems.

The ADCMP395 features a common-mode input voltage range of 200 mV beyond the rails, an offset voltage of 1 mV typical across the full common-mode range, and a UVLO monitor. In addition, the design of the comparator allows a defined output state upon power-up. The comparator generates a logic low output when the supply voltage is less than the UVLO threshold.

The ADCMP395 incorporates a 1 V  $\pm$  0.9% buffered reference voltage. The reference voltage output can directly connect to the comparator input to serve as the trip value for precise monitoring and detection of positive voltage. It can also act as an offset when monitoring the negative voltage.

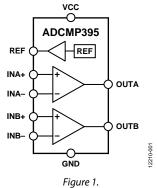
The ADCMP395 is available in a 10-lead MSOP package, and is specified to operate over the  $-40^{\circ}$ C to  $+125^{\circ}$ C extended temperature range.

# ADCMP395

**Dual Comparator with** 

### FUNCTIONAL BLOCK DIAGRAM

Accurate Reference Output



#### Rev. 0

#### Document Feedback

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# TABLE OF CONTENT

Features 1	L
Applications1	L
Functional Block Diagram1	Ĺ
General Description 1	L
Revision History 2	2
Specifications	3
Absolute Maximum Ratings 4	ł
Thermal Resistance 4	ł
ESD Caution 4	ł
Pin Configuration and Function Descriptions5	;
Typical Performance Characteristics6	5
Theory of Operation10	)
Basic Comparator10	)
Rail-to-Rail Input (RRI)10	)

## **REVISION HISTORY**

10/14—Revision 0: Initial Version

Open-Drain Output 10
Power-Up Behavior10
Crossover Bias Point
Comparator Hysteresis 10
Typical Applications
Adding Hysteresis11
Window Comparator for Positive Voltage Monitoring 11
Window Comparator for Negative Voltage Monitoring 12
Programmable Sequencing Control Circuit12
Mirrored Voltage Sequencer Example14
Threshold and Timeout Programmable Voltage Supervisor 15
Outline Dimensions
Ordering Guide

# **SPECIFICATIONS**

 $V_{CC} = 2.3 \text{ V to } 5.5 \text{ V}, T_{A} = -40^{\circ}\text{C to } + 125^{\circ}\text{C}, V_{CMR} = -200 \text{ mV to } V_{CC} + 200 \text{ mV, unless otherwise noted.}$  Typical values are at  $T_{A} = 25^{\circ}\text{C}$ .

	Conselle al	NA:	<b>T</b>	Maria	11	Test Conditions/Commentel
Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments <sup>1</sup>
POWER SUPPLY						
Supply Voltage Range	V <sub>cc</sub>	2.3		5.5	V	
		0.9		UVLORISE	V	Guarantees comparator output low
V <sub>cc</sub> Quiescent Current	Icc		37.2	51.9	μΑ	All outputs in high-Z state, $V_{\text{OD}} = 0.1 \text{ V}$
			35.9	49.2	μΑ	All outputs low, $V_{OD} = 0.1 V$
UNDERVOLTAGE LOCKOUT						
Vcc Rising	UVLORISE	2.062	2.162	2.262	V	
Hysteresis	<b>UVLO</b> <sub>HYS</sub>	5	25	50	mV	
REFERENCE OUTPUT						
Reference Output Voltage	VREF	0.991	1	1.008	v	$I_{REF} = \pm 1 \text{ mA}, T_A = -40^{\circ}\text{C to} +85^{\circ}\text{C}$
	• ner	0.991	1	1.008	v	$I_{\text{REF}} = \pm 1 \text{ mA}$
COMPARATOR INPUT		0.551	•	1.000		
Common-Mode Input Range	V <sub>CMR</sub>	-200		Vcc + 200	mV	
Input Offset Voltage	V CMR Vos	-200	0.5	Vcc + 200 2.5	mV	IN+=IN-=1V
input Onset voltage	VOS					
			0.5	2.5	mV	$IN+=IN-=1$ V, $T_A = -40$ °C to +85°C
			1	5	mV	
			1	5	mV	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$
Input Offset Current	los			10	nA	$V_{CMR} = -50 \text{ mV} \text{ to } V_{CC} + 50 \text{ mV}$
Input Bias Current	I <sub>BIAS</sub>			±30	nA	IN+=IN-=1V
				±80	nA	$V_{CMR} = -50 \text{ mV}$ to $V_{CC} + 50 \text{ mV}$
				±10	nA	$V_{CMR} = -50 \text{ mV}$ to $V_{CC} + 50 \text{ mV}$ ,
						$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$
Input Hysteresis	V <sub>HYST</sub>		3	4	mV	$V_{CM} = 1 V$
			6	8	mV	
COMPARATOR OUTPUT						
Output Low Voltage	Vol		0.1	0.3	V	$V_{CC} = 2.3 V$ , $I_{SINK} = 2.5 mA$
			0.01	0.15	V	$V_{CC} = 0.9 \text{ V}, \text{ I}_{SINK} = 100 \mu\text{A}$
Output Leakage Current	ILEAK			150	nA	V <sub>OUT</sub> = 0 V to 5.5 V
COMPARATOR CHARACTERISTICS						
Power Supply Rejection Ratio	PSRR	60	80		dB	
Common-Mode Rejection Ratio	CMRR	50	74		dB	
Voltage Gain	Av	50	132		dB	
Rise Time <sup>2</sup>			1.1			$M = 100\% \pm 0.00\% \text{ of } M$
	t <sub>R</sub>				μs	$V_{OUT} = 10\%$ to 90% of V <sub>CC</sub>
Fall Time <sup>2</sup>	t⊧		0.15		μs	$V_{OUT} = 90\%$ to 10% of $V_{CC}$
Propagation Delay						
Input Rising <sup>2</sup>	tprop_r					
Channel A			4.7		μs	$V_{CM} = 1 \text{ V}, V_{CC} = 2.3 \text{ V}, V_{OD} = 10 \text{ mV}$
			4.9		μs	$V_{CM} = 1 V, V_{CC} = 5 V, V_{OD} = 10 mV$
Channel B			4.9		μs	$V_{CM} = 1 \text{ V}, V_{CC} = 2.3 \text{ V}, V_{OD} = 10 \text{ mV}$
			9.7		μs	$V_{CM} = 1 V, V_{CC} = 5 V, V_{OD} = 10 mV$
	t <sub>PROP_F</sub>					
Input Falling <sup>2</sup>		1	4.5		μs	$V_{CM} = 1 V, V_{CC} = 2.3 V, V_{OD} = 10 mV$
Input Falling <sup>2</sup> Channel A			4.5		μ	VCM = 1 V, VCC = 2.5 V, VOD = 10 111V
			4.5 9.5			
					μs μs μs	$V_{CM} = 1 V, V_{CC} = 2.3 V, V_{OD} = 10 mV$ $V_{CM} = 1 V, V_{CC} = 5 V, V_{OD} = 10 mV$ $V_{CM} = 1 V, V_{CC} = 2.3 V, V_{OD} = 10 mV$

