

## PWM 3-PHASE DC BRUSHLESS MOTOR CONTROL IC

### □ GENERAL DESCRIPTION

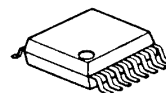
The NJM2626 is a 3-phase DC brush less motor control pre-driver IC with PWM control.

It takes hall IC inputs and generates motor driving waveform.

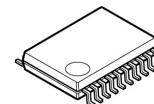
Output pre-driver is optimized to work with external power MOS transistors for better power handling.

The NJM2626 can easily implement 3-phase DC motor application with speed control feature.

### □ Package Outline



**NJM2626V**



**NJM2626VC3**

- Operating Voltage V<sub>cc</sub>= 6V to 26V
- Pre-driver circuit
  - Lower arm: I<sub>out</sub>=+30mA/-30mA TYP.
  - Upper arm: I<sub>out</sub>=30mA TYP.
- Current limit sensing voltage Current limit=0.5V±10%
- Internal Oscillator
  - Frequency control by external capacitor
- Forward or Reverse direction Internal pull-up resistor 10kΩ
- Internal Soft Start
  - External capacitor to V<sub>err</sub> pin
- Internal ON/OFF Circuit
  - No-output is V<sub>err</sub> pin to GND
- Bipolar Technology
- Package Outline SSOP-16/ SSOP20-C3

# NJM2626

## □ ABSOLUTE MAXIMUM RATINGS

(Ta=25°C)

PARAMETER	SYMBOL	RATINGS		UNIT
Logic Supply Voltage	$V_{CC}$	28		V
Maximum Output Current	$I_{O_{MAX}}$	40		mA
Power Dissipation (SSOP-16)	$P_D$	Without Board	300	mW
		(*1) Mounted on the 2 layered PCB	640	
Power Dissipation (SSOP20-C3)	$P_D$	(*1) Mounted on the 2 layered PCB	1000	mW
		(*1) Mounted on the 4 layered PCB	1500	
Operating Temperature Range	$T_{opr}$	-40 ~ +85		°C
Storage Temperature range	$T_{stg}$	-50 ~ +150		°C

(\*1): Mounted on the glass epoxy board based on EIA/JEDEC. (114.3x76.2x1.6mm: 2Layer/4Layer)

