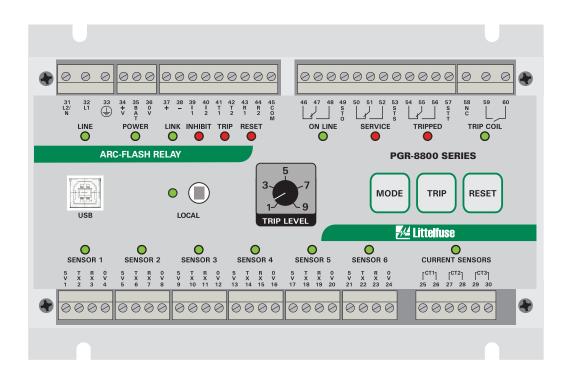


Arc-Flash Relay PGR-8800

PGR-8800

ARC-FLASH RELAY

REVISION 3-A-112913



Document Number: PM-1400-EN



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Littelfuse



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1 INTRODUCTION

The PGR-8800 Arc-Flash Relay is a high-speed, arc-detection device for electrical powerdistribution systems. The PGR-8800 has one local sensor and supports both point and fiber-optic sensor technologies for optical arc detection. There are inputs for six optical sensors and three current sensors.

On the occurrence of an arc fault, the PGR-8800 detects the fault and pulses the trip contact in less than one millisecond. The tripping pulse is typically used to trip the circuit breaker(s) supplying the circuit. The total arcing time is effectively reduced to the mechanical opening time of the circuit breaker; typically between 30 and 75 milliseconds. The trip contact is a solid-state switch (IGBT), which provides fast reaction and sufficient drive capability for circuit-breaker trip circuits.

Using optical sensors rather than relying strictly on current measurement allows a much faster detection time than overcurrent relays or a circuit breaker alone can typically provide. This will lower the incident energy of an arc flash and increase worker safety, reduce fault damage, and improve uptime. Since the incident energy is decreased, the hazard risk category (HRC) and associated level of personal protective equipment (PPE) may also be lowered, subject to an arc-flash study modeling the system parameters.

The MODBUS RTU protocol is implemented in the PGR-8800. This will provide status information for sensors, analog inputs, digital inputs, digital outputs, and numerous event and error flags. It also provides the ability to remotely reset the PGR-8800. See Section 11.3 and Appendices A and B.

The PGR-8800 can be used on any electrical system with any voltage (ac or dc) and can be powered from either an ac or dc supply, or both. If it is powered from line supply, it can charge a backup battery to power the PGR-8800 when the line supply is lost.

1.1 Current-Supervised Arc-Flash Protection

The PGR-8800 has three phase-current inputs which can be used to prevent optical trips when the measured current is below a user-specified level. This makes it possible to avoid nuisance tripping from external light sources such as lightning or welding arcs.

1.2 Definite-Time Overcurrent Protection

Using the phase-current inputs, the PGR-8800 can be configured to trip on overcurrent, with a minimum reaction time of one millisecond. There are two user-adjustable levels of overcurrent protection with independent trip times to coordinate with other protective devices. This provides protection from long-lasting overload conditions and fast reaction to overcurrent even when no arc is detected.

1.3 Fail-Safe Operation

The PGR-8800 continuously monitors its internal circuitry as well as the connected optical sensors. Any system faults, including a sensor-cable fault, are indicated by a flashing LED and can be logged. A redundant trip circuit ensures that the PGR-8800 will trip on an arc flash even if a primary trip-circuit component fails. The solid-state design of the redundant trip circuit also provides a significantly faster response to an arc on power-up (for example, after maintenance during a shutdown) than is possible with microprocessor-only relays.

1.4 Fast-Fault Location

The optical sensors used with the PGR-8800 include LED indication of health and, if it has detected an arc flash, of fault location. The PGR-8800 also has one LED per optical sensor to indicate which sensor(s) have caused a trip.



1.5 USB Interface

A USB interface on the front of the PGR-8800 provides easy PC access to configuration settings and access to an event log which provides detailed diagnostic information about measurements before and after a trip. No PC driver or software installation is required.

1.6 Scalable System

Up to four PGR-8800 modules can be connected into a single system, allowing a total of 24 optical sensors per system.

1.7 Upstream Circuit Breaker Tripping

The PGR-8800 can be configured to trip an upstream circuit breaker as a backup to local circuitbreaker failure. Circuit-breaker failure can be detected with a discrete input (such as a local circuit breaker feedback signal), current measurement, or the Link function. See Appendix C for more information.

2 INSTALLATION

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The PGR-8800 can be surface mounted using four 5-mm (10-32) screws, or it can be DIN-rail mounted using the optional mounting brackets (PGA-0031).

Ensure there is enough clearance around the module to allow the plug-in terminals to be removed and inserted.

Do not install modules which have been damaged in transport.

See the PGR-8800 Arc-Flash Relay Application Guide for additional installation information.

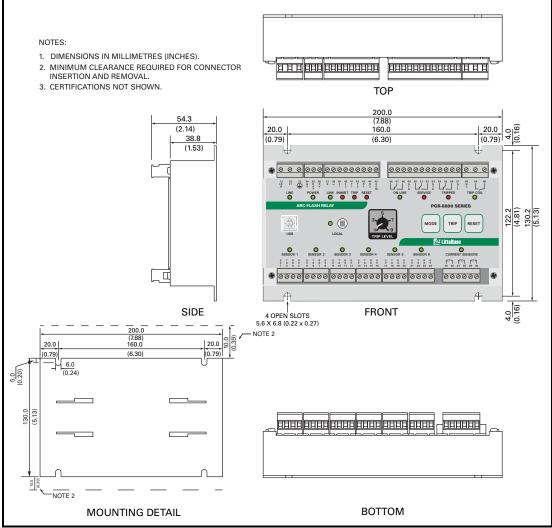
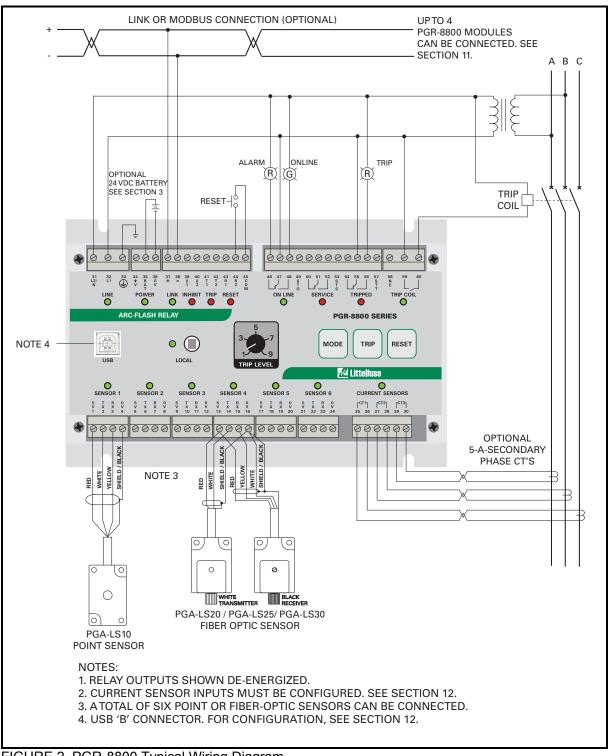


FIGURE 1. PGR-8800 Outline and Mounting Details.









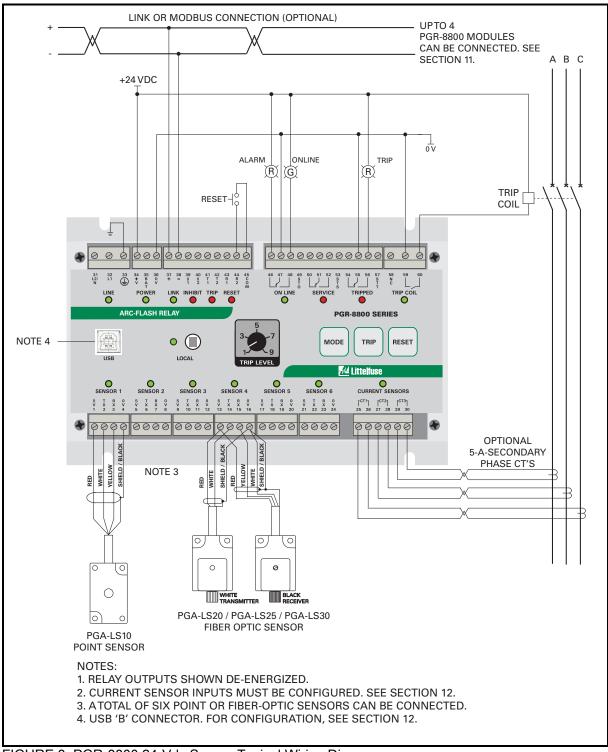


FIGURE 3. PGR-8800 24-Vdc Source Typical Wiring Diagram.

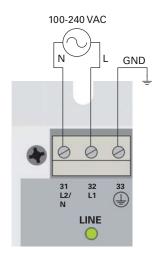


3 POWER SUPPLY

The PGR-8800 Arc-Flash Relay can be supplied by a single ac or a single dc source – not both.

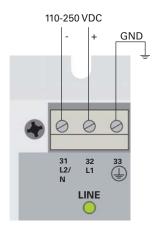
3.1 AC Supply

Connect an ac supply to terminals 31 and 32. The supply voltage must be 100 to 240 Vac.



3.2 DC Supply

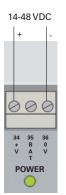
Connect a dc supply to terminals 31 and 32, ensuring correct polarity. The supply voltage must be 110 to 250 Vdc.





3.3 Low-Voltage DC Supply

Connect a dc supply to terminals 34 and 36, ensuring correct polarity. The supply voltage must be 14 to 48 Vdc. This input will not charge the backup battery.

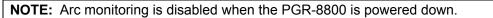


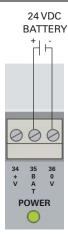
3.4 External 24-V Battery Backup

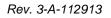
Connect a 24-Vdc battery to terminals 35 and 36, ensuring correct polarity. The PGR-8800 will only charge the battery when there is rated voltage on power-supply terminals 31 and 32 (ac or dc). The PGR-8800 supplies a constant-current, constant-voltage (CCCV) of 27 V with no load and maximum available current of 200 mA. A sealed lead-acid battery with a capacity between 2 and 15 Ah, such as a pair of Panasonic VRLA LC-R122R2P, should be used and exchanged regularly according to the manufacturer's recommendations.

If the PGR-8800 is supplied by the backup battery and the battery voltage drops below 20 V, the PGR-8800 will shut down to protect the battery.

Do not combine external battery backup and the low-voltage DC supply. The DC supply will not charge the battery.







4

Littelfuse

OPTICAL SENSORS

The PGR-8800 has one local sensor and six inputs for external optical sensors. The local sensor is primarily used for commissioning and can also be enabled for arc-flash protection. Its light-detection zone is illustrated in the diagram below.

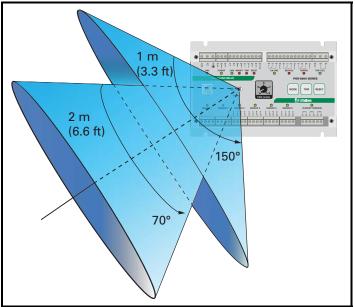


FIGURE 4. Local Sensor Detection Zone for a 3 kA Fault.

Two external sensor types are supported:

- PGA-LS10 Photoelectric Point Sensors with sensor check
- PGA-LS20, PGA-LS25, and PGA-LS30 Fiber-Optic Sensors with sensor check

The sensors can be used together, in any combination.

Both sensor types have LED indication of sensor health and fault location. A sensor-check circuit tests the sensor to verify that the sensor assembly is functioning correctly. A healthy sensor will indicate two fast flashes of its internal red LED every few seconds. A sensor that has detected an arc will slowly flash red.

The sensors connect to the PGR-8800 with shielded three-wire 20 AWG (0.5 mm^2) electrical cable. Each sensor includes 10 m (33 ft) of cable which can be shortened or extended up to 50 m (164 ft). These cables should be considered to be at ground potential when determining electrical clearances in the cabinet.

Any connected optical sensor with circuit check will be automatically detected and cause the PGR-8800 to report an error if it is subsequently disconnected.

PGA-LS10

PGA-LS20 / PGA-LS25 / PGA-LS30





4.1 PGA-LS10 Photoelectric Point Sensor with Sensor Check

Littelfuse

This sensor has a detection area of a 2-m (7 ft) half-sphere for arcs of 3 kA or more.

A built-in LED enables the PGR-8800 to verify the function of the light sensor, wiring, and electronics. If the sensor does not detect the sensor-check LED, a sensor-fail alarm will occur -- the ONLINE output will change state and the ONLINE LED will begin to short flash. See Section 9.

The sensor includes 10 m (33 ft) of shielded three-wire electrical cable which can easily be shortened or extended to a maximum of 50 m (164 ft). Use Belden 85240 or equivalent cable (wire colors may vary).