 $^1$   $V_{\text{OD}}$  is overdrive voltage.  $^2$   $R_{\text{PULL-UP}} = 10$  k $\Omega,$  and  $C_{\text{L}} = 50$  pF.

# **ABSOLUTE MAXIMUM RATINGS**

#### Table 2.

1 4010 21	
Parameter	Rating
VCC Pin	–0.3 V to +6 V
All INx+ and INx- Pins	–0.3 V to +6 V
All OUTx Pins	–0.3 V to +6 V
Reference Load Current, IREF	±1 mA
OUTx Pins Sink Current, Isink	10 mA
Storage Temperature Range	–65°C to +150°C
Operating Temperature Range	–40°C to +125°C
Lead Temperature (10 sec)	300°C
Junction Temperature	150°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

#### Table 3. Thermal Resistance

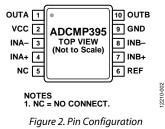
Package Type	Αιθ	Unit
10-Lead MSOP	130	°C/W

## **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**



Pin No.	Mnemonic	Description
1	OUTA	Comparator A Output, Open Drain.
2	VCC	Device Supply Input.
3	INA-	Comparator A Inverting Input.
4	INA+	Comparator A Noninverting Input.
5	NC	No Connect. Leave floating.
6	REF	Reference Output. Use this pin to set up comparator threshold.
7	INB+	Comparator B Noninverting Input.
8	INB-	Comparator B Inverting Input.
9	GND	Device Ground.
10	OUTB	Comparator B Output, Open Drain.

## Rev. 0 | Page 5 of 16

# ADCMP395

# **TYPICAL PERFORMANCE CHARACTERISTICS**

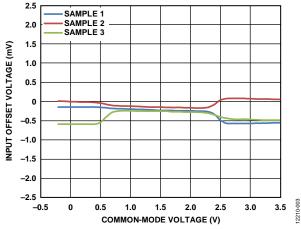


Figure 3. Input Offset Voltage (Vos) vs. Common-Mode Voltage (Vom),  $V_{CC} = 3.3 V$ 

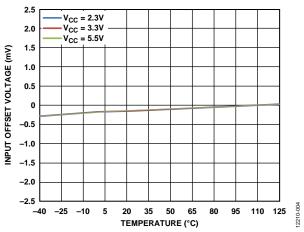


Figure 4. Input Offset Voltage ( $V_{OS}$ ) vs. Temperature for Various Supply Voltages,  $V_{CM} = 1 V$ 

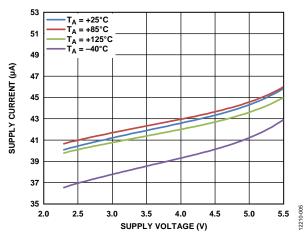


Figure 5. Supply Current (I<sub>cc</sub>) vs. Supply Voltage (V<sub>cc</sub>) at Output Low Voltage for Various Temperatures

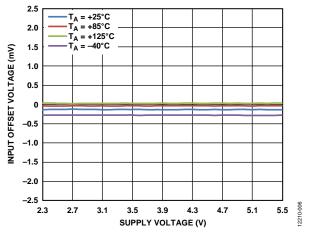


Figure 6. Input Offset Voltage ( $V_{CS}$ ) vs. Supply Voltage ( $V_{CC}$ ),  $V_{CM} = 1 V$ for Various Temperatures

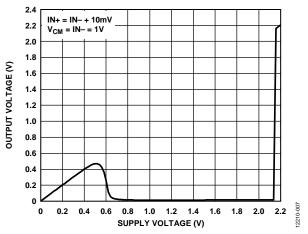


Figure 7. Output Voltage (V<sub>OUT</sub>) vs. Supply Voltage (V<sub>CC</sub>),  $R_{PULL-UP} = 10 k\Omega$ 