## □ ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub>=12V, C<sub>t</sub>=1000pF, C<sub>ref</sub>=1μF, T<sub>a</sub>=25°C)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
□ General						
Operation Supply Voltage	V <sub>CC</sub>	-	6.0	-	26.0	V
Under Voltage Sense Voltage	UVLO	Output Enable V <sub>CC</sub> Decreasing	4.5	5.0	5.5	V
Hysteresis Voltage (Under Voltage Lock Out)	ΔUVLO	-	0.35	0.45	0.55	V
Supply Current	I <sub>CC</sub>	R <sub>L</sub> =∞	-	12.0	18.0	mA
□ Reference Voltage Section						
Reference Voltage Output	V <sub>ref</sub>	I <sub>ref</sub> =1.0mA	3.6	4.0	4.4	V
Line Regulation	ΔV <sub>ref_LI</sub>	V <sub>CC</sub> =6V ~ 18V	-	50	100	mV
Load Regulation	ΔV <sub>ref_LO</sub>	I <sub>ref</sub> =1.0mA ~ 20.0mA	-	10	50	mV
□ Hall Amplifier Section						
Input H Level Voltage	V <sub>hH</sub>	-	V <sub>CC</sub> -0.8	-	-	V
Input L Level Voltage	V <sub>hL</sub>	-	-	-	0.8	V
Input Bias Voltage	I <sub>ho</sub>	V <sub>in</sub> =0.8V	-	-	-400	nA
Pull-up Resistance	R <sub>PUH</sub>	V <sub>in</sub> =0.8V	7	10	13	kΩ
□ Output Section						
Under Arm Output Voltage 1	V <sub>OH(D)</sub>	I <sub>source</sub> =30mA	10	10.3	-	V
Under Arm Output Voltage 2	V <sub>OL(D)</sub>	I <sub>sink</sub> =30mA	-	0.5	1.0	V
Output Clamp Voltage	V <sub>CL(D)</sub>	V <sub>CC</sub> =26V	-	18	20	V
Upper Arm Output Voltage	V <sub>OL(U)</sub>	I <sub>sink</sub> =30mA	-	0.5	1.0	V
Output Leak Current	I <sub>OLEAK</sub>	-	-	-	1.0	μA
□ Over Current Sense Section						
Sense Voltage	V <sub>TH</sub>	-	0.45	0.50	0.55	V
Hysteresis Voltage	V <sub>THhys</sub>	-	-	0.1	-	V
Input Voltage Ratio	V <sub>IN</sub>	-	-	-	3.0	V
Input Bias Current	I <sub>IB</sub>	V <sub>IN</sub> =0V	-	-0.9	-5.0	μA
□ Oscillator Section						
Oscillation Frequency	f <sub>osc</sub>	-	22	27	33	kHz
Supply Voltage Change Ratio	Δf <sub>osc</sub> /ΔV	V <sub>CC</sub> =6V ~ 18V	-	1	5	%
PWM0% Sense Voltage	PWM0	PWM DUTY=0%	-	-	0.35	V
PWM100% Sense Voltage	PWM1	PWM DUTY=100%	3.5	-	-	V
Saw Wave Peak Voltage	V <sub>p</sub> fosc	-	2.4	2.8	3.2	V
Saw Wave Bottom Voltage	V <sub>b</sub> fosc	-	0.75	0.9	1.05	V

# NJM2626

## □ ELECTRICAL CHARACTERISTICS

( $V_{CC}=12V$ ,  $C_t=1000pF$ ,  $C_{ref}=1\mu F$ ,  $T_a=25^\circ C$ )

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
□ Error Amplifier Section						
Input Offset Voltage	$V_{IO}$	-	-	7	-	mV
Input Bias Current	$I_{IBRR}$	-	-	-46	-	nA
Input Common Mode Voltage Range	$V_{ICMRR}$	-	0	-	Vref	V
□ Forward/ Reverse Direction Section (FR input terminal)						
Output Forward Direction	$V_F$	-	Vref-0.8	-	Vref	V
Output Reverse Direction	$V_R$	-	-	-	0.8	V
Hysteresis Voltage Ratio	$\Delta V_{FR}$	-	-	0.5	-	V
Pull-Up Resistance	$R_{PU_{FR}}$	-	7	10	13	k $\Omega$

Note: Output switch test are performed under pulsed conditions to minimize power dissipation.

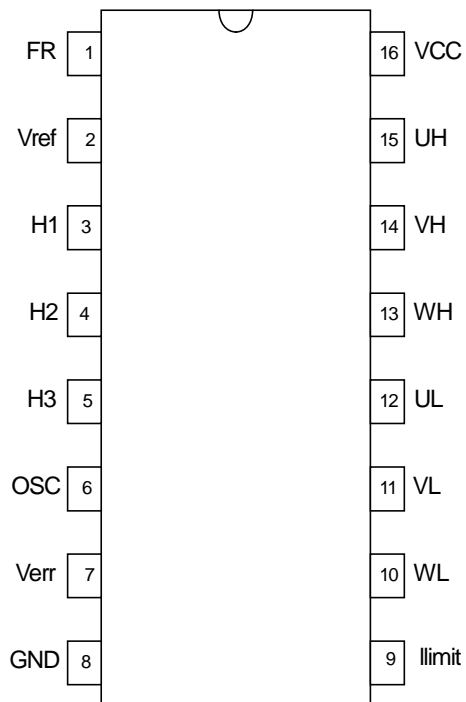
## ■ HALL INPUT vs HALL OUTPUT TRUTH TABLE