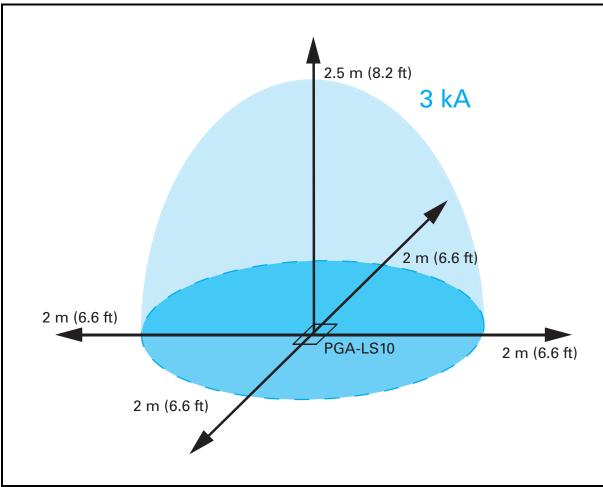


FIGURE 5. PGA-LS10 Detection Range for a 3 kA Fault.



4.1.1 PGA-LS10 Connection

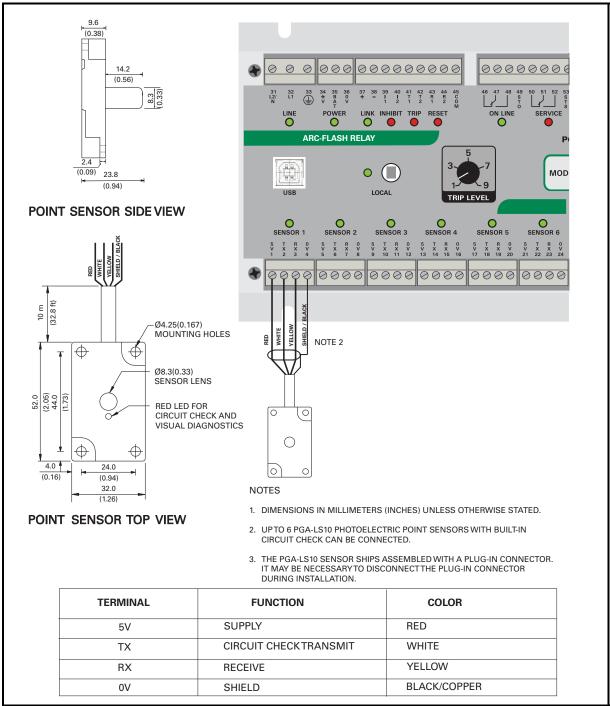


FIGURE 6. PGA-LS10 Connection Diagram.





4.1.2 PGA-LS10 Installation

Point sensors include an adhesive-backed drill template for easy surface or panel-mount installation.

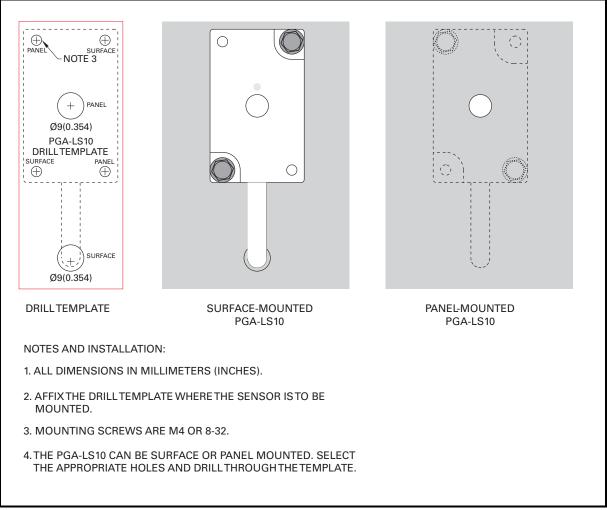


FIGURE 7. PGA-LS10 Mounting Detail.



4.2 PGA-LS20, PGA-LS25 and PGA-LS30 Fiber-Optic Sensors with Sensor Check

The PGA-LS20, PGA-LS25, and PGA-LS30 have a 360° detection zone along the fiber's length. A built-in LED enables the PGR-8800 to verify the function of the light sensor, wiring, and electronics. If the sensor does not detect the sensor-check LED, a sensor-fail alarm will occur -- the ONLINE output will change state and the ONLINE LED will begin to short flash. See Section 9.

The PGA-LS20, PGA-LS25, and PGA-LS30 sensor have three components:

- A fiber-optic cable, with one end covered with a black sleeve. The PGA-LS20 has 8 m (26 ft) of active fiber and 2 m (7 ft) of covered fiber. The PGA-LS25 has 5 m (16 ft) of active fiber and 3 m (10 ft) of covered fiber. The PGA-LS30 has 18 m (59 ft) of active fiber and 2 m (7 ft) of covered fiber.
- 2. A transmitter with a white enclosure and a white thumb nut.
- 3. A receiver with a white enclosure, a black thumb nut, and an adjustment screw behind an access hole.

Both the receiver and the transmitter connect to one PGR-8800 input using shielded three-wire electrical cable. All three components are monitored to ensure correct operation.

4.2.1 Fiber Connection

The fiber is the light-collecting element of the PGA-LS20, PGA-LS25, and PGA-LS30. It must be installed so it has line-of-sight to all current-carrying parts. In some cases this may be accomplished by following the bus bars along the back wall of the cabinets.

Drill holes using the included drill template and fasten the transmitter and receiver to the cabinet walls using rivets or screws. Connect the attached cables to the PGR-8800. The wires of the transmitter and receiver must be connected as shown in Fig. 8.

Connect the black-sleeve-covered end to the receiver using the black thumb nut, and the white uncovered end to the transmitter using the white thumb nut. Ensure the fiber is inserted completely into the transmitter and receiver and the nuts are tightened. Pull gently on the cable to verify a secure connection. The maximum pull strength of the fiber is 30 N (6.7 lb_f).

The fiber should not be sharply bent or pinched. The minimum bending radius is 5 cm (2"). Ensure that any drilled holes are free of any sharp edges or burrs. Use grommets for further protection.

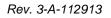
4.2.2 Receiver Wiring Connections

Connect the red wire to 5V. Connect the yellow wire to RX. Connect the white wire **and** the shield to 0V.

4.2.3 Transmitter Wiring Connections

Connect the red wire to 5V. Connect the white wire to TX. Connect the shield to 0V.

The yellow wire is not used.



4.2.4 PGA-LS20, PGA-LS25, and PGA-LS30 Connection

Littelfuse

The sensor is shipped with the wires mounted in a terminal block. See Fig 8.

The transmitter and receiver include 10 m (33 ft) of shielded three-wire electrical cable which can be shortened or extended up to 50 m (164 ft). Transmitter and receiver cables can be different lengths and must be independently shielded. Use Belden 85240 or equivalent cable (wire colors may vary). Failure to independently shield transmitter and receiver cables can lead to an incorrect circuit check – a faulty sensor could be falsely detected as continuous. However, if there is no sensor fault, arc-flash detection will function normally in this condition.

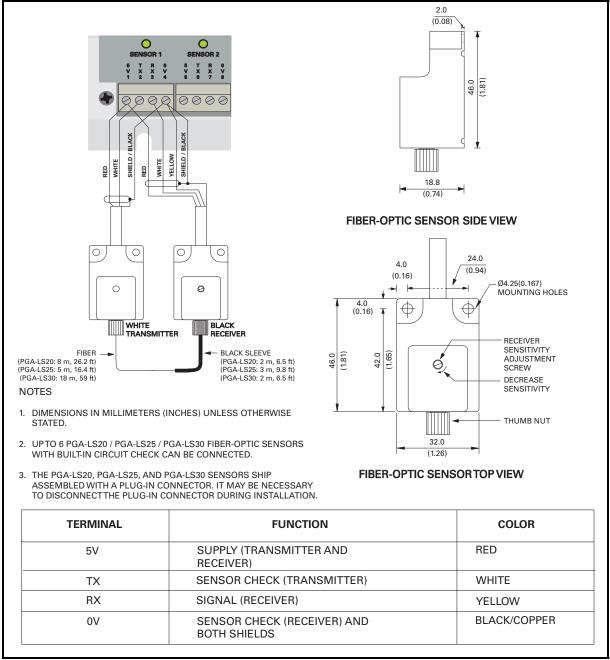


FIGURE 8. PGA-LS20, PGA-LS25, and PGA-LS30 Connection Diagram.



5 SENSOR PLACEMENT

5.1 General Guidelines

Optical sensors require line-of-sight to points being monitored. Ensure that the point sensors and fiber are not blocked by fixed or moveable objects. Areas that will be accessed for maintenance or with moveable parts (such as draw-out circuit breakers) should be considered a high priority for installation. Do not place sensors or cables on bare components that will be energized and avoid sharp bends in the cable, particularly when using the PGA-LS20, PGA-LS25, and PGA-LS30 fiber-optic sensors. The electrical cables and sensors should be considered to be at ground potential when determining electrical clearances.

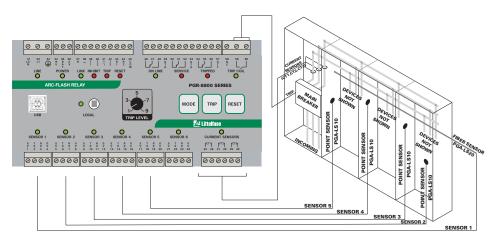
Sensors should be mounted in a location that will minimize the chance of debris or dust build-up and with easy access for maintenance if needed. A point sensor mounted at the top of an enclosure and facing down is optimal for reducing dust build-up. It should be noted that most enclosures are metallic and the reflectivity combined with the high intensity of an arc mean that even a dirty sensor will collect adequate light.

Sensors can be tested individually by putting the PGR-8800 into service mode by pressing the MODE button and shining a bright light on the sensor. A trip will be indicated if the sensor detects the light, but a trip signal will not be sent to the circuit breaker. If the LED on the sensor or relay isn't indicating a trip, cleaning is necessary. Note that in service mode, the PGR-8800 will not trip if an arc flash occurs. Remember to return the PGR-8800 to online mode after testing is completed. In dusty environments, sensor cleaning should be part of a regular maintenance schedule and can be performed using compressed air or a dry cloth.

5.2 Switchgear Protection

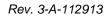
The sensors used for arc-flash detection are optical sensors. Line-of-sight between the points where an arc could occur and the sensor is crucial.

Often one point sensor is sufficient to monitor a complete switchgear compartment. However, if there are large components such as circuit breakers that cast shadows over wider areas, more than one point sensor is required.



5.3 Transformer Protection

The PGR-8800 can also be used for the protection of transformers. Two or more point sensors should be used per transformer to monitor the primary and secondary connection terminals. For the placement of the sensors, the same considerations apply as for switchgear protection.





6 CURRENT SENSORS

The PGR-8800 has three phase-current inputs which can be configured in a current-supervised trip inhibit mode and for overcurrent protection.

The current inhibit mode prevents the module from tripping on a light signal, unless the current is above a threshold. This can prevent nuisance tripping e.g. photo flashes or welding in the area.

The overcurrent protection provides a fast, but less accurate ANSI 50 overcurrent protection function.

The current-sensor inputs can also be used to verify that the local circuit breaker has tripped successfully, providing an ANSI 50BF circuit breaker failure function. See Appendix C for more information.

6.1 Current Inhibit Mode

If the current-supervised trip inhibit mode is enabled, the PGR-8800 will only trip when the following conditions apply:

- An arc is detected by an optical sensor, and
- Current detected by a current sensor exceeds the inhibit threshold.

The PGR-8800 will trip after the programmed delay time for the light as soon as the absolute value of the current on any phase exceeds the inhibit setting. Thus, the current inhibit does not add any delay to the trip if the arc is drawing current.

6.2 Overcurrent Protection

In addition, two definite-time overcurrent protection levels are provided that will trip on current detection alone. Overcurrent levels can be set from 150 to 1,000% of rated nominal load current. Overcurrent protection is not active by default, and must be set using the configuration software.

Overcurrent trip times can be set between 1 and 20,000 milliseconds. The trip decision is based on an internal counter. The PGR-8800 will increment the counter if a sample exceeds the trip-level setting and decrement it when a sample is below the setting. When the counter exceeds the number of samples necessary to exceed the time delay, the PGR-8800 will trip. The time for the trip coil IGBT (insulated-gate bipolar transistor) to operate is approximately 0.2 milliseconds, which happens after the time delay.

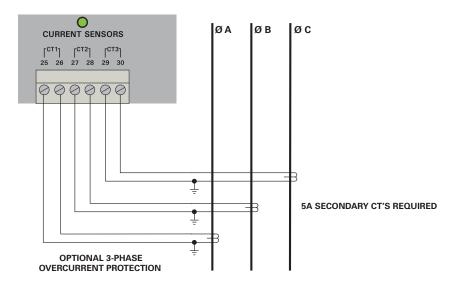
NOTE: Using overcurrent trip on a system with fewer than three phase current sensors can significantly increase trip times and levels. This does not apply to the inhibit system, which will function at no added delay, also in single phase systems.



6.3 Current Sensor Characteristics

The current-sensor inputs require 5-A-secondary current sensors. Three phase-current sensors are required for optimal performance. For best performance, select current sensors with a primary rating approximately equal to the system's rated current and protection class 10P5 or better. The current sensors can be placed in series with other equipment as long as the total burden of the wiring and inputs are within the current sensor rating.