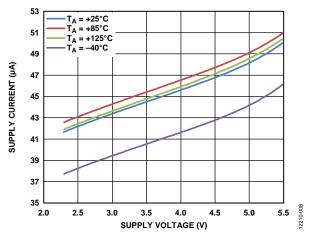


Figure 8. Supply Current (Icc) vs. Supply Voltage (Vcc) at Output High Voltage for Various Temperatures

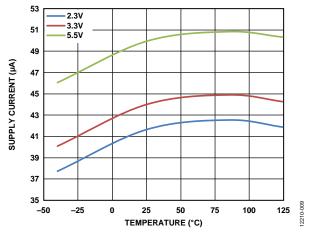
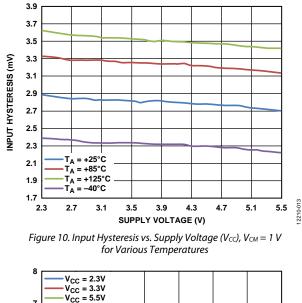
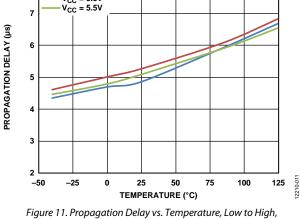
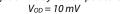


Figure 9. Supply Current ( $I_{cc}$ ) vs. Temperature at Output High Voltage ( $V_{OH}$ ) for Various Supply Voltages ( $V_{cc}$ )







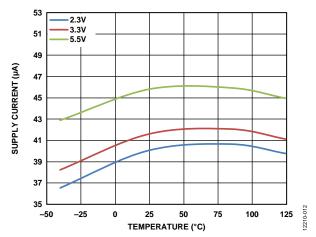


Figure 12. Supply Current (I<sub>cc</sub>) vs. Temperature at Output Low Voltage (V<sub>ol</sub>) for Various Supply Voltages (V<sub>cc</sub>)

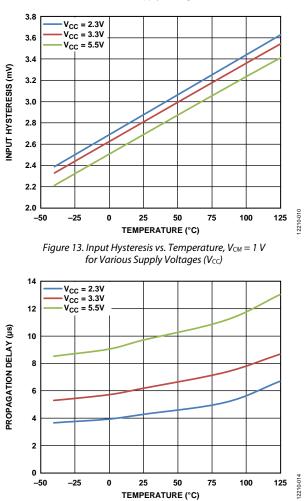


Figure 14. Propagation Delay vs. Temperature, High to Low,  $V_{\text{OD}} = 10 \text{ mV}$ 

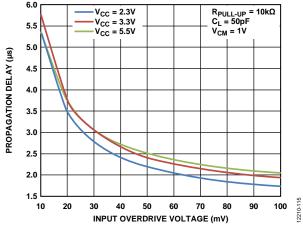


Figure 15. Propagation Delay vs. Input Overdrive Voltage, Low to High, Channel A

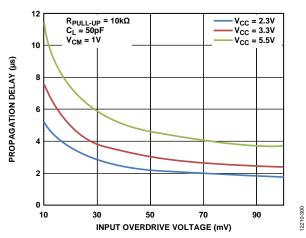


Figure 16. Propagation Delay vs. Input Overdrive Voltage, Low to High, Channel B

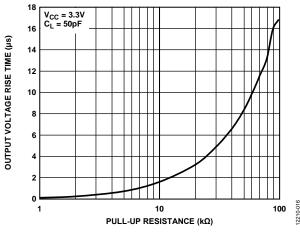


Figure 17. Output Voltage Rise Time (t<sub>R</sub>) vs. Pull-Up Resistance (R<sub>PULL-UP</sub>)

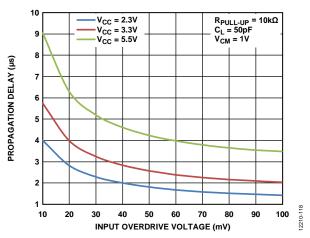


Figure 18. Propagation Delay vs. Input Overdrive Voltage, High to Low, Channel A

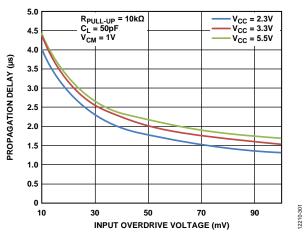


Figure 19. Propagation Delay vs. Input Overdrive Voltage, High to Low, Channel B

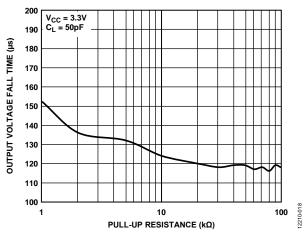


Figure 20. Output Voltage Fall Time (t<sub>F</sub>) vs. Pull-Up Resistance (R<sub>PULL-UP</sub>)

#### 1.008 1.006 1.004 $\mathfrak{S}^{1.002}$ > 1.000 0.998 0.996 0.994 0.2 0.4 0.6 0.8 1.0 1.2 1.4 1.6 1.8 2.0 12210-101 I<sub>SOURCE</sub> (mA)

Figure 21. Reference Voltage ( $V_{REF}$ ) vs. Source Current ( $I_{SOURCE}$ ) of the REF Pin,  $V_{CC} = 3.3 V$ 