FR=L			FR=H			H:Source, L:Sink, X:Hi-Z					
H1	H2	H3	H1	H2	H3	UH	VH	WH	UL	VL	WL
H	L	H	L	H	L	X	L	X	H	L	L
H	L	L	L	H	H	X	X	L	H	L	L
H	H	L	L	L	H	X	X	L	L	H	L
L	H	L	H	L	H	L	X	X	L	H	L
L	H	H	H	L	L	L	X	X	L	L	H
L	L	H	H	H	L	X	L	X	L	L	H

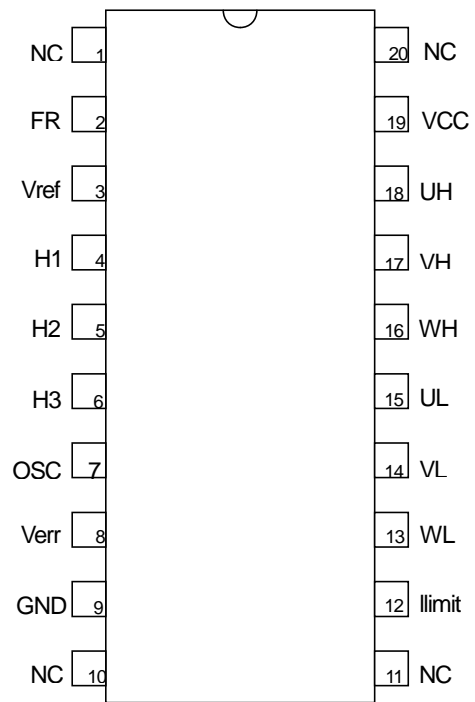
## ■ FR INPUT TERMINAL

Terminal Voltage	Direction
L input	F
H input	R