The PGR-8800 measures instantaneous currents and is insensitive to phasing and polarity. The current-sensor inputs have a burden of less than 0.25 VA at 5 A, will withstand up to 75 A for one second, and are isolated from all other terminals up to 500 Vac.





7 DIGITAL INPUTS

The PGR-8800 has three digital-input functions; trip inhibit, trip and reset. Each function has two inputs to simplify wiring.

By default, the inputs are considered active when connected to COM (terminal 45). The inputs can also be configured to be active when not connected to terminal 45 and to use circuit check in the configuration software. See Section 12.2.7.

7.1 Inhibit

The INHIBIT function suppresses a trip signal.

There are two INHIBIT inputs: terminals 39 and 40.

When inhibit is activated, the PGR-8800 will indicate that an arc fault is being detected, but will not pulse the trip-coil output. If the PGR-8800 detects an arc fault while inhibited, the sensor LED and INHIBIT LED will flash.

Inhibit can also block a digital-input if so configured. See Section 12.2.7. The INHIBIT input is enabled by default.

7.2 Trip

The TRIP input is used to remotely trip the PGR-8800. Once activated, the PGR-8800 will pulse the TRIP COIL output instantaneously.

There are two TRIP inputs: terminals 41 and 42.

In SERVICE mode, this input does not affect the TRIP COIL output.

The TRIP input can also be configured to connect to the auxiliary contact of a circuit breaker to verify that the circuit breaker has tripped successfully. See Appendix C.

The TRIP input is enabled by default.

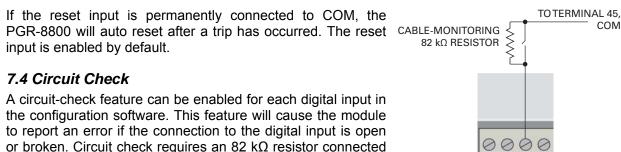
7.3 Reset

The RESET input is used as a remote reset after a fault has been detected.

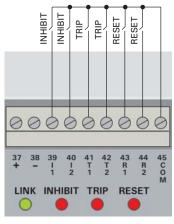
There are two RESET inputs: terminals 43 and 44.

in parallel with the external contact. This resistor must be connected as close as possible to the contact to ensure the

Activating this input will reset an alarm or error, clear the TRIPPED and TRIP COIL outputs, clear the indicators, and place the unit back in service or online mode, depending on the mode it was operating in prior to the trip.



full-length of the cable is protected.



LINK INHIBIT



OUTPUTS 8

An LED provides visual indication of each output The output contacts are shown on the status. faceplate in the powered-off state.

8.1 Online

The ONLINE output consists of two contact sets:

- A change-over (Form C) contact (terminals 46-48)
- A normally-open status contact, STO (terminal 49) with reference to COM (terminal 45)

45 C 0 M

The ONLINE output is energized unless the PGR-8800:

- detects an optical sensor fault,
- detects a cable fault on a digital input if cable monitoring is activated in the configuration software.
- detects loss of trip coil supply voltage,
- loses supply voltage, or
- is in service mode

8.2 Service

The SERVICE output consists of two contact sets:

- A change-over (Form C) contact (terminals 50-52)
- A normally-open status contact STS (terminal 53) with reference to COM (terminal 45)

The SERVICE output signals that the PGR-8800 is being commissioned or set up. The output is energized when the PGR-8800:

- is in service mode, or
- is connected via USB to a PC

The SERVICE output can also be configured to trip an upstream device after a local circuit-breaker failure or to follow the Trip Coil output. See Appendix C.

8.3 Tripped

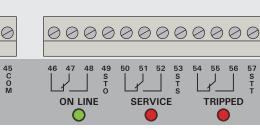
The TRIPPED output consists of two contact sets:

- A change-over (Form C) contact (terminals 54-56)
- A normally-open status contact STT (terminal 57) with reference to COM (terminal 45)

NOTE: The TRIPPED output is used for signalling a trip condition to a remote monitoring system or to trip an upstream circuit breaker. It is not intended to trip the local circuit breaker due to the slower response time of a mechanical relay.

In default configuration, the TRIPPED output will energize if the PGR-8800 detects a fault during regular operation or in service mode.

The TRIPPED output can also be configured to trip an upstream device (with a delay of approximately five milliseconds) after a local circuit-breaker failure, or to follow the TRIP COIL output. See Appendix C.





8.4 Trip Coil

Use the TRIP COIL output to trip a shunt or undervoltage circuit breaker. The operating mode is programmable using the PGR-8800 configuration software. See Section 12.2.8.

The TRIP COIL output can be used for trip coils with a 24 to 300 Vac/Vdc supply voltage. The output is monitored to verify that there is voltage available to the tripping circuit. If voltage is not detected, the ONLINE output will change state and its LED will flash green.

The TRIP COIL output is a pulsed output when in shunt trip mode. When an arc flash is detected, the TRIP COIL output is activated in less than one millisecond. When overcurrent protection is enabled and an overcurrent is detected, the TRIP COIL output is activated after an adjustable delay. The TRIP COIL output is deactivated after the adjustable pulse period delay. The output is an IGBT that can carry 10 A ac or dc for five seconds.

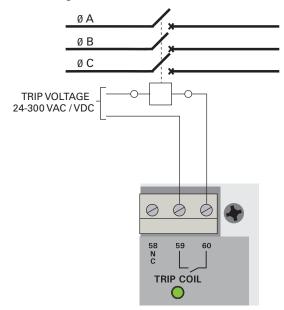
The TRIP COIL output is isolated up to 1,000 Vac.

NOTE: The TRIP COIL output is an IGBT switch. There is a voltage drop of 2-4 V across the TRIP COIL output when energized. See Section 14.

The TRIP COIL output consists of a rectifier bridge and an IGBT. The IGBT is able to switch large currents and high voltages. In combination, this creates a very fast relay-like switch which is able to trip even large circuit breakers without the added delay of a mechanical relay.

NOTE: The TRIP COIL output functions as a momentary switch and is protected against thermal overload. It will gradually lower the time the trip coil is active if the PGR-8800 is tripped repeatedly.

By default, when the PGR-8800 is in service mode, the TRIP COIL output will not operate when an arc-flash or overcurrent trip occurs, but it will operate when the TRIP button is pressed for at least one second. The TRIP COIL output can also be programmed to trip while in service mode using the configuration software.





9

LINE

Off

Off

LINK

Off

LED INDICATION FAST FLASHING ON On, green Supply voltage is connected OFF Supply voltage is not connected 100 ms 200 ms 1 s POWER SLOW FLASHING On, green PGR-8800 is running from a supply other than battery ON PGR-8800 is running from the Slow green flashing OFF 1200 ms 400 ms 800 ms Battery input. The PGR-8800 will shut down at 20 V to protect SHORT FLASHING the battery from damage Short green flashing PGR-8800 is charging a battery ON 1500 ms PGR-8800 is not powered OFF 100 ms 1600 ms 2 s FIGURE 9. LED Flash Patterns. On, green Link mode is enabled and active Network traffic indication Green flashing (intermittent) Slow red flashing A relay in the system is tripping. If the trip is locally inhibited, the Link LED will revert to green when the trip source is removed Short red flashing Link mode is enabled but not all relays are being detected Link mode is disabled INHIBIT On. red INHIBIT input is active or current sensing is inhibiting trips (current not above setting) Fast red flashing The PGR-8800 detects an arc (light), but the INHIBIT input or current sensing is preventing a trip Short red flashing Digital-input circuit check failed; check the wiring of the inputs, or use the configuration software to disable circuit check

Off INHIBIT input is inactive

TRIP

On, red TRIP input or another trip source is active

- Fast red flashing TRIP input is causing a trip
- Slow red flashing Last trip was caused by this input or by the TRIP button on the front panel. Press RESET in Online mode to clear the trip
- Short red flashing Digital-input circuit check failed; check the wiring of the inputs, or use the configuration software to disable circuit check
- Off TRIP input is inactive



| RESET | |
|----------------------|--|
| On, red | RESET input or another reset source is active |
| Short red flashing | Digital-input circuit check failed; check the wiring of the inputs, or use the configuration software to disable circuit check |
| Off | RESET input is inactive |
| ONLINE | |
| On, green | PGR-8800 is online, active and operational; the TRIP COIL output will pulse if trip conditions are met |
| Short green flashing | PGR-8800 has detected an error. The front-panel LED's will provide error information. The TRIP COIL output will still operate if trip conditions are met |
| Off | PGR-8800 is off or in service mode |
| SERVICE | |
| On, red | PGR-8800 is in service mode. Please note it will switch to and stay in service mode if a USB cable and PC are connected. In service mode, the TRIP COIL output can be activated from the front-panel TRIP button but not by an arc fault, overcurrent, or TRIP input, unless configured to trip in service mode. See Section 12.2.8. |
| | Press and hold RESET to configure the sensors. See Section 13.1. |
| Short red flashing | PGR-8800 is in service mode, and has detected an error. The front-panel LED's will provide error information |
| Slow red flashing | PGR-8800 is in the process of auto set up or firmware update |
| Off | PGR-8800 is off or in online mode |
| TRIPPED | |
| On, red | The TRIP COIL output is or has been active or was prevented from activating while in service mode. Press RESET to clear the trip |
| Off | No unacknowledged trips |
| TRIP COIL | |
| On, green | TRIP COIL output is ready and detects trip voltage of 5 V or more in shunt mode |
| Fast red flashing | TRIP COIL output is activated due to an existing trip event and is currently pulsing the output |
| Slow red flashing | TRIP COIL output has been activated and has completed the pulsed output. Press RESET to clear the trip |
| Short red flashing | TRIP COIL output is blocking less than 5 V. The trip voltage is missing; check the wiring and the power supply to the trip coil |

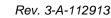


| LOCAL | |
|---------------------|--|
| On, green | Online mode. The front-panel sensor is configured for use as a trip sensor |
| | The LED may also indicate that the PGR-8800 is powering up if it is the only lit LED. If this condition remains for an extended period, it indicates unit error |
| Slow green flashing | If the SERVICE LED is also flashing, the PGR-8800 is awaiting manual confirmation of the connected sensors. See Section 13.1 |
| Fast green flashing | The internal supervisor or a USB host is reading or writing to internal memory, or the light detected on the front sensor is close to trip level |
| SENSORS | |
| On, green | SENSOR input is active and has a connected sensor |
| Fast green flashing | Sensor is currently detecting more than 50% of the light level needed to trip. The level at which this occurs is programmable. This is a warning only. If this warning is active during normal condition, it may indicate that the system Trip Level is set too low, which could lead to unintentional tripping |
| Slow red flashing | Sensor caused a trip event. Press RESET to clear the trip |
| Short red flashing | Sensor check of the sensor failed; check the wiring and, if using a PGA-LS20, PGA-LS25, or PGA-LS30 ensure the small metal adjustment screw is not set to minimum sensitivity. See Section 13. |
| Off | SENSOR input is inactive |

CURRENT SENSORS

| On, green | Current sensors are activated and configured | | |
|--|---|--|--|
| On, red | Current is above the inhibit level | | |
| Fast green flashing | Current sensors are detecting more than 50% of the current level needed to trip. The level at which this occurs is programmable. This is a warning only. If this warning is active during normal condition, it may indicate that the system Trip Level is set too low, which could lead to unintentional tripping | | |
| Fast red flashing | Current sensor is causing a trip event | | |
| Slow red flashing | The PGR-8800 has tripped on overcurrent. Press RESET in online mode to clear the trip | | |
| Off | Current sensors are inactive | | |
| PGA LS10, PGA-LS20, PGA-LS25, PGA-LS30 | | | |
| Short red flashing | Sensor is operating normally. Double flashes occur every few seconds. | | |

- Slow red flashing Sensor has detected an arc
- Off Sensor inactive





10 PGR-8800 BUTTONS

10.1 Mode

The MODE button switches the PGR-8800 between online and service mode.

10.2 Trip

In service mode, when the TRIP button is pressed for more than one second, the TRIP COIL output is activated. In online mode, the TRIP button is disabled.

10.3 Reset

In online mode, press the RESET button to clear a trip (if trip conditions are no longer present). In service mode, when the RESET button is pressed for more than one second, the optical sensor detection process will begin. See Section 13.1.

10.4 Mode + Reset

When MODE and RESET are pressed for more than 20 seconds, a file system reset will occur. This will erase the logged information.

10.5 Mode + Trip

When MODE and TRIP are pressed for more than 20 seconds, a reset of all configuration settings to factory defaults will occur. This will not clear the logged information on the file system.



11 LINK

The PGR-8800 Link function allows up to four PGR-8800 modules to be connected to form a single system. This enables the PGR-8800 to share sensor inputs and relay outputs as if they were one unit. The maximum link cable length is 10 m (33 ft).

It is necessary to configure the Link function before use. See Section 12.2.9.

11.1 Configuration

Set the Link interface, address, and number of connected modules with the configuration software.