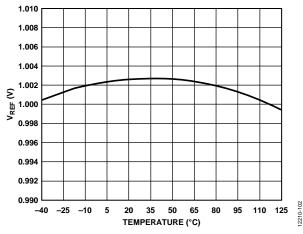


Figure 22. Reference Voltage ( $V_{REF}$ ) vs. Temperature,  $V_{CC} = 3.3 V$ 

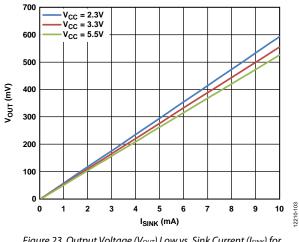


Figure 23. Output Voltage (Vour) Low vs. Sink Current (IsiNK) for Various Supply Voltages

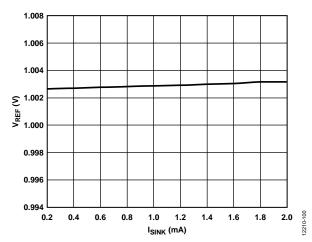


Figure 24. Reference Voltage (V<sub>REF</sub>) vs. Sink Current (I<sub>SINK</sub>) of the REF Pin, V<sub>CC</sub> = 3.3 V

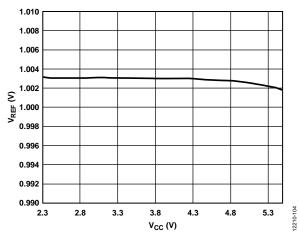


Figure 25. Reference Voltage (VREF) vs. Supply Voltage (VCC)

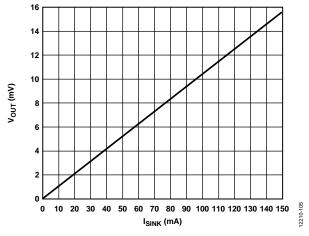


Figure 26. Output Voltage (Vout) Low vs. Sink Current (ISINK), Vcc = 0.9 V

## $V_{CC} = 3.3 V$

## THEORY OF OPERATION BASIC COMPARATOR

In its most basic configuration, a comparator can be used to convert an analog input signal to a digital output signal (see Figure 27). The analog signal on INx+ is compared to the voltage on INx-, and the voltage at OUTx is either high or low, depending on whether INx+ is at a higher or lower potential than INx-, respectively.

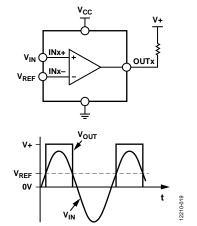


Figure 27. Basic Comparator and Input and Output Signals

## **RAIL-TO-RAIL INPUT (RRI)**

Using a CMOS nonRRI stage (that is, a single differential pair) limits the input voltage to approximately one gate-to-source voltage ( $V_{GS}$ ) away from one of the supply lines. Because  $V_{GS}$  for normal operation is commonly more than 1 V, a single differential pair input stage comparator greatly restricts the allowable input voltage. This restriction can be quite limiting with low voltage supplies. To resolve this issue, RRI stages allow the input signal range to extend up to the supply voltage range. In the case of the ADCMP395, the inputs continue to operate 200 mV beyond the supply rails.

## **OPEN-DRAIN OUTPUT**

The ADCMP395 has an open-drain output stage that requires an external resistor to pull up to the logic high voltage level when the output transistor is switched off. The pull-up resistor must be large enough to avoid excessive power dissipation, but small enough to switch logic levels reasonably quickly when the comparator output is connected to other digital circuitry. The rise time of the open-drain output depends on the pull-up resistor ( $R_{PULL-UP}$ ) and load capacitor ( $C_L$ ) used.

The rise time can be calculated by

$$t_R = 2.2 R_{PULL-UP} C_L$$

### **POWER-UP BEHAVIOR**

On power-up, when  $V_{\rm CC}$  reaches 0.9 V, the ADCMP395 is asserts an output low logic. When the voltage on the  $V_{\rm CC}$  pin exceeds UVLO, the comparator inputs take control.

## **CROSSOVER BIAS POINT**

Rail-to-rail inputs of this type of architecture in both op amps and comparators, have a dual front-end design. PMOS devices are inactive near the  $V_{CC}$  rail, and NMOS devices are inactive near GND. At some predetermined point in the common-mode range, a crossover occurs. At this point, normally 0.8 V and  $V_{CC}$  – 0.8 V, the measured offset voltages change.

## **COMPARATOR HYSTERESIS**

In noisy environments, or when the differential input amplitudes are relatively small or slow moving, adding hysteresis (V<sub>HYST</sub>) to the comparator is often desirable. The transfer function for a comparator with hysteresis is shown in Figure 28. As the input voltage approaches the threshold (0 V in Figure 28) from below the threshold region in a positive direction, the comparator switches from low to high when the input crosses +V<sub>HYST</sub>/2. The new switch threshold becomes  $-V_{HYST}/2$ . The comparator remains in the high state until the  $-V_{HYST}/2$  threshold is crossed from below the threshold region in a negative direction. In this manner, noise or feedback output signals centered on the 0 V input cannot cause the comparator to switch states unless it exceeds the region bounded by  $\pm V_{HYST}/2$ .

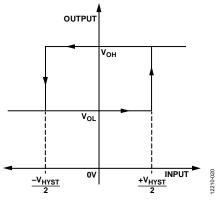


Figure 28. Comparator Hysteresis Transfer Function

(1)

## TYPICAL APPLICATIONS ADDING HYSTERESIS

To add hysteresis, see Figure 29; two resistors are used to create different switching thresholds, depending on whether the input signal is increasing or decreasing in magnitude. When the input voltage increases, the threshold is above  $V_{REF}$ , and when the input voltage decreases, the threshold is below  $V_{REF}$ .