## □ PIN CONFIGURATION



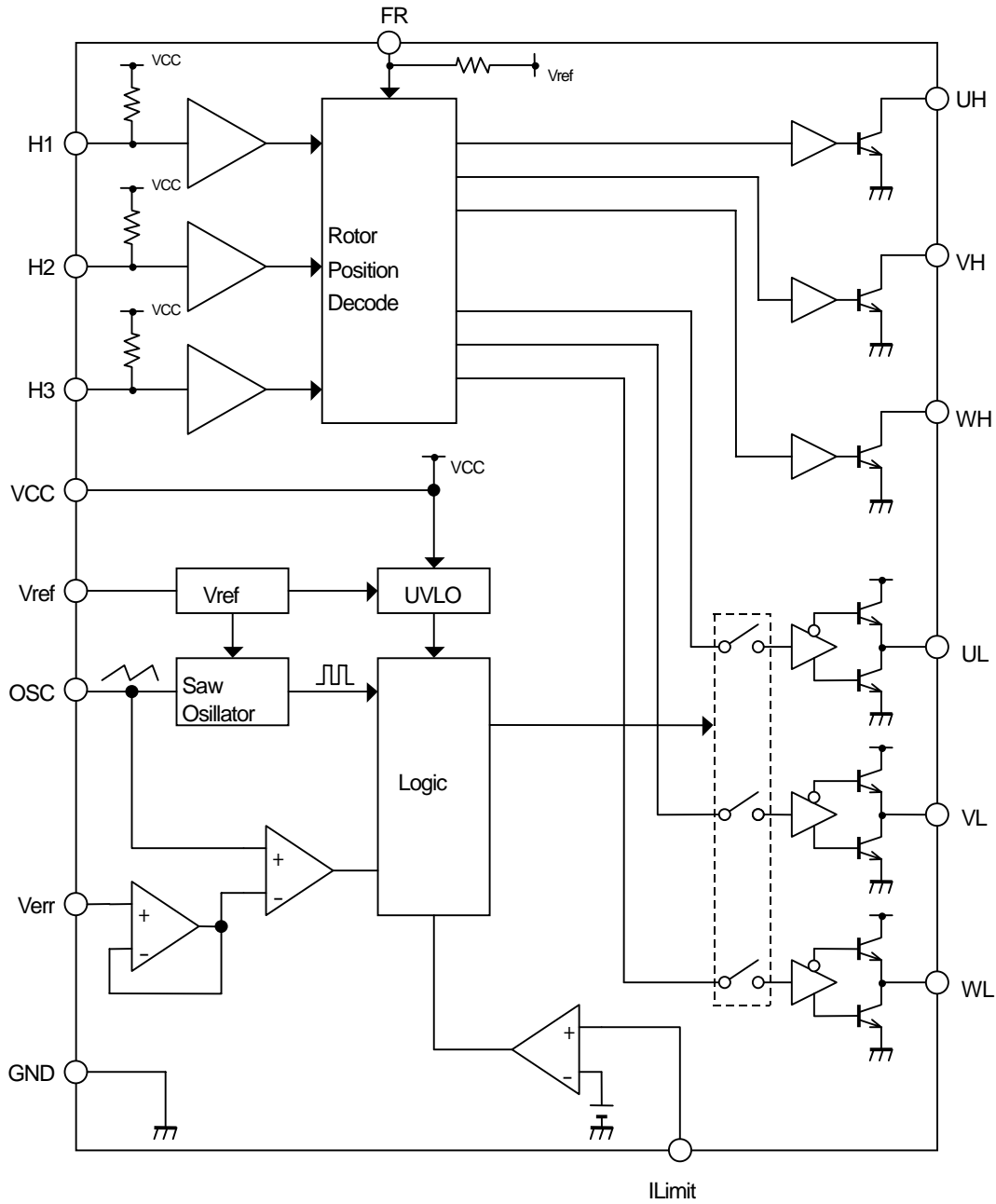
SSOP-16



SSOP20-C3

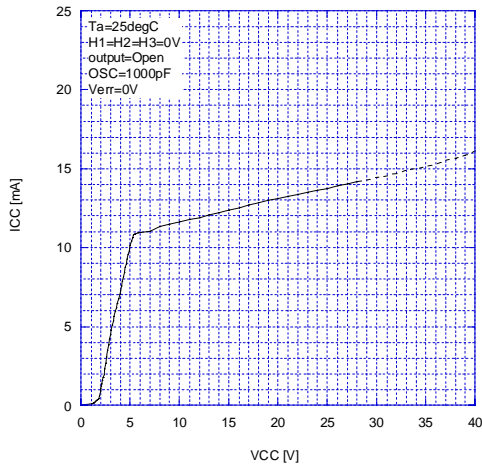
# NJM2626

## □ BLOCK DIAGRAM

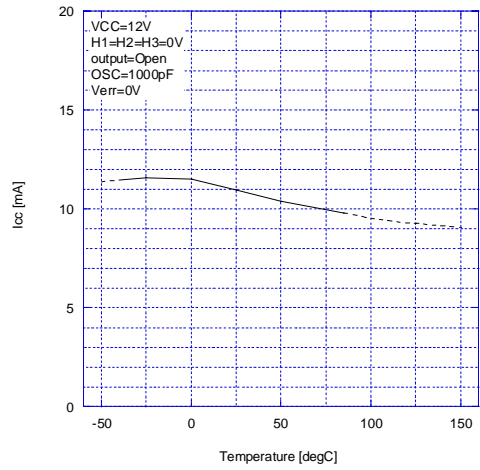


## TYPICAL CHARACTERISTICS

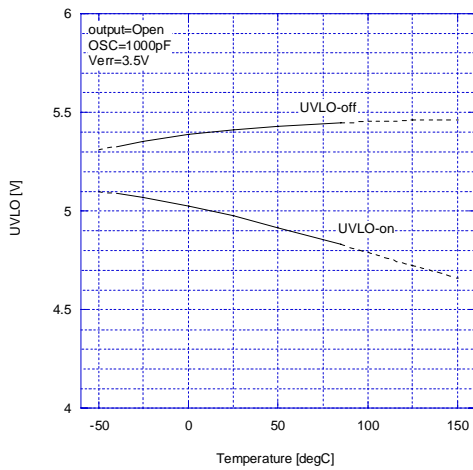
ICC vs. VCC



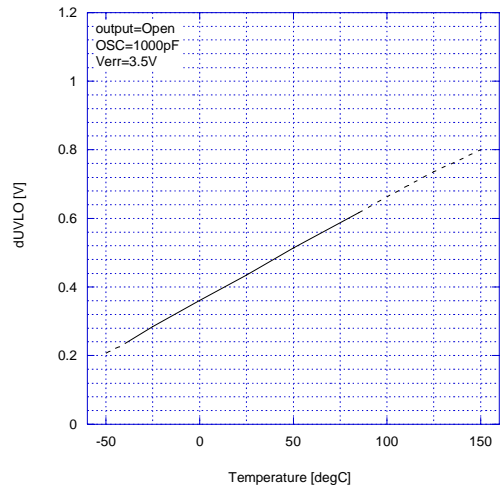
ICC vs. Temperature