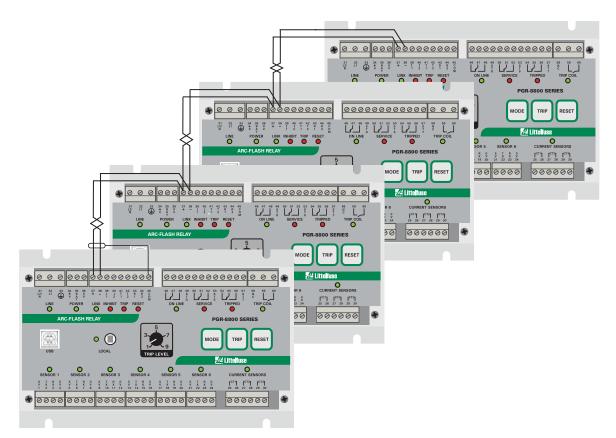
Each PGR-8800 must have a unique link address, starting from one for the module connected to the local circuit breaker.

The PGR-8800 Link function continuously monitors link-cable-break faults.

11.2 Button Function

When a PGR-8800 is configured for the Link function, the front buttons can be shared with all modules in the system or set to apply only to the local module. For example, if one PGR-8800 is set to service mode and Link user interface is enabled, all the linked modules will be placed in service mode. This also applies to the RESET button.

The TRIP button is only applied locally. If the TRIP button is pressed in service mode, only the local module will trip.

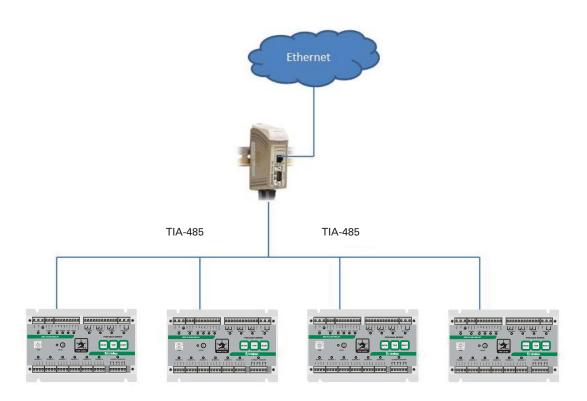


When connecting modules using the Link interface, connect terminals 37 and 38 as shown using Belden 3105A cable, or equivalent.



11.3 Modbus Communication

The MODBUS[®] RTU protocol is implemented in the PGR-8800, and allows up to four modules to be connected using a 2-wire TIA-485 bus. The PGR-8800 can also be connected to a local HMI or SCADA system. This will provide status information for sensors, analog inputs, digital inputs, digital outputs, and numerous event and error flags. It also provides the ability to remotely reset the PGR-8800. A converter for TIA-485 to Ethernet, IEC-61850, or other network type can be used for remote network connections and many other communications options.



Set the Modbus interface and address with the configuration software. Each PGR-8800 must have a unique Modbus address. See Section 12.2.9 and Appendices A and B.

| Terminal | Description | Signal | Connection |
|----------|-------------|-----------|-----------------------------|
| 37 | В + | TIA-485 B | B signal of the TIA-485 bus |
| 38 | A - | TIA-485 A | A signal of the TIA-485 bus |

The 2-wire multi-drop TIA-485 bus requires common terminals to be connected (terminals 37 to 37, 38 to 38). The maximum cable length is 10 m (33 ft) and must be shielded twisted pair. Use Belden 3105A cable, or equivalent.



12 USB INTERFACE

The PGR-8800 contains configuration software, data logs, and event records that can be accessed through the USB Interface. No drivers or software installation is required to access configuration or data. Use a USB A-B cable as shown below to connect the PGR-8800 to a computer.



The PC application for configuring the PGR-8800 is pre-installed on the internal Configuration drive. When the PGR-8800 is connected to a PC, the Configuration drive (wrench icon) and the Log drive (notepad icon) will appear in the file manager as shown in Section 12.1.

This makes it possible to automate configuration if several relays with the same configuration are needed. Contact Littelfuse for more information.

NOTE: The configuration and log-viewer applications are HTML Applications (HTA). HTA is a proprietary Microsoft[™] technology and is only supported by Internet Explorer 5.0 or later on Microsoft Windows systems. Once configured, the data log file can be accessed on any platform.

12.1 Connecting to a PC

The PGR-8800 requires supply voltage before connecting the USB cable. Although some LED's may light when connecting a USB cable to an unpowered PGR-8800, the USB interface does not supply adequate power to allow proper operation.

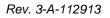
A powered PGR-8800 will enter service mode when a PC is connected with a USB cable. In service mode, arc-flash protection is inactive by default, but can be configured to trip in service mode. See Section 12.2.8. The PCR 2200 will

mode. See Section 12.2.8. The PGR-8800 will remain in service mode until the USB cable is disconnected and the MODE button is pressed to return to online mode. When connected to a PC, the PGR-8800 appears as two mass-storage devices and two drives will be displayed in the file manager. These drives are internal to the PGR-8800 and behave like any standard drive. Files can be copied to or from the drives or even dragged and dropped.

NOTE: The changes made in the configuration software will not be stored unless saved. The configuration changes will be activated when the USB cable is disconnected.

NOTE: The Log drive operates as a First-In, First-Out (FIFO) log. When the Log drive is full, the oldest entry will be removed to make room for a new event.





12.2 Configuration Software

Littelfuse

The configuration software for the PGR-8800 is located on the Configuration drive (the wrench icon). To run the software, open the Configuration drive in the PC file manager and double-click on the config.hta file. The program will open in Internet Explorer regardless of the default browser. The features of the software are outlined in subsequent sections of this manual.

For any setting or button, hovering the mouse cursor over it will display the possible values of the setting or the function of the button.

| General Optical Sensors Current Sensors | Digital Inputs Trip Output Communications Advanced Ab | oout |
|---|---|--------------------------|
| General | | |
| System Name | | |
| Description of this unit | PGR-8800 Arc-Flash Relay | <u>Undo</u> <u>Reset</u> |
| Date and Time | 2011-07-04 04:47:05 | |
| Synchronize to PC Clock | | Undo Reset |
| Save All Reset (This Tab) | Undo (This Tab) Save and Exit Exit | |

12.2.1 Configuration Software Tabs

The configuration software is displayed in a window with eight tabs along the top of the screen. Click on a tab to display the relevant configuration options.

| General | Set the date, time, and a general description of the relay. |
|------------------------|--|
| Optical Sensors | Configure optical sensors and arc-detection time before tripping. |
| Current Sensors | Set overcurrent and current-supervised arc-flash protection parameters. |
| Digital Inputs | Configure or disable the operation of the digital inputs. |
| Trip Output | Define the behaviour and pulse time of the Trip Coil output. |
| Communications | Link multiple PGR-8800 relays together into a single system or configure Modbus. |
| Advanced | Enable data logging or restore configuration and factory defaults. |
| About | View information on firmware and hardware versions. |

12.2.2 Configuration Software Buttons

ittelfuse

There are five buttons along the bottom of the configuration software window that are common to every tab.

- **Save All** Save all configuration settings made in every tab.
- **Reset (This Tab)** Reset all configuration settings in this tab to the factory default. Changes will not be stored until they are saved.
- **Undo (This Tab)** Undo any changes that have been made to the current tab since opening the configuration software.
- **Save and Exit** Save all configuration settings made in every tab and exit the configuration software.
- Exit Exit the configuration software. No changes will be saved unless the Save All button has been pressed. If the Save All button is clicked accidentally, use the Undo (This Tab) button on any tab where changes were made and then Save and Exit.

There are two buttons for each configuration setting, Undo and Reset. The Undo button will cancel any changes made to the value before the configuration software was opened. The Reset button will load the factory default for that setting.

12.2.3 Default Configuration

It is possible to use the basic protection features of the PGR-8800 without using the configuration software. Any connected optical sensors with circuit-check will be automatically detected and cause the relay to report an error if subsequently disconnected.

The initial configuration can be stored permanently without use of the configuration software by using the commissioning procedure outlined in Section 13.1. By default, the local sensor will not cause a trip on excess light.

The PGR-8800 current sensors are disabled by default; sufficient light alone will cause an arc-flash trip and overcurrent conditions will not cause a trip.

The amount of time that light must be detected to cause a trip is set at the factory to one milliseconds. The cable-check feature for the digital inputs is disabled by default, but the inputs will function if they are connected to terminal 45.

The default trip pulse time is one second.

The configuration software is required to enable data logging, Link, MODBUS, and current sensor functions.



12.2.4 General Settings

General Optical Sensors Current Sensors Digital Inputs Trip Output Communications Advanced About

| General | | | | | | |
|--|----------------------------|--------------------------|--|--|--|--|
| System Name | | | | | | |
| Description of this unit | PGR-8800 Arc-Flash Relay | Undo Reset | | | | |
| Date and Time | Date and Time | | | | | |
| Unit time when USB cable was connected | 2011-07-04 04:47:05 | | | | | |
| Synchronize to PC Clock | | <u>Undo</u> <u>Reset</u> | | | | |
| Save All Reset (This Tab) Undo (Th | is Tab) Save and Exit Exit | | | | | |

System Name

The system name can help identify the PGR-8800 (up to 25 characters) e.g. name and number of the switchboard section in which the unit is mounted.

Date and Time

This section will show the current date and time on the PGR-8800 and provides the option to synchronize with the connected PC.

12.2.5 Optical-Sensor Settings

| Optical Sensors | | |
|------------------------------------|------|------------|
| Common Settings | | |
| common setungs | | |
| Arc detection time before tripping | 1 ms | Undo Reset |

Common Settings

These settings apply to all optical sensors. The arc detection time specifies the amount of time light from an arc must be detected to cause a trip.

Valid settings are 0 to 20,000 milliseconds and the default setting is 1 millisecond. If set to zero milliseconds, the effective trip time is less than 0.8 milliseconds. If a sensor detects light approaching the trip level, the LED for that sensor will begin to flash. The threshold for the warning flashes can be set to 50%, 75% (default), or 90% of the trip-level setting.



Individual Sensor Settings

| Sensor 1 | | | |
|----------------------------|-----------------|------------|--|
| Sensor status | Sensor detected | | |
| Sensor description | Sensor 1 | Undo Reset | |
| Ignore sensor check errors | | Undo Reset | |
| Change configuration | No change | Undo Reset | |

Optical sensors are individually configurable with a 25-character description. The PGR-8800 scans all optical sensor terminals periodically for sensors.

| Sensor description | A name for the sensor (such as the switchboard section it is monitoring) to aid in troubleshooting. |
|----------------------------|---|
| Ignore sensor check errors | The PGR-8800 will not report if a sensor is removed. Check this box to disable sensor check. The corresponding sensor-check LED will still flash if connected. |
| Change configuration | Once a sensor is connected to a terminal, the PGR-8800 will report an error if it is removed. If a sensor is removed, this allows the sensor expected status to be reset. |

NOTE: Sensor status can also be reset by placing the PGR-8800 in service mode and then pressing the RESET button.

Local Sensor

| Local Sensor | | | | |
|--------------------------|--------------|------------|--|--|
| Sensor description | Local sensor | Undo Reset | | |
| Local sensor causes trip | | Undo Reset | | |

The local sensor is located on the front of the PGR-8800 and is primarily intended for commissioning of sensors. The configuration software allows a 25-character description.

The local sensor can also be used to trip the circuit breaker if the checkbox is marked.



12.2.6 Current-Sensor Settings

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| etup | | | |
|----------------------------|------|---------------------|------------|
| Rated nominal load current | 100 | A RMS on CT primary | Undo Reset |
| CT transformation ratio | 100 | A to 5 A RMS | Undo Reset |
| Current sensor mode | AC 💌 | | Undo Reset |
| Enable current inhibit | | | Undo Reset |
| rip on Overcurrent 1 | | | Undo Reset |
| rip on Overcurrent 2 | | | Undo Reset |

Setup

The current sensors can be configured for use as current-supervised trip inhibit and/or overcurrent protection.

By default, overcurrent protection and current-supervised trip inhibit are disabled. The value of the rated-current set point will not affect the operation of the PGR-8800 until one of these functions is enabled using the checkboxes.

When using current sensors, the signal being applied to the sensors (ac or dc) must be defined. The module will automatically track the zero point if AC is selected.

The rated nominal load current is the typical current level that will be observed on the current sensor primary and is the reference for the Inhibit and Overcurrent functions.

The current sensor ratio must also be defined. The PGR-8800 only accepts current sensors with a 5-A-secondary current. The accuracy of the reading is 1 A (current-sensors-secondary current). Due to the fast reaction time of the PGR-8800 to an arc flash, it is important to set all levels and time delays with this in mind.



Current-Supervised Trip Inhibit

| Enable current inhibit | | Undo Reset |
|---------------------------------------|------------------------|------------|
| Trip on Overcurrent 1 | | Undo Reset |
| Trip on Overcurrent 2 | _ | Undo Reset |
| Indicator blinks when above | 100 % of rated current | Undo Reset |
| Trip Inhibit | | |
| Inhibit function disables trips below | 50 % of rated current | Undo Reset |

The primary function of the current-sensor inputs is to provide current-supervised arc-flash protection. If light is detected by the optical sensors but the current is below the Trip Inhibit setting, the PGR-8800 will not trip. This value is adjustable from 10 to 1,000% of the rated nominal load current. This feature is disabled by default. See Section 6.