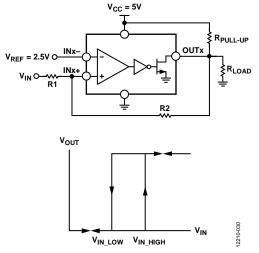


Figure 29. Noninverting Comparator Configuration with Hysteresis

The upper input threshold level is given by

$$V_{IN\_HIGH} = \frac{V_{REF}(R1+R2)}{R2}$$
(2)

Assuming  $R_{LOAD} >> R2$ ,  $R_{PULL-UP}$ .

The lower input threshold level is given by

$$V_{IN\_LOW} = \frac{V_{REF} (R1 + R2 + R_{PULL-UP}) - V_{CC} R1}{R2 + R_{PULL-UP}}$$
(3)

The hysteresis is the difference between these voltages levels.

$$V_{HYS} = \frac{V_{REF}(R1)}{R2} - \frac{RI(V_{REF} + V_{CC})}{R2 + R_{PULL-UP}}$$
(4)

# WINDOW COMPARATOR FOR POSITIVE VOLTAGE MONITORING

When monitoring a positive supply, the desired nominal operating voltage for monitoring is denoted by  $V_M$ ,  $I_M$  is the nominal current through the resistor divider,  $V_{OV}$  is the overvoltage trip point, and  $V_{UV}$  is the undervoltage trip point.

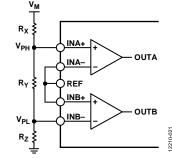


Figure 30. Positive Undervoltage/Overvoltage Monitoring Configuration

Figure 30 illustrates the positive voltage monitoring input connection. Three external resistors,  $R_X$ ,  $R_Y$ , and  $R_Z$ , divide the positive voltage for monitoring ( $V_M$ ) into the high-side voltage ( $V_{PH}$ ) and the low-side voltage ( $V_{PL}$ ). The high-side voltage is connected to the INA+ pin and the low-side voltage is connected to the INB- pin.

To trigger an overvoltage condition, the low-side voltage (in this case,  $V_{PL}$ ) must exceed the  $V_{REF}$  threshold on the INB+ pin. Calculate the low-side voltage,  $V_{PL}$ , by the following:

$$V_{PL} = V_{REF} = V_{OV} \left( \frac{R_Z}{R_X + R_Y + R_Z} \right)$$
(5)

In addition,

$$R_X + R_Y + R_Z = V_M / I_M \tag{6}$$

Therefore, R<sub>Z</sub>, which sets the desired trip point for the overvoltage monitor, is calculated as

$$R_{Z} = \frac{\left(V_{REF}\right)\left(V_{M}\right)}{\left(V_{OV}\right)\left(I_{M}\right)} \tag{7}$$

To trigger the undervoltage condition, the high-side voltage,  $V_{PH}$ , must be less than the  $V_{REF}$  threshold on the INA– pin. The high-side voltage,  $V_{PH}$ , is calculated by

$$V_{PH} = V_{REF} = V_{UV} \left( \frac{R_Y + R_Z}{R_X + R_Y + R_Z} \right)$$
(8)

Because  $R_Z$  is already known,  $R_Y$  can be expressed as

$$R_Y = \frac{(V_{REF})(V_M)}{(V_{UV})(I_M)} - R_Z$$
(9)

When R<sub>Y</sub> and R<sub>Z</sub> are known, R<sub>X</sub> can be calculated by

$$R_X = (V_M/I_M) - R_Y - R_Z$$
(10)

If V<sub>M</sub>, I<sub>M</sub>, V<sub>OV</sub>, or V<sub>UV</sub> changes, each step must be recalculated.

# WINDOW COMPARATOR FOR NEGATIVE VOLTAGE MONITORING

Figure 31 shows the circuit configuration for negative supply voltage monitoring. To monitor a negative voltage, a reference voltage is required to connect to the end node of the voltage divider circuit, in this case, REF.

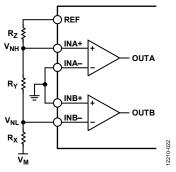


Figure 31. Negative Undervoltage/Overvoltage Monitoring Configuration

Equation 7, Equation 9, and Equation 10 need some minor modifications. The reference voltage,  $V_{REF}$ , is added to the overall voltage drop; therefore, it must be subtracted from  $V_{M}$ ,  $V_{UV}$ , and  $V_{OV}$  before using each of them in Equation 7, Equation 9, and Equation 10.

To monitor a negative voltage level, the resistor divider circuit divides the voltage differential level between  $V_{REF}$  and the negative supply voltage into the high-side voltage,  $V_{NH}$ , and the low-side voltage,  $V_{NL}$ . The high-side voltage,  $V_{NH}$ , is connected to INA+, and the low-side voltage,  $V_{NL}$ , is connected to INB–.