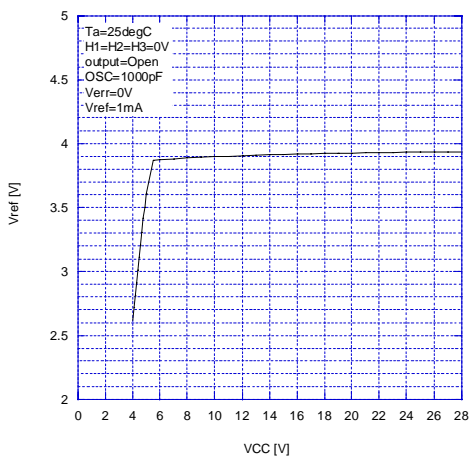
UVLO vs. Temperature



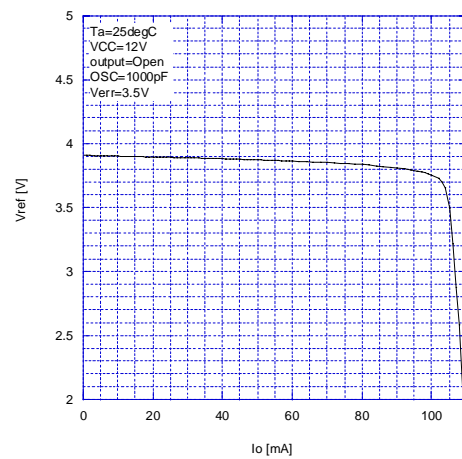
dUVLO vs. Temperature



Vref vs. VCC

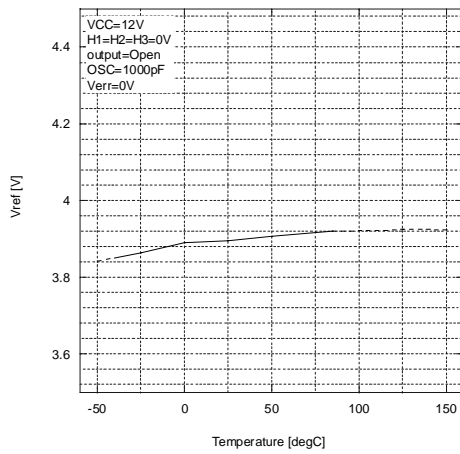


Vref vs. Io

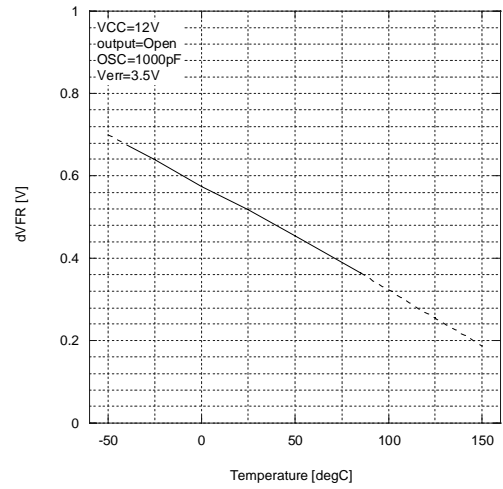


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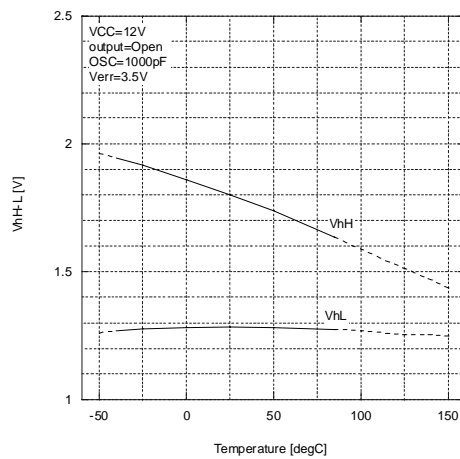
Vref vs. Temperature