When Current Inhibit is enabled, the INHIBIT LED on the front of the PGR-8800 will be on when current is below the set point. When the current is above the set point, the INHIBIT LED will be off.

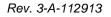
Overcurrent Protection

| Trip on Overcurrent 1 | | Undo Reset |
|---|------------------------|--|
| Trip on Overcurrent 2 | | Undo Reset |
| Indicator blinks when above | 100 % of rated current | Undo Reset |
| Overcurrent 1 Protection | | |
| Overcurrent 1 Protection | 150 % of rated current | Undo Reset |
| Overcurrent 1 Protection Trip on current above Time delay | 150 % of rated current | <u>Undo</u> <u>Reset</u> <u>Undo</u> <u>Reset</u> |

The PGR-8800 has two definite-time overcurrent set points which can be used for instantaneous, short-, and long-time overcurrent protection. This feature is disabled by default.

The current level required to trip is set as a percentage of the rated nominal load current. The overcurrent trip levels can be set from 150 to 1,000% and the time delay is adjustable from 1 to 20,000 milliseconds. See Section 6.

Overcurrent protection operates independently from arc-flash protection and the optical sensors.





12.2.7 Digital-Input Settings

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Digital Inputs | | |
|-------------------------------------|--|--------------------------|
| Inhibit Inputs | | |
| Function: | Inhibit when low (switch closed) | <u>Undo</u> <u>Reset</u> |
| Trip Inputs | | |
| Main function: | Trip input | <u>Undo</u> <u>Reset</u> |
| Function: | Trip the output when low (switch closed) | Undo Reset |
| Trip on this input can be inhibited | | Undo Reset |
| Reset Inputs | | |
| Function: | Reset when low (switch closed) | <u>Undo</u> <u>Reset</u> |
| | | |
| Save All Reset (This Tab) | Undo (This Tab) Save and Exit Exit | |

By default, the digital inputs are considered active when connected to COM (terminal 45). Using the drop-down lists, the inputs can be disabled, circuit-check can be enabled (see Section 7) and the inputs can be configured to be inactive when connected to COM (inverted).

The Trip inputs can also be inhibited if enabled. Otherwise, a Trip input is allowed to occur regardless of the Inhibit Inputs function selection.

When the PGR-8800 sends a trip signal to the local circuit breaker, the status of the circuit breaker can be monitored using the Trip input. In the case of a local circuit breaker failure, the PGR-8800 can be configured to trip an upstream circuit breaker. See Appendix C.



12.2.8 Output Settings

| General Optical Sensors Current Sensors Digital Ir | nputs Outputs Communication Advanced About | |
|--|--|--------------|
| Outputs | | |
| Trip Coil Output | | |
| Circuit breaker type | Shunt coil (trips when powered) Undo | Reset |
| Circuit breaker pulse time | 2 seconds Undo | Reset |
| Trip in Service mode | | Reset |
| Report an error if trip coil is not detected | ✓ Undo | Reset |
| Coordinated Tripping | | |
| Detect clearing failure by trip input | □ <u>Undo</u> | Reset |
| Detect clearing failure by current | | <u>Reset</u> |
| Service Output | | |
| Service output function: | Indicate Service mode Undo | <u>Reset</u> |
| Tripped Output | | |
| Tripped output function: | Indicate that the unit tripped Undo Undo | Reset |
| | | |
| Save All Reset (This Tab) Undo (Thi | s Tab) Save and Exit Exit | |

12.2.8.1 Trip Coil Output

The Trip Coil Output can be configured to operate a shunt or an undervoltage circuit breaker. In shunt mode, power is required to cause the circuit breaker to trip. Most installations will use this type of circuit breaker because the trip times are typically faster than undervoltage circuit breakers. However, the undervoltage circuit breaker has the advantage of tripping when supply voltage is lost, making it a fail-safe device.

The amount of time that supply voltage will be applied to a shunt circuit breaker or removed from an undervoltage circuit breaker is defined by the circuit-breaker pulse time and can be set from 1 to 5 s.

An external trip voltage is applied to one side of the Trip Coil output. If voltage is not present while in shunt mode, the PGR-8800 will deactivate the ONLINE output, and flash the Trip Coil red LED. This feature can be disabled by deselecting the Report an error if trip coil is not detected checkbox.

For more information on trip-coil operation, see Section 8.4.

By default, the PGR-8800 does not send a trip signal when in service mode because this mode can be used for verifying sensor operation. Service-mode tripping can be selected by the Trip in service mode checkbox. There is no indication of this setting on the front panel, so work procedures should make a note of this.



12.2.8.2 Coordinated Tripping

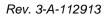
| Coordinated Tripping | | | |
|---------------------------------------|--------------------------------|---|--------------------------|
| Detect clearing failure by trip input | | | Undo Reset |
| Detect clearing failure by current | | | Undo Reset |
| Service Output | | | |
| Service output function: | Indicate Service mode | | <u>Undo</u> <u>Reset</u> |
| Tripped Output | | | |
| Tripped output function: | Indicate that the unit tripped | - | Undo Reset |

The PGR-8800 relies on the circuit breaker to extinguish an arc flash. The PGR-8800 can be programmed to trip a secondary device further upstream if the local circuit breaker fails. Circuit-breaker failure is detected by connecting the auxiliary contact to the PGR-8800 Trip input or by measuring the current using the current sensors, or both.

The Service and Tripped outputs can be configured to match the Trip Coil output or to trip an upstream circuit breaker on a clearing failure.

The Link interface can also be used for coordinated tripping by sending a trip signal via the interface when the primary circuit breaker fails.

For more on this topic, see Appendix C.





12.2.9 Communications Settings

Link Interface

| General Optical Sensors | Current Sensors | Digital Inputs | Outputs | Communication | Advanced | About | | |
|-------------------------|---------------------|------------------|------------|---------------|----------|-------|------|-------|
| Communicat | tion | | | | | | | |
| Link Interface | | | | | | | | |
| Is used for | | Noth | ning | - | | | Undo | Reset |
| NOTE: Changes to this | parameter will rebo | ot the unit to c | omplete th | e change. | | | | |
| | | | | | | | | |
| | | | | | | | | |
| Save All Reset | (This Tab) | Undo (This Tab |) (| Save and Exit | Exit | | | |

The Link input on the PGR-8800 (terminals 37, 38) is a multi-function communications port. The port is disabled by default and can be configured as follows through the Link Interface drop-down list:

| Nothing | Disable communications port. |
|---------------------|--|
| Link multiple units | Connect up to four PGR-8800 relays. |
| Modbus | Enable remote communication using the Modbus protocol. |
| Factory test | Not intended for customer use. |

Selecting each option in the drop-down list will reveal further options.



Link Configuration

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About Communication Link Interface Linking multiple units 👻 Is used for Undo Reset Link Configuration Unit address 1 Must be unique, lowest must be 1 Undo Reset Number of linked units in the system 4 Report an error if any unit is missing Trip Send Link alarm signal on -Undo Reset Received Link alarm signal trips this unit ~ Undo Reset Link sends and receives the user interface ~ Undo Reset Link sends and receives errors ~ Save All Undo (This Tab) Save and Exit Reset (This Tab) Exit

Up to four PGR-8800's can be linked in this mode, but each must be given a unique Unit address and the total Number of linked units in the system must be configured in all linked units.

The PGR-8800 can be programmed to send an alarm signal over the link interface:

| Never | The PGR-8800 will receive alarm signals but not send them. |
|-----------------------|--|
| Light above threshold | An alarm signal will be sent when light is above the trip level regardless of the local inhibit status. |
| Trip | An alarm signal will only be sent when all local conditions such as light level and inhibit are satisfied. |
| Clearing failure | The PGR-8800 will send an alarm signal when the local circuit breaker does not trip. |

Received Link alarm signal trips this unit

If selected, this option will allow the module to receive a Link alarm sent from another unit, and will trip the module.

Link sends and receives the user interface

This option will allow the module to send and receive button presses. Pressing RESET on one module will reset all link-enabled modules with this option selected. Modules will also change mode together. This does not influence the Trip and Inhibit terminal inputs.

Link sends and receives errors

This option shares errors such as sensor-check failure or no voltage on the TRIP COIL to all the linked units. As a result, an error on one module will change the online mode on all link-enabled modules.

The PGR-8800 can be configured to share light-sensor information. Although a current-inhibited PGR-8800 detecting excess light will not trip, it will trip a remote PGR-8800 that is not inhibited by sharing light intensity. See Section 11 for more information on linking multiple units.



Modbus Configuration

| Link Interface Is used for | MODBUS | Undo Reset |
|--------------------------------------|---|------------|
| NOTE: Changes to this parameter will | reboot the unit to complete the change. | |
| MODBUS Configuration | | |
| | | Undo Reset |
| | | |
| Baud rate | 19200 - | Undo Reset |
| Parity | Even 💌 | Undo Reset |
| Allow writes via MODBUS | V | Undo Reset |

The Modbus device address, baud rate, and parity must be configured on the device with the Configuration Software.

Default configuration

| Device address | 1 |
|--|-------|
| Baudrate | 19200 |
| Parity | Even |
| Number of start bits | 8 |
| Number of stop bits (controlled by parity selection) | |
| Even Parity | 1 |
| Odd Parity | 1 |
| None | 2 |
| | |

Allow writes via MODBUS is disabled by default.

Network Termination

Since the PGR-8800 Modbus interface shares the Link interface, the network is already terminated internally. This limits the number of units which can be connected, and the maximum length of the connection. See Section 11.3.

See Appendices A and B for the Modbus Protocol description and database table.



12.2.10 Advanced Settings

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Advanced | | |
|---|---------------------------------------|------------|
| Logging | | |
| Enable data logging | | Undo Reset |
| Enable waveform capture (beta) | | Undo Reset |
| NOTE: Data logging requires an uninterrupted po | ower supply (such as battery backup). | |
| Internal Drives | | |
| Reset configuration drive to factory default | | Undo Reset |
| Reset log drive to factory default | | Undo Reset |
| Configuration | | |
| Reset configuration to factory defaults | | Undo Reset |
| | | |
| Save All Reset (This Tab) Undo | (This Tab) Save and Exit Exit | |

Logging

The data logging feature is disabled by default. A preliminary version of a waveform capture feature can also be enabled but this feature is still in a testing stage and is not considered complete. If the PGR-8800 will be connected in an application where tripping results in a loss of supply power, use of a backup battery supply is required when using data logging. Power supply failure while writing to the log drive can lead to loss of data. See Section 12.3.

Internal Drives & Configuration

In addition to the hardware reset procedures outlined in Section 10, the configuration software allows for partial reset of certain modules and configuration. Every parameter can be individually reset by using the Reset button associated with it (see Section 12.2.2).

Resetting the configuration drive will retain all settings but any files stored on the drive will be lost. Resetting the log drive will result in a loss of any logged events and stored data on the log drive.

By using the Reset configuration to factory defaults checkbox, all configuration settings can be restored to their default values.



12.2.11 About Tab

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

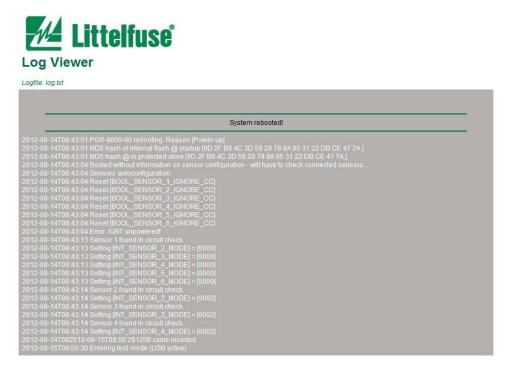
| onfiguration save | ad at 2012 00 15 07 | | | |
|---|----------------------|--------|--|--|
| | eu al 2012-00-10 01. | :47:42 | | |
| roduct type: PGI | | | | |
| a shift and the second s | ion: 01.03.05 (2012- | 08-07) | | |
| roduct HW Vers | | | | |
| W serial number | r: 441979 | | | |

The About tab displays general information about the PGR-8800 such as the last time the configuration was saved, the firmware revision number, hardware revision number, and serial number.

12.3 Data Log Drive

The PGR-8800 can log all significant events including trips, errors and button presses. By default, data logging is disabled. See Section 12.2.10.

Once enabled, the raw data is logged in a plain text file on the log drive. This file can be viewed in any text editor or in the included log.hta log reader. Log.hta requires Internet Explorer 5.0 or greater and displays the data log in a simplified format.





13 COMMISSIONING

Even without configuration, the PGR-8800 will work using the factory default settings. See Section 12.2.3. It will always trip if a sensor input exceeds the Trip Level setting, even if the circuit check is falsely reporting a cable to be broken. However, we recommend doing a few simple tests on the sensors to ensure that problems on the sensors or cabling will be detected and reported.

The PGR-8800 will detect sensors on power up and report if they disappear, but in most installations it is advantageous to store the sensor configuration permanently. This is easily done by configuring the installed sensors either via USB as shown above or with the method described below.

13.1 Configuration of Installed Sensors

1. Press MODE to switch to service mode (SERVICE LED will be solid red).

2. Press and hold RESET for a few seconds to start the test sequence.

3. The LED's for sensors 1-6 will flash for 10 seconds while the system tests the optical sensors. This clears the sensor configuration¹.