To trigger an overvoltage condition, the monitored voltage must exceed the nominal voltage in terms of magnitude, and the high-side voltage (in this case,  $V_{NH}$ ) on the INA+ pin must be more negative than ground. Calculate the high-side voltage,  $V_{NH}$ , by using the following formula:

$$V_{NH} = GND = \left[ \left( V_{REF} - V_{OV} \right) \left( \frac{R_X + R_Y}{R_X + R_Y + R_Z} \right) \right] + V_{OV}$$
(11)

In addition,

$$R_X + R_Y + R_Z = \frac{\left(V_M - V_{REF}\right)}{I_M} \tag{12}$$

Therefore, R<sub>Z</sub>, which sets the desired trip point for the overvoltage monitor, is calculated by

$$R_{Z} = \frac{-V_{REF} (V_{M} - V_{REF})}{I_{M} (V_{OV} - V_{REF})}$$
(13)

To trigger an undervoltage condition, the monitored voltage must be less than the nominal voltage in terms of magnitude, and the low-side voltage (in this case,  $V_{\rm NL}$ ) on the INB– pin must be more positive than ground. Calculate the low-side voltage,  $V_{\rm NL}$ , by the following:

$$V_{NL} = GND = \left[ \left( V_{REF} - V_{UV} \left( \frac{R_X}{R_X + R_Y + R_Z} \right) \right] + V_{UV}$$
(14)

Because R<sub>Z</sub> is already known, R<sub>Y</sub> can be expressed as follows:

$$R_{Y} = \frac{-V_{REF}(V_{M} - V_{REF})}{I_{M}(V_{UV} - V_{REF})} - R_{Z}$$
(15)

When  $R_Y$  and  $R_Z$  are known,  $R_X$  is then calculated by

$$R_X = \frac{\left(V_M - V_{REF}\right)}{I_M} - R_Y - R_Z \tag{16}$$

## PROGRAMMABLE SEQUENCING CONTROL CIRCUIT

The circuit shown in Figure 32 is used to control power supply sequencing. The delay is set by the combination of the pull-up resistor ( $R_{PULL-UP}$ ), the load capacitor ( $C_L$ ), and the resistor divider network.

V<sub>REF</sub>/V<sub>CC</sub>

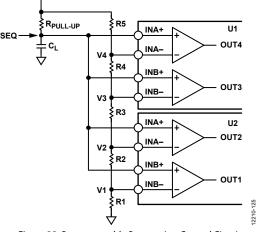


Figure 32. Programmable Sequencing Control Circuit

Figure 33 shows a simple block diagram for a programmable sequencing control circuit. The application delays the enable signal, EN, of the external regulators (LDO x) in a linear order when the open-drain signal (SEQ) changes from low to high impedance.

The ADCMP395 has a defined output state during startup, which prevents any regulator from turning on if  $V_{\rm CC}$  is still below the UVLO threshold.

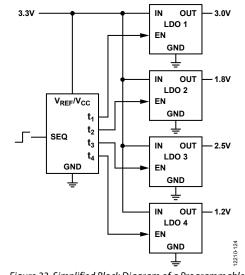


Figure 33. Simplified Block Diagram of a Programmable Sequencing Control Circuit

Rev. 0 | Page 12 of 16

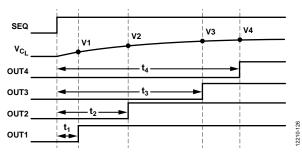


Figure 34. Programmable Sequencing Control Circuit Timing Diagram

When the SEQ signal changes from low to high impedance, the load capacitor,  $C_L$ , starts to charge. The time it takes to charge the load capacitor to the pull-up voltage (in this case,  $V_{REF}$  or  $V_{CC}$ ) is the maximum delay programmable in the circuit. It is recommended to have the threshold within 10% to 90% of the pull-up voltage. Calculate the maximum allowable delay by

$$t_{MAX} = 2.2R_{PULL-UP}C_{LOAD} \tag{17}$$

The delay of each output is changed by changing the threshold voltage, V1 to V4, when the comparator changes its output state.

To calculate the voltage thresholds for the comparator, use the following formulas:

$$VI = V_{REF} \left( 1 - e^{\frac{-t_1}{R_{FUL-UF}C_L}} \right)$$
(18)

$$V2 = V_{REF} \left( 1 - e^{\frac{-t_2}{R_{PUIL-UF}C_L}} \right)$$
(19)

$$V3 = V_{REF} \left( 1 - e^{\frac{-t_3}{R_{PUIL-UP}C_L}} \right)$$
(20)

$$V4 = V_{REF} \left( 1 - e^{\frac{-t_4}{R_{PUIL-UP}C_L}} \right)$$
(21)

The threshold voltages can come from a voltage reference or a voltage divider circuit, as shown in Figure 32.

First, determine the allowable current,  $I_{DIV}$ , flowing through the resistor divider. After the value for  $I_{DIV}$  is determined, calculate R1, R2, R3, R4, and R5 using the following formulas:

$$R_{DIV} = \frac{V_{REF}}{I_{DIV}} = R1 + R2 + R3 + R4 + R5$$
(22)

$$RI = \frac{VIR_{DIV}}{V_{REF}}$$
(23)

$$R2 = \frac{V2R_{DIV}}{V_{REF}} - R1 \tag{24}$$

$$R3 = \frac{V3R_{DIV}}{V_{PEE}} - R1 - R2$$
(25)

$$R4 = \frac{V4R_{DIV}}{V_{REF}} - R1 - R2 - R3$$
(26)

$$R5 = R_{DIV} - R1 - R2 - R3 - R4 \tag{27}$$

To create a mirrored voltage sequence, add a resistor ( $R_{MIRROR}$ ) between the pull-up resistor ( $R_{PULL-UP}$ ) and the load capacitor ( $C_L$ ) as shown in Figure 35.