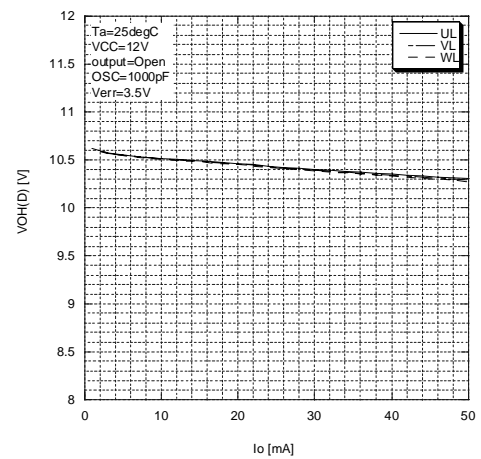
dVFR vs. Temperature



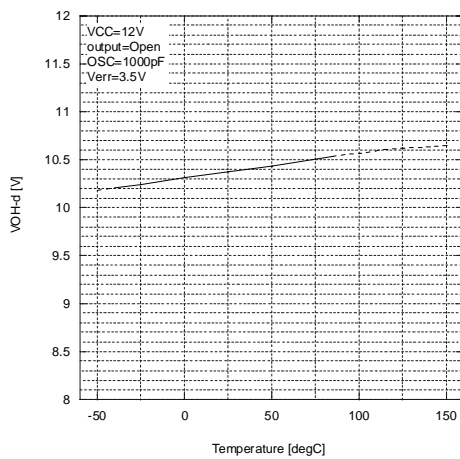
VhH-L vs. Temperature



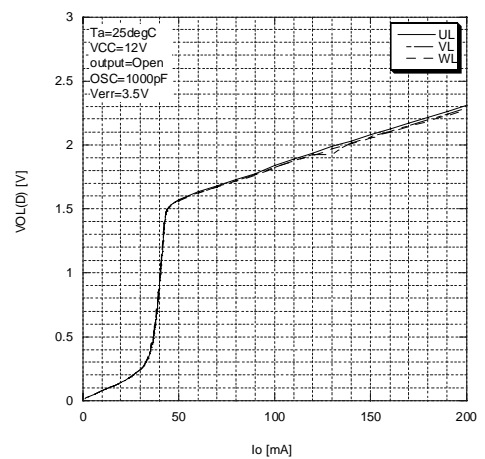
VOH(D) vs. Io



VOH-d vs. Temperature



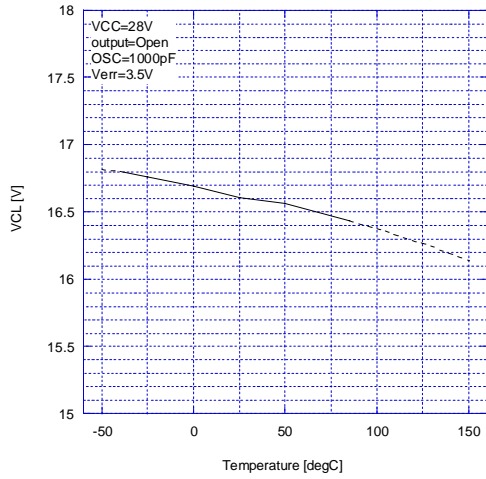
VOL(D) vs. Io



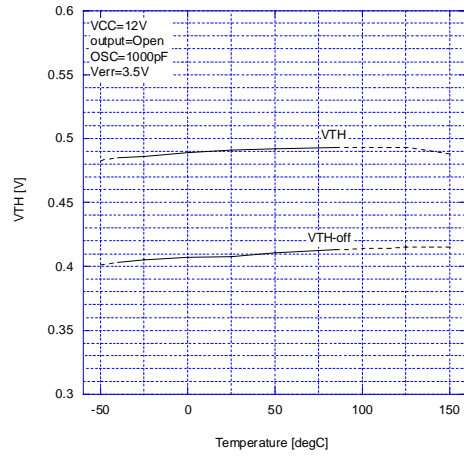