4. Move a light source of at least 100 lumen (e.g. 300 W halogen lamp) towards the local sensor until the LOCAL LED turns off. When using fiber sensors, a photo flash with a guide number of 15 m (49 ft) or larger can be used. See Section 15 for ordering information.

5. Observe that all connected sensor LED's are flashing. Move the light source towards each sensor until its internal LED turns off. This should happen at approximately the same distance at which was used before the local sensor reacted. The PGR-8800 LED associated with the sensor will change to solid green at the same time.

6. Return to the central unit and confirm that all LED's for connected sensors are showing a solid green LED. Illuminate the local sensor again to store the results.

7. The system will now flash green on all sensors briefly, store the results in non-volatile memory, and return to service mode. Sensor errors that may occur when the supply voltage is cycled can now be detected.

8. Press MODE to switch back to online mode. The sensors are now configured and the system will alarm if a sensor malfunctions.

13.2 Testing the Sensors

1. Press MODE to switch to service mode (SERVICE LED will be solid red).

2. Confirm that there is a solid PGR-8800 green LED for each connected optical sensor. This confirms that sensors are connected and healthy.

3. Confirm that a short red flashing light occurs periodically in each sensor. This indicates that the sensor circuit is being checked.

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¹ If something is not functioning properly during the test, it can be cancelled by pressing RESET at any time. Reverting back to the previous configuration requires a power cycle of the unit.



4. Point a light source at a sensor and check that the LED on the sensor and the unit begin to flash red continuously. On the first sensor tested, the TRIPPED LED will also turn on until the RESET button is pushed.

- 5. Repeat step 4 for the remaining sensors.
- 6. Confirm that all LED's at connected sensors are flashing red.
- 7. Press MODE to switch back to online mode (ONLINE LED will be solid green and SERVICE LED will be off).

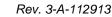
The test can be cancelled at any time by pressing MODE, to return to online mode.

13.3 Testing the Trip Coil

- 1. Ensure that the system is ready for testing. The TRIP COIL output will be tripped during this procedure.
- 2. Press MODE to switch to service mode (SERVICE LED will be solid red).
- 3. Press and hold TRIP for a few seconds to activate the TRIP COIL output.
- 4. Observe that the connected trip coil operates. The output will reset itself after the configured pulse time, one second by default.
- 5. Press RESET. Reset the tripping device if necessary.
- 6. Press MODE to switch back to online mode (ONLINE LED will be solid green and SERVICE LED will be off).

13.4 Full Operation Test (Online)

- 1. Make sure that the system is ready for test. The TRIP COIL output will be tripped during this procedure.
- 2. If necessary, press MODE to switch to online mode (ONLINE LED will be solid green).
- 3. Confirm that there is a solid PGR-8800 green LED for each connected optical sensor. This confirms that sensors are connected and healthy.
- 4. Confirm that a short red flashing light occurs periodically in each sensor. This indicates that the sensor circuit is being checked.
- 5. Move a light source towards the local sensor and confirm that it starts flashing.
- 6. Move a light source towards an external sensor. The SENSOR LED will start flashing green when the light intensity is approaching the Trip Level.
- 7. Continue to move a light source closer to the sensor. Confirm that the TRIP COIL output trips and that the LED's of the TRIP COIL and sensor change to flashing red.
- 8. Press RESET. Reset the tripping device if necessary.
- 9. Repeat steps 6 to 8 for the remaining sensors.





13.5 Light Sensitivity Adjustment

1. Adjust the TRIP LEVEL dial; lower numbers result in higher sensitivity and greater detection range.

13.6 Fiber-Optic Sensor Adjustment

The sensor is calibrated at the factory for 60 cm (24") of fiber in each monitored compartment. When using a fiber-optic sensor in compartments with less than 60 cm (24") of fiber, the sensitivity may have to be adjusted. The sensor is unable to differentiate between 10,000 lux on 60 cm (24") of fiber and 30,000 lux on 20 cm (8") of fiber – the same amount of light is transmitted through the fiber to the receiver. To achieve the desired sensitivity, the receiver (with the black thumb nut) must be adjusted.

13.6.1 Sensor Adjustment for a Fiber Length other than 60 cm (24")

To adjust for fiber length, a powerful light source of at least 100 lumen (e.g. 300 W halogen lamp) is required. In some cases, a photo flash with a guide number of 15 m (49 ft) or larger can be used. Use the following procedure to calibrate the sensor:

- 1. Switch the PGR-8800 to service mode by pressing the MODE button. The red SERVICE LED will light.
- 2. Adjust the TRIP LEVEL setting to 1 on the PGR-8800.
- 3. Slowly move the lamp towards the local sensor on the front of the PGR-8800.
- 4. Note the distance from the lamp to the sensor when the LOCAL LED starts blinking.
- 5. Adjust the receiver (black thumb nut) sensitivity level to the minimum by turning the small metal screw clockwise until it begins to click. This may be too low to detect the sensor-check signal and may cause the related LED on the relay to flash red.
- 6. Place the lamp facing the fiber in the compartment closest to the transmitter end (white thumb nut) of the fiber at the distance observed in step 4. This allows for loss along the full length of the fiber.
- Slowly turn the metal screw on the receiver counter-clockwise until the PGR-8800 sensorindicator LED for that sensor changes to red. If the LED was already flashing red in step 5, it should change to green first.
- 8. Adjust the TRIP LEVEL setting back to the desired position.



13.6.2 Sensor Adjustment in Small Compartments

If the fiber-optic sensor is used in multiple compartments of varying size, the sensor must be calibrated to the compartment with the least fiber. If the lamp cannot be placed far enough away in the compartment to follow the procedure in Section 13.6.1, the sensitivity-adjustment procedure can be modified as follows:

- 1. Switch the PGR-8800 to service mode by pressing the MODE button. The red SERVICE LED will light.
- 2. In the compartment with the shortest fiber, measure the distance from the fiber to the lamp when the lamp is placed at the point in the compartment where it is furthest away.
- 3. Set the TRIP LEVEL to 9 on the PGR-8800.
- 4. Place the lamp facing the local sensor on the PGR-8800 at the same distance as measured in step 2.
- 5. Turn the TRIP LEVEL dial on the PGR-8800 counter clockwise until the LOCAL LED starts blinking.
- 6. Adjust the receiver (black thumb nut) sensitivity level to minimum by turning the small metal screw clockwise until it begins to click. This may be too low to detect the sensor-check signal and may cause the related LED on the relay to flash red.
- 7. Place the lamp in the compartment closest to the transmitter end (white thumb nut) of the fiber at the distance observed in step 2. This allows for loss along the full length of the fiber.
- Slowly turn the metal screw on the receiver counter-clockwise until the PGR-8800 sensorindicator LED for that sensor changes to red. If the LED was already flashing red in step 6, it should change to green first.
- 9. Adjust the TRIP LEVEL setting back to the desired position.



14 SPECIFICATIONS 14.1 PGR-8800

| 14.1 FGR-0000 | |
|---------------------------------|--|
| Supply: | |
| Universal: | 20 VA, 100 to 240 Vac (+10%, -15%) 50/60 Hz, |
| | 8 W, 110 to 250 Vdc (+10%, -20%) |
| Low Voltage: | 4 W, 14 to 48 Vdc (+10%, -20%) |
| Backup Battery (user supplied): | 24 Vdc lead-acid, 2 to 15 Ah capacity |
| | Charged at 27.5 Vdc, 200 mA max when universal |
| | supply is used |
| Optical Settings: | |
| External Sensors: | Up to 24 (6 per unit) |
| Sensor Types: | PGA-LS10, PGA-LS20, PGA-LS25, PGA-LS30 all with |
| | sensor check |
| Trip Sensitivity Adjustment: | 1 to 9 (corresponding to 9 to 25 klux) |
| Trip Time Settings: | 0 to 20,000 ms (0.8 ms effective minimum) |
| Trip Coil Output: | |
| Type: | IGBT Switch |
| Configuration: | Normally Open (Form A) |
| UL Rating: | 120/240 Vac, 1800 VA, 0.75 A maximum continuous, |
| | 125/250 Vdc, 138 VA, 0.75 A maximum continuous |
| Supplemental Rating: | |
| Make/Carry 0.2 s: | 30 A |
| Voltage Rating ¹ : | 24 to 300 Vac, 24 to 300 Vdc |
| Current Rating: | 20 A for 2 s, 10 A for 5 s |
| Control Voltage Alarm: | 5 V |
| Operating Modes: | Shunt or Undervoltage |
| Protection: | 320 Vac MOV, thermally protected |
| Isolation: | 1,000 Vac |
| Pulse Duration: | 1 to 5 s, configurable |
| On-State Voltage Drop: | 2.5 V at 5 A, 25°C (77°F) |
| | 4.0 V at 10 A, 25°C (77°F) |
| Output Relays: | |
| Main Relays: | Online, Service, Tripped |
| Contact Configuration: | Change-over (Form C) |
| UL Contact Rating: | 5 A Resistive, 250 Vac |
| | 5 A Resistive, 30 Vdc |
| | |



| Supplemental Contact Rating: | |
|------------------------------|--|
| Make/Carry 0.2 s: | 30 A |
| Rating Code: | B300, R300 |
| Break: | |
| dc: | 28 W Resistive |
| ac: | 1500 VA (PF=1.0) |
| | 360 VA (PF=0.4) |
| | Subject to maximums of 5 A and 250 V (ac or dc) |
| Status Relays: | Online, terminal 49 (STO) |
| | Service, terminal 53 (STS) |
| | Tripped, terminal 57 (STT) |
| Contact Configuration: | Normally Open (Form A), reference to terminal 45 (COM) |
| UL Rating: | 100 mA, 50 Vac/Vdc |
| Supplemental Rating: | |
| Contact Rating: | 3 A Resistive, 240 Vac |
| | 3 A Resistive, 30 Vdc |
| Terminals: | Wire Clamping, 22-12 AWG (0.14 to 2.5 mm ²) copper |
| | conductors |
| Torque: | 4 to 5.5 in-lb |
| Current Inputs: | |
| Full Scale: | 5 A Secondary |
| Continuous: | 10 A Secondary |
| Thermal Withstand: | 75 A for 1 s |
| Burden: | < 0.25 VA at 5 A |
| Current Sensor Class: | Protection Class 10P5 or better |
| Trip Time: | 1 to 20,000 ms |
| Trip Level: | |
| Overcurrent 1: | 150 to 1,000% of rated nominal load current |
| Overcurrent 2: | 150 to 1,000% of rated nominal load current |
| Accuracy: | 1 A secondary |
| Resolution: | 100 mA secondary |
| Isolation: | 500 Vac |
| Local Interface: | USB 1.1 |
| Communications Interface: | |
| Protocol: | Modbus [®] RTU |
| | Moddus RTU |



| Bus Length: | 10 m (32.8 ft) |
|--|---|
| Cable: | Shielded twisted pair, Belden 3105A or equivalent |
| System Expansion: | Link up to four units |
| Internal Real-Time Clock: | |
| Battery ² : | CR1632 |
| Life: | Minimum 10 years |
| Dimensions: | |
| Height: | 130 mm (5.1 in) |
| Width: | 200 mm (7.9 in) |
| Depth: | 54 mm (2.1 in) |
| Shipping Weight: | 0.9 kg (2 lbs) |
| Mounting: | 35 mm DIN rail or surface mount |
| Environment: Operating Temperature: | -25 to 70°C (-13°F to 158°F) |
| Storage Temperature: | -40 to 70°C (-40°F to 158°F) |
| Humidity: | 93% Non-condensing |
| Altitude: | so is Norr condensing |
| Below 2,000 m (6,500 ft): | Normal Operation |
| Above 2,000 m (6,500 ft): | 24 Vdc supply only, shunt trip only |
| Above 2,000 m (0,000 ft): | Contact Littelfuse for further information. |
| EMC Tests: | |
| Verification tested in accordance | with EN60255-26:2009. |
| 1 MHz Burst: | IEC 60255-22-1 |
| | ± 1 kV differential mode |
| | (line-to-line) |
| | ± 2.5 kV common mode |
| Electrostatic Discharge: | IEC 60255-22-2 |
| - | ± 6 kV Contact Discharge |
| | (direct and indirect) |
| | ± 8 kV Air Discharge |
| Radiated RF Immunity: | IEC 60255-22-3 |
| | 10 V/m, 80-1,000 MHz, |
| | 80% AM (1 kHz) |
| | 10 V/m, 1.4 to 2.7 GHz, |
| | 80% AM (1 kHz) |
| Fast Transient: | IEC 60255-22-4 |
| | Class A: ± 4 kV |
| | |