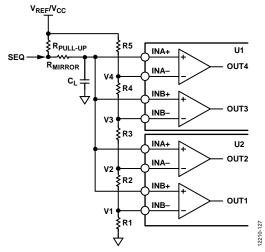


Figure 35. Circuit Configuration for a Mirrored Voltage Sequencer

Figure 35 shows the circuit configuration for a mirrored voltage sequencer. When SEQ changes from low to high impedance, the response is similar to Figure 34. When SEQ changes from high to low impedance, the load capacitor ( $C_L$ ) starts to discharge at a rate set by  $R_{MIRROR}$ . The delay of each comparator is dependent on the threshold voltage previously set for  $t_1$  to  $t_4$ . The result is a mirrored power-down sequence.

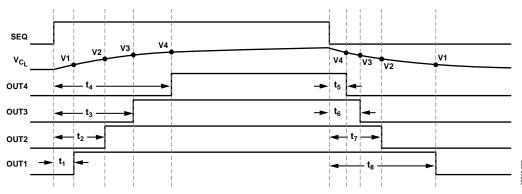


Figure 36. Mirrored Voltage Sequencer Timing Diagram

The timing diagram for the mirrored voltage sequencer is shown in Figure 36.

Equation 18 through Equation 21 must account for the additional resistance,  $R_{MIRROR}$ , in the calculations of the voltage thresholds. To calculate these new thresholds, see Equation 28 through Equation 31.

$$V1 = V_{REF} \left( 1 - e^{\frac{-t_l}{\left(R_{PULL-UP} + R_{MIRROR}\right)C_L}} \right)$$
(28)

$$V2 = V_{REF} \left( 1 - e^{\frac{-t_2}{\left(R_{PULL-UP} + R_{MIRROR}\right)C_L}} \right)$$
(29)

$$V3 = V_{REF} \left( 1 - e^{\frac{-t_3}{(R_{PULL-UP} + R_{MIRROR})C_L}} \right)$$
(30)

$$V4 = V_{REF} \left( 1 - e^{\frac{-t_4}{(R_{PULL-UP} + R_{MIRROR})C_L}} \right)$$
(31)

R<sub>MIRROR</sub> provides the mirrored delay by prolonging the discharge time of the capacitor. The mirrored voltage sequencer uses the same threshold in Equation 28 to Equation 31 in a decreasing order. To calculate the exact value of the mirrored delay time, see Equation 32 through Equation 35.

$$t_{5} = -R_{MIRROR}C_{L}\ln\left(\frac{V4}{V_{REF}}\right)$$
(32)

$$t_6 = -R_{MIRROR}C_L \ln\left(\frac{V3}{V_{REF}}\right)$$
(33)

$$t_7 = -R_{MIRROR}C_L \ln\left(\frac{V2}{V_{REF}}\right)$$
(34)

$$t_{8} = -R_{MIRROR}C_{L}\ln\left(\frac{V1}{V_{REF}}\right)$$
(35)

## **MIRRORED VOLTAGE SEQUENCER EXAMPLE**

To illustrate operation of the mirrored voltage sequencer, see Figure 33 and then consider a system that uses a V<sub>REF</sub> of 1 V and requires a delay of 50 ms when SEQ changes from low to high impedance, and between each regulator when turning on. These considerations require a rise time of at least 200 ms for the pull-up resistor (R<sub>PULL-UP</sub>) and the load capacitor (C<sub>L</sub>). The sum of the resistance of R<sub>MIRROR</sub> and R<sub>PULL-UP</sub> must be large enough to charge the capacitor longer than the minimum required delay. For a symmetrical mirrored power-down sequence, the value of R<sub>MIRROR</sub> must be much larger than R<sub>PULL-UP</sub>. A 10 k $\Omega$  R<sub>PULL-UP</sub> value limits the pull-down current to 100  $\mu$ A while giving a reasonable value for R<sub>MIRROR</sub>. A typical 1  $\mu$ F capacitor together with a 150 k $\Omega$  R<sub>MIRROR</sub> value gives a value of

$$t_{MAX} = 2.2((160 \times 10^3) \times (1 \times 10^{-6})) = 351 \text{ ms}$$
 (36)

The threshold voltage required by each comparator is set by Equation 28 to Equation 31. For example,

$$VI = V_{REF} \left( 1 - e^{\frac{-50 \times 10^{-3}}{160 \times 10^3 \times 1 \times 10^{-6}}} \right)$$

where *V1* = 268.38 mV.

Therefore, V2 = 464.74 mV, V3 = 608.39 mV, and V4 = 713.5 mV.

Next, consider 10  $\mu$ A as the maximum current (I<sub>DIV</sub>) flowing through the resistor divider network. This current gives the total resistance of the divider network (R<sub>DIV</sub>) and the individual resistor values using Equation 22 to Equation 27, resulting in the following:

• 
$$R_{DIV} = 100 \text{ k}\Omega$$

•  $R1 = 26.84 \text{ k}\Omega \approx 26.7 \text{ k}\Omega$ 

- $R2 = 19.64 \text{ k}\Omega \approx 19.6 \text{ k}\Omega$
- $R3 = 14.37 \text{ k}\Omega \approx 14.3 \text{ k}\Omega$
- $R4 = 10.51 \text{ k}\Omega \approx 10.5 \text{ k}\Omega$
- $R5 = 28.65 \text{ k}\Omega \approx 28.7 \text{ k}\Omega$

Resistor values from the calculation are nonindustry standard, using industry standard resistor values result in a new  $R_{DIV}$  value of 99.8 k $\Omega$ . Due to the discrepancy of the calculated resistor value to the industry standard value, the threshold of each comparator also changes. Calculate the new threshold values by using a simple voltage divider formula:

$$V1 = V_{REF}R1/R_{DIV}$$
(37)  
where V1 =  $\frac{1 V(26.7 k\Omega)}{99.8 k\Omega} = 267.54 mV.$ 

Therefore, V2 = 463.93 mV, V3 = 607.21 mV, and V4 = 712.42 mV.