## TYPICAL CHARACTERISTICS

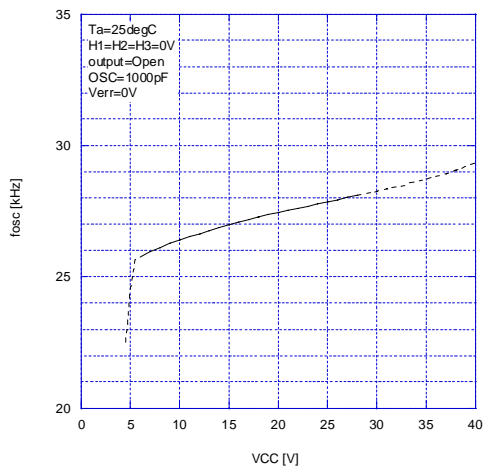
VCL vs. Temperature



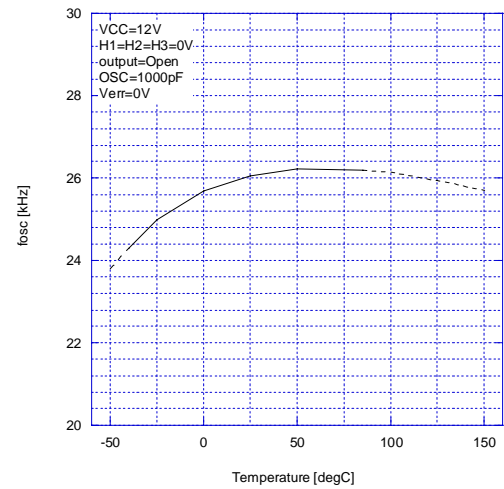
VTH vs. Temperature



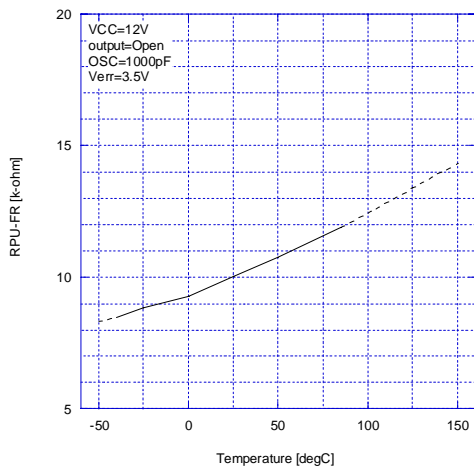
fosc vs. VCC



fosc vs. Temperature



RPU-FR vs. Temperature



**[CAUTION]**

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