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| | (on AC mains) |
|-------------------------------|--|
| Surge Immunity: | IEC 60255-22-5 |
| | ± 4 kV differential mode |
| | (on AC lines) |
| | ± 2 kV common mode |
| | (on AC lines) |
| | ± 2 kV common mode |
| | (on I/O ports) |
| | ± 1 kV differential mode |
| | (on I/O ports) |
| Conducted RF Immunity: | IEC 60255-22-6 |
| | 10 Vrms, 0.15-80 MHz |
| | 80% AM (1 kHz) |
| Power Frequency: | IEC 60255-22-7 |
| | Not applicable |
| | Cables are < 10 m |
| Magnetic Field Immunity: | IEC 61000-4-8 |
| | 50 Hz and 60 Hz |
| | 30 A/m and 300 A/m |
| Current Harmonics and Voltage | |
| Fluctuations: | IEC 61000-3-2 |
| | and IEC 61000-3-3 |
| | Class A |
| Radiated and Conducted | |
| Emissions: | CISPR 22:2008-09 / EN55022:2010 |
| | Class A |
| Voltage Interruptions: | IEC 60255-11 |
| | and IEC 60255-29 |
| | 100% Interrupts 3 x for 5 ms, 10 ms, 20 ms, 50 ms, |
| | 100 ms, 200 ms |
| Vibration: | IEC 60255-21-1 (Vibration, shock, and seismic) |
| Safety: | IEC 61010-1: 2010 3 rd Edition |
| | Safety Requirements for Electrical Equipment for |
| | Measurement, Control, and Laboratory Use – Part I |



Certification:

UL Listed LISTED IND.CONT.EQ AVY5 NRGU.E348169 UL508 Industrial Control Equipment³ Australia CE, European Union CE, European Union EMC standards: EN60255-26 FCC FCC ANSI/IEEE C37.90.1-2002 (Oscillatory and Fast Transient

PGA-LS20, PGA-LS25, and

PGA-LS30

Surge Withstand:

14.2 Sensors

PGA-LS10

| Туре: | Point sensor | Fiber-optic sensor |
|-----------------------------|--|---|
| Detection Zone: | 180 x 360° (half sphere) | 360° along fiber |
| Output: | 0-35 mA | 0-35 mA |
| Electrical Cable: | Shielded 3-wire 20 AWG (0.5 mm ²) electrical cable | Shielded 3-wire 20 AWG (0.5 mm ²) electrical cable |
| Factory Cable Length: | 10 m (33 ft) electrical cable | PGA-LS20: $8 m (26 ft)$ active; 10 m (33 ft) total $(2 m (7 ft)$ shielded), $2 x 10 m$ electrical cable PGA-LS25: $5 m (16 ft)$ active; $8 m (26 ft)$ total $(3 m (10 ft)$ shielded), $2 x 10 m (33 ft)$ electrical cable PGA-LS30: $18 m (59 ft)$ active; $20 m (66 ft)$ total $(2 m (7 ft)$ shielded), $2 x 10 m (33 ft)$ electrical cable |
| Max. Elec. Cable Length: | 50 m (164 ft) | 50 m (164 ft) |
| Sensor Check: | Built-in LED for visual feedback | Built-in LED for visual feedback |



| Dimensions: | 32 x 52 x 24 mm (1.3 x 2.0 x 0.9 in) | Transmitter and Receiver: 32 x 56 x 19 mm (1.3 x 2.2 x 0.7 in) |
|-------------|---|--|
| Enclosure: | IP 30 | IP 30 |

PGR-8800 uses the open source components FreeRTOS and FreeMODBUS internally. For license, version, and source-code information please contact opensource@littelfuse.com.

15 ORDERING INFORMATION

PGR-8800-00⁽⁴⁾

Accessories:

| PGA-LS10 | Point Sensor |
|-------------|--|
| PGA-LS20 | Fiber-Optic Sensor, 8 m (26 ft) active length |
| PGA-LS25 | Fiber-Optic Sensor, 5 m (16 ft) active length |
| PGA-LS30 | Fiber-Optic Sensor, 18 m (59 ft) active length |
| PGA-0031 | DIN-rail mounting brackets |
| PGA-1100 | Diode Logic Unit |
| PGA-FLSH-00 | Photo Flash |
| PGA-FLSH-01 | Photo Flash, CE and RoHS |

16 WARRANTY

The PGR-8800 Arc-Flash Relay is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse will (at Littelfuse's option) repair, replace, or refund the original purchase price of a PGR-8800 that is determined by Littelfuse to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse does not warrant products repaired or modified by non-Littelfuse personnel.

NOTES:

¹ Contact Littelfuse for trip coil voltages higher than 300 Vac/Vdc.

- ² Battery is mounted in an internal socket and should be changed by qualified service personnel only. Contact your distributor for more information.
- ³ The PGR-8800 Arc Flash Relay is currently listed as a protective relay (UL category NRGU) and complies with the UL508 Industrial Control Equipment standard. UL did not evaluate the functionality of the arc fault protection afforded by this product. A file review will occur when the requirements for investigation of arc detection and mitigation systems are developed and additional tests will be performed if required.
- ⁴ Hardware revision 2.1 includes UL, CE, and C-Tick certification. Hardware revision 2.0 includes UL and C-Tick certification. Refer to Appendix E for details.



APPENDIX A PGR-8800 MODBUS RTU PROTOCOL

A.1 PROTOCOL

The MODBUS RTU protocol is implemented in the PGR-8800, and allows up to four modules to be connected using a 2-wire TIA-485 bus. The MODBUS interface will provide status information for sensors, analog inputs, digital inputs, digital outputs, and numerous event and error flags. It also provides the ability to remotely reset the PGR-8800. Writes are not allowed by default.

A.1.1 Configuration Setup

| Z Configuration | | | |
|--|--|----------------|----------|
| E Littelfus | :e° | | × |
| Configuration Software | | | |
| General Optical Sensors Current Sensor | S Digital Inputs Outputs Communication | Advanced About | _ |
| Communication | | | |
| Link Interface | | | |
| Is used for | MODBUS | Undo Reset | |
| NOTE: Changes to this parameter will rel | boot the unit to complete the change. | | |
| MODBUS Configuration | | | |
| Unit address | 1 | Undo Reset | |
| Baud rate | 19200 - | Undo Reset | |
| Parity | Even 💌 | Undo Reset | |
| Allow writes via MODBUS | | Undo Reset | |
| | | | |
| Save All Reset (This Tab) | Undo (This Tab) Save and Exit | Exit | |
| | | | |
| Copyright (c) 2011-2012. Littelfuse Inc. All rig | hts reserved. | | |
| | | | |
| | | | T |

A.2 MESSAGE SYNCHRONIZATION

Message synchronization is accomplished by detection of an idle communication line. The communication line is considered idle when no communication exists for an equivalent delay of 3.5 characters.

The first byte received after idle-line detection is interpreted as the address byte of the next message. Message bytes must be transmitted in a continuous stream until the complete message has been sent. If a delay of more than 3.5 characters exists within the message, the message is discarded. Response messages from the PGR-8800 are delayed by at least 3.5 character delays.

A.3 ERROR CHECKING

Modbus RTU uses a 16-bit cyclic redundancy check (CRC). The error check includes all of the message bytes, starting with the first address byte. When a CRC error is detected, the message is discarded and there will be no response.



A.4 FUNCTION CODES SUPPORTED

The PGR-8800 Modbus Protocol supports the following function codes:

Read Holding registers (Function code 3)

Read Input registers (Function code 4)

Write Single register* (Function code 6)

Read Slave ID (Function code 11)

Write Multiple registers* (Function code 16)

*If writing is enabled in the configuration

A.4.1 Read Input/Holding Registers (Code 04/03)

The first byte of the read message is the slave address. The second byte is the function code. Bytes three and four indicate the starting register. The next two bytes specify the number of 16-bit registers to read. The last two bytes contain the CRC code for the message.

| | TABLE A.1 REA | D REGISTERS (CODE 04/03) |
|----------|---------------|--------------------------|
| HEX BYTE | | DESCRIPTION |
| | Byte 1 | Slave Address |
| | Byte 2 | Function Code |
| | Byte 3 | MSB Register Address |
| | Byte 4 | LSB Register Address |
| | Byte 5 | MSB Number of Registers |
| | Byte 6 | LSB Number of Registers |
| | Byte 7 | LSB CRC |
| | Byte 8 | MSB CRC |

The two-byte values of starting register and number of registers to read are transmitted with the highorder byte followed by the low-order byte. The CRC value is sent with the LSB followed by the MSB.

A.4.2 Write to Register

Function Code 6 or 16 is used to make set-point changes.

A.4.2.1 Write Single Register (Code 6)

The function code format for writing a single register is shown in Table A.2.

The message consists of the slave address followed by the Function Code 6 and two 16-bit values. The first 16-bit value specifies the register to be modified and the second value is the 16-bit data.

| TABLE A.2 WITTE BINGEL REGISTER (BODE 0) | | |
|--|----------------------|--|
| HEX BYTE | DESCRIPTION | |
| Byte 1 | Slave Address | |
| Byte 2 | Function Code | |
| Byte 3 | MSB Register Address | |
| Byte 4 | LSB Register Address | |
| Byte 5 | MSB of Data | |
| Byte 6 | LSB of Data | |
| Byte 7 | LSB of CRC | |
| Byte 8 | MSB of CRC | |



A.4.2.2 Write Multiple Registers (Code 16)

The function-code format in Table A.3 can be used for writing single or multiple registers.

| TABLE A.3 WRITE MULTIPLE REGISTERS | (CODE 16) |
|------------------------------------|-----------|
| | (00000) |

| HEX BYTE # | DESCRIPTION |
|------------|----------------------|
| Byte 1 | Slave Address |
| Byte 2 | Function Code |
| Byte 3 | MSB Register Address |
| Byte 4 | LSB Register Address |
| Byte 5 | MSB of Quantity |
| Byte 6 | LSB of Quantity |
| Byte 7 | Byte Count |
| | MSB of Data |
| | LSB of Data |
| | LSB of CRC |
| Byte n | MSB of CRC |

The slave will reply with the slave address, function code, register address, and the quantity followed by the CRC code for a total of eight bytes.

A.4.3 Exception Responses

The PGR-8800 will return appropriate error codes as per the standard for malformed or out-of-range requests.

A.5 PGR-8800 DATABASE

Appendix B contains the Modbus Registers in the Communications Database Table. The table starts at register 200 and each register is 16-bits wide.

A.6 SPECIFICATIONS

| Interface | Isolated TIA-485, 2-wire multi-drop |
|----------------------|--|
| Protocol | Modbus [®] RTU |
| Baud Rate | 1,200 to 19,200 bit/s |
| Bit Format | 8 bits, even or odd parity, one or two stop bits |
| Maximum Cable Length | 10 m (33 ft) |
| Cable Type | Shielded Twisted Pair, Belden 3105A or equivalent |
| Terminals | 22 to 12 AWG, (0.1 to 2.5 mm ²) conductors |
| | |

NOTE: The TIA-485 hardware is shared with the Link function and can either be configured for Link or Modbus but not both at the same time.

References

[1] "MODBUS over serial line specification and implementation guide V1.02" http://www.modbus.org/docs/Modbus_over_serial_line_V1_02.pdf

[2] "MODBUS Application protocol Specification V1.1b" http://www.modbus.org/docs/Modbus_Application_Protocol_V1_1b.pdf



APPENDIX B MODBUS COMMUNICATIONS DATABASE TABLE

| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | ТҮРЕ |
|-----------------------------------|---------------------------------|-----------------------------------|-----------|----------|------------------------|
| Analog Inputs | (Values) | · | | • | · |
| 200 | 40201 | Number of analog inputs on system | Read Only | N/A | 16-bit word, always 22 |
| 201 | 40202 | Light on Sensor 1 | Read Only | 3 | T1 |
| 202 | 40203 | Light on Sensor 2 | Read Only | 7 | T1 |
| 203 | 40204 | Light on Sensor 3 | Read Only | 11 | T1 |
| 204 | 40205 | Light on Sensor 4 | Read Only | 15 | T1 |
| 205 | 40206 | Light on Sensor 5 | Read Only | 19 | T1 |
| 206 | 40207 | Light on Sensor 6 | Read Only | 23 | T1 |
| 207 | 40208 | Current on CT1 | Read Only | 25 – 26 | T2 |
| 208 | 40209 | Current on CT2 | Read Only | 27 – 28 | T2 |
| 209 | 40210 | Current on CT3 | Read Only | 29 – 30 | T2 |
| 214 | 40215 | Light on Front Sensor | Read Only | N/A | T1 |
| Analog Inputs | (Max value si | nce last read) | | | |
| 300 | 40301 | Number of analog inputs on system | Read Only | N/A | 16-bit word, always 22 |
| 301 | 40302 | Light on Sensor 1 | Read Only | 3 | T1 |
| 302 | 40303 | Light on Sensor 2 | Read Only | 7 | T1 |
| 303 | 40304 | Light on Sensor 3 | Read Only | 11 | T1 |
| 304 | 40305 | Light on Sensor 4 | Read Only | 15 | T1 |
| 305 | 40306 | Light on Sensor 5 | Read Only | 19 | T1 |
| 306 | 40307 | Light on Sensor 6 | Read Only | 23 | T1 |
| 307 | 40308 | Current on CT1 | Read Only | 25 – 26 | T2 |
| 308 | 40309 | Current on CT2 | Read Only | 27 – 28 | T2 |
| 309 | 40310 | Current on CT3 | Read Only | 29 – 30 | T2 |
| 314 | 40315 | Light on Front Sensor | Read Only | N/A | T1 |
| Analog Inputs | (Min value si | nce last read) | | | |
| 400 | 40401 | Number of analog inputs on system | Read Only | N/A | 16-bit word, always 22 |
| 401 | 40402 | Light on Sensor 1 | Read Only | 3 | T1 |
| 402 | 40403 | Light on Sensor 2 | Read Only | 7 | T1 |
| 403 | 40404 | Light on Sensor 3 | Read Only | 11 | T1 |
| 404 | 40405 | Light on Sensor 4 | Read Only | 15 | T1 |
| 405 | 40406 | Light on Sensor 5 | Read Only | 19 | T1 |
| 406 | 40407 | Light on Sensor 6 | Read Only | 23 | T1 |
| 407 | 40408 | Current on CT1 | Read Only | 25 – 26 | T2 |
| 408 | 40409 | Current on CT2 | Read Only | 27 – 28 | T2 |
| 409 | 40410 | Current on CT3 | Read Only | 29 – 30 | T2 |
| 414 | 40415 | Light on Front Sensor | Read Only | N/A | T1 |
| Sensor Input | Status | | | | |
| 500 | 40501 | Number of light sensors on system | Read Only | N/A | 16-bit word, always 6 |
| 501 | 40502 | Status of Sensor 1 | Read Only | 3 | Т3 |
| 502 | 40503 | Status of Sensor 2 | Read Only | 7 | Т3 |
| 503 | 40504 | Status of Sensor 3 | Read Only | 11 | Т3 |
| 504 | 40505 | Status of Sensor 4 | Read Only | 15 | Т3 |
| 505 | 40506 | Status of Sensor 5 | Read Only | 19 | Т3 |
| 506 | 40507 | Status of Sensor 6 | Read Only | 23 | Т3 |



| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | ТҮРЕ |
|-----------------------------------|---------------------------------|--|------------|----------|------------------------|
| Power Voltag | es | · | | | |
| 600 | 40601 | Number of power inputs on system | Read Only | N/A | 16-bit word, always 5 |
| 601 | 40602 | Output from AC supply | Read Only | 35 | T4 |
| 602 | 40603 | Input from DC terminal | Read Only | 34 | T5 |
| 603 | 40604 | Input from battery | Read Only | 35 | Т6 |
| 604 | 40605 | Output from 5 V supply | Read Only | N/A | T7 |
| 605 | 40606 | Output from sensor supply | Read Only | N/A | Т8 |
| Mode Control | | | | | · |
| 1100 | 41101 | Number of user-writable mode selections | Read Only | N/A | 16-bit word, always 3 |
| 1101 | 41102 | Mode | Read/Write | N/A | Т9 |
| 1102 | 41103 | Power | Read Only | N/A | T10 |
| 1103 | 41104 | Error | Read Only | N/A | T11 |
| Digital Inputs | | | | | |
| 1200 | 41201 | Number of Digital Inputs on system | Read Only | N/A | 16-bit word, always 3 |
| 1201 | 41202 | Status of Inhibit Input | Read Only | 39 – 40 | T12 |
| 1202 | 41203 | Status of Trip Input | Read Only | 41 – 42 | T12 |
| 1203 | 41204 | Status of Reset Input | Read/Write | 43 – 44 | T13 |
| Address | | | | | |
| 1300 | 41301 | Number of relay outputs on system | Read Only | N/A | 16-bit word, always 4 |
| 1301 | 41302 | Status of Online output | Read Only | 46 – 49 | T14 |
| 1302 | 41303 | Status of Service output | Read Only | 50 – 53 | T14 |
| 1303 | 41304 | Status of Tripped output | Read Only | 54 – 57 | T14 |
| 1304 | 41305 | Status of IGBT output | Read Only | 59 – 60 | T14 |
| Event Flags | | | | | |
| 1500 | 41501 | Number of status flags available | Read Only | N/A | 16-bit word, always 58 |
| 1501 | 41502 | Not used | Read Only | N/A | T15 |
| 1502 | 41503 | Sensor 1 | Read Only | N/A | T15 |
| 1503 | 41504 | Sensor 2 | Read Only | N/A | T15 |
| 1504 | 41505 | Sensor 3 | Read Only | N/A | T15 |
| 1505 | 41506 | Sensor 4 | Read Only | N/A | T15 |
| 1506 | 41507 | Sensor 5 | Read Only | N/A | T15 |
| 1507 | 41508 | Sensor 6 | Read Only | N/A | T15 |
| 1508 | 41509 | Sensor front | Read Only | N/A | T15 |
| 1509 | 41510 | Analog OR of all sensors | Read Only | N/A | T15 |
| 1510 | 41511 | Current inhibit | Read Only | N/A | T15 |
| 1511 | 41512 | Current overload 1 | Read Only | N/A | T15 |
| 1512 | 41513 | Current overload 2 | Read Only | N/A | T15 |
| 1513 | 41514 | Not used | Read Only | N/A | T15 |
| 1514 | 41515 | Inhibit input | Read Only | N/A | T15 |
| 1515 | 41516 | Trip input | Read Only | N/A | T15 |
| 1516 | 41517 | Reset input | Read Only | N/A | T15 |
| 1517 | 41518 | Mode button | Read Only | N/A | T15 |
| 1518 | 41519 | Trip button long press | Read Only | N/A | T15 |
| 1519 | 41520 | Reset button | Read Only | N/A | T15 |
| 1520 | 41521 | Reset button long press | Read Only | N/A | T15 |
| 1521 | 41522 | Link trip | Read Only | N/A | T15 |
| 1522 | 41523 | Link command inhibit | Read Only | N/A | T15 |



| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | ТҮРЕ |
|-----------------------------------|---------------------------------|---|------------------|----------|------------------------|
| 1523 | 41524 | Link command trip | Read Only | N/A | T15 |
| 1524 | 41525 | Link command reset | Read Only | N/A | T15 |
| 1525 | 41526 | Modbus command inhibit | Read Only | N/A | T15 |
| 1526 | 41527 | Modbus command trip | Read Only | N/A | T15 |
| 1527 | 41528 | Modbus command reset | Read Only | N/A | T15 |
| 1528 | 41529 | Test or USB active | Read Only | N/A | T15 |
| 1529 | 41530 | State timeout | Read Only | N/A | T15 |
| 1530 | 41531 | Error timeout | Read Only | N/A | T15 |
| 1531 | 41532 | State done | Read Only | N/A | T15 |
| 1532 | 41533 | Trip log complete | Read Only | N/A | T15 |
| 1533 | 41534 | Link command service | Read Only | N/A | T15 |
| 1534 | 41535 | Link command online | Read Only | N/A | T15 |
| 1535 | 41536 | Modbus command service | Read Only | N/A | T15 |
| 1536 | 41537 | Modbus command online | Read Only | N/A | T15 |
| 1537 | 41538 | Error link | Read Only | N/A | T15 |
| 1538 | 41539 | Error task failed | Read Only | N/A | T15 |
| 1539 | 41540 | Error power failure | Read Only | N/A | T15 |
| 1540 | 41541 | Error IGBT missing voltage | Read Only | N/A | T15 |
| 1541 | 41542 | Error sensor power failure | Read Only | N/A | T15 |
| 1542 | 41543 | Link command error | Read Only | N/A | T15 |
| 1543 | 41544 | Link command setup | Read Only | N/A | T15 |
| 1544 | 41545 | Trip button | Read Only | N/A | T15 |
| 1545 | 41546 | Output trip momentary command | Read Only | N/A | T15 |
| 1546 | 41547 | CB closed feedback | Read Only | N/A | T15 |
| 1547 | 41548 | CB clearing failure | Read Only | N/A | T15 |
| 1548 | 41549 | Current detect for CB failure | Read Only | N/A | T15 |
| 1549 | 41550 | Currently AC powered | Read Only | N/A | T15 |
| 1550 | 41551 | Currently DC powered | Read Only | N/A | T15 |
| 1551 | 41552 | Local CB tripped in this event | Read Only | N/A | T15 |
| 1552 | 41553 | Upstream CB tripped via Service relay | Read Only | N/A | T15 |
| 1553 | 41554 | Upstream CB tripped via Tripped relay | Read Only | N/A | T15 |
| 1554 | 41555 | Local CB tripped via Service relay | Read Only | N/A | T15 |
| 1555 | 41556 | Local CB tripped via Tripped relay | Read Only | N/A | T15 |
| 1556 | 41557 | Link alarm sent due to Light | Read Only | N/A | T15 |
| 1557 | 41558 | Link alarm sent due to Trip | Read Only | N/A | T15 |
| 1558 | 41559 | Link alarm sent due to Trip fault - tripped Upstream | Read Only | N/A | T15 |
| Status Flags | | | D • • • • | | |
| 1600 | 41601 | Number of status flags available | Read Only | N/A | 16-bit word, always 58 |
| 1601 | 41602 | Not used | Read Only | N/A | T15 |
| 1602 | 41603 | Sensor 1 | Read Only | N/A | T15 |
| 1603 | 41604 | Sensor 2 | Read Only | N/A | T15 |
| 1604 | 41605 | Sensor 3 | Read Only | N/A | T15 |
| 1605 | 41606 | Sensor 4 | Read Only | N/A | T15 |
| 1606 | 41607 | Sensor 5 | Read Only | N/A | T15 |
| 1607 | 41608 | Sensor 6 | Read Only | N/A | T15 |
| 1608 | 41609 | Sensor front | Read Only | N/A | T15 |
| 1609 | 41610 | Analog OR of all sensors | Read Only | N/A | T15 |



| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | ТҮРЕ |
|-----------------------------------|---------------------------------|---|------------------------|----------|------|
| 1610 | 41611 | Current inhibit | Read Only | N/A | T15 |
| 1611 | 41612 | Current overload 1 | Read Only | N/A | T15 |
| 1612 | 41613 | Current overload 2 | Read Only | N/A | T15 |
| 1613 | 41614 | Not used | Read Only | N/A | T15 |
| 1614 | 41615 | Inhibit input | Read Only | N/A | T15 |
| 1615 | 41616 | Trip input | Read Only | N/A | T15 |
| 1616 | 41617 | Reset input | Read Only | N/A | T15 |
| 1617 | 41618 | Mode button | Read Only | N/A | T15 |
| 1618 | 41619 | Trip button long press | Read Only | N/A | T15 |
| 1619 | 41620 | Reset button | Read Only | N/A | T15 |
| 1620 | 41621 | Reset button long press | Read Only | N/A | T15 |
| 1621 | 41622 | Link trip | Read Only | N/A | T15 |
| 1622 | 41623 | Link command inhibit | Read Only | N/A | T15 |
| 1623 | 41624 | Link command trip | Read Only | N/A | T15 |
| 1624 | 41625 | Link command reset | Read Only | N/A | T15 |
| 1625 | 41626 | Modbus command inhibit | Read Only | N/A | T15 |
| 1626 | 41627 | Modbus command trip | Read Only | N/A | T15 |
| 1627 | 41628 | Modbus command reset | Read Only | N/A | T15 |
| 1628 | 41629 | Test or USB active | Read Only | N/A | T15 |
| 1629 | 41630 | State timeout | Read Only | N/A | T15 |
| 1630 | 41631 | Error timeout | Read Only | N/A | T15 |
| 1631 | 41632 | State done | Read Only | N/A | T15 |
| 1632 | 41633 | Trip log complete | Read Only | N/A | T15 |
| 1633 | 41634 | Link command service | Read Only | N/A | T15 |
| 1634 | 41635 | Link command online | Read Only | N/A | T15 |
| 1635 | 41636 | Modbus command service | Read Only | N/A | T15 |
| 1636 | 41637 | Modbus command online | Read Only | N/A | T15 |
| 1637 | 41638 | Error link | Read Only | N/A | T15 |
| 1638 | 41639 | Error task failed | Read Only | N/A | T15 |
| 1639 | 41640 | Error power failure | Read Only | N/A | T15 |
| 1640 | 41641 | Error IGBT missing voltage | Read Only | N/A | T15 |
| 1640 | 41642 | | · · · | N/A | T15 |
| 1642 | 41642 | Error sensor power failure Link command error | Read Only | N/A | T15 |
| 1643 | 41644 | | Read Only Read Only | N/A | T15 |
| 1644 | 41645 | Link command setup Trip button | · · · | N/A | T15 |
| } | 41645 | Output trip momentary command | Read Only Read Only | N/A | T15 |
| 1645 | 41646 | | , | N/A | T15 |
| 1646 | | CB closed feedback | Read Only | | |
| 1647 | 41648 | CB clearing failure | Read Only | N/A | T15 |
| 1648 | 41649 | Current detect for CB failure | Read Only | N/A | T15 |
| 1649 | 41650 | Currently AC powered | Read Only | N/A | T15 |
| 1650 | 41651 | Currently DC powered | Read Only | N/A | T15 |
| 1651 | 41652 | Local CB tripped in this event | Read Only | N/A | T15 |
| 1652 | 41653 | Upstream CB tripped via Service relay Upstream CB tripped via Tripped | Read Only | N/A | T15 |
| 1653 | 41654 | relay | Read Only | N/A | T15 |
| 1654 | 41655 | Local CB tripped via Service relay | Read Only | N/A | T15 |
| 1655 | 41656 | Local CB tripped via Tripped relay | Read Only | N/A | T15 |
| 1656 | 41657 | Link alarm sent due