Because the threshold of each comparator has changed, the time when each comparator changes its output has also changed. Calculate the new delay values for each comparator by using the following equation:

$$t_{I} = -C_{L} \left( R_{PULL-UP} + R_{MIRROR} \right) \ln \left( 1 - \frac{VI}{V_{REF}} \right)$$
(38)

where  $t_i = -1 \ \mu F(10 \ \text{k}\Omega + 150 \ \text{k}\Omega) \ln \left( 1 - \frac{267.54 \ \text{mV}}{1} \right) = 49.81 \ \text{ms}.$ 

Therefore,  $t_2 = 99.78 \text{ ms}$ ,  $t_3 = 149.52 \text{ ms}$ , and  $t_4 = 199.4 \text{ ms}$ .

To calculate t<sub>5</sub> through t<sub>8</sub>, use Equation 32 to Equation 35:

$$t_{5} = -R_{MIRROR}C_{L}\ln\left(\frac{V4}{V_{REF}}\right)$$

where  $t_5 = -150 \text{ k}\Omega \times 1 \mu\text{F} \times \ln\left(\frac{712.42 \text{ mV}}{1}\right) = 50.86 \text{ ms}.$ 

Therefore,  $t_6 = 74.83 \text{ ms}$ ,  $t_7 = 115.2 \text{ ms}$ , and  $t_8 = 197.78 \text{ ms}$ .

# THRESHOLD AND TIMEOUT PROGRAMMABLE VOLTAGE SUPERVISOR

Figure 37 shows a circuit configuration for a programmable threshold and timeout circuit. The timeout,  $t_{RESET}$ , defines the duration that the input voltage  $(V_{IN})$  must be kept above the threshold voltage to toggle the RESET signal, preventing the device from operating when  $V_{IN}$  is not stable. If  $V_{IN}$  falls below the threshold voltage, the RESET signal toggles quickly.

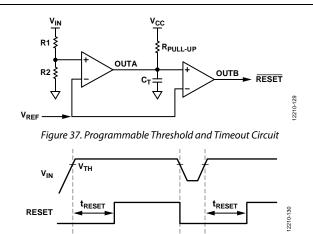


Figure 38. Threshold and Timeout Programmable Voltage Supervisor Timing Diagram

During startup, the ADCMP395 guarantees a low output state when  $V_{CC}$  is still below the UVLO threshold, preventing the voltage supervisor from toggling.

When  $V_{IN}$  reaches the threshold set by the resistor divider (R1 and R2) and  $V_{REF}$ , OUT1 changes from low to high and starts to charge the timeout capacitor ( $C_T$ ). If  $V_{IN}$  is kept above the threshold voltage and the voltage in  $C_T$  reaches  $V_{REF}$ , OUT2 toggles. If  $V_{IN}$  falls below the threshold voltage while  $C_T$  is charging, the timeout capacitor quickly discharges, preventing OUT2 from toggling while  $V_{IN}$  is not stable.

In the condition that  $V_{IN}$  is tied to  $V_{CC}$ , the circuit operates when  $V_{CC}$  is more than the minimum operating voltage.

The threshold voltage ( $V_{TH}$ ) is configured by changing the resistor divider or  $V_{REF}$ . Calculate the threshold voltage by

$$V_{TH} = V_{REF} \left( 1 + \frac{RI}{R2} \right)$$
(39)

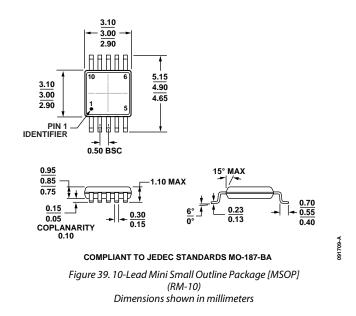
Timeout is adjusted by changing the values of the pull-up resistor or the timeout capacitor. To set the timeout value, determine the allowable current flowing through R<sub>PULL-UP</sub> and I<sub>PULL-UP</sub>. When I<sub>PULL-UP</sub> is known, calculate R<sub>PULL-UP</sub> and C<sub>T</sub> by the following formulas:

$$R_{PULL-UP} = V_{CC}/I_{PULL-UP}$$
(40)

$$C_{T} = \frac{-t_{RESET}}{R_{PULL-UP} ln \left(1 - \frac{V_{REF}}{V_{CC}}\right)}$$
(41)

# ADCMP395

# **OUTLINE DIMENSIONS**



## **ORDERING GUIDE**

Model <sup>1</sup> Temperature Range		Package Description	Package Option	Branding
ADCMP395ARMZ	-40°C to +125°C	10-Lead Mini Small Outline Package [MSOP]	RM-10	LQ4
ADCMP395ARMZ-RL7	-40°C to +125°C	10-Lead Mini Small Outline Package [MSOP]	RM-10	LQ4

 $^{1}$  Z = RoHS Compliant Part.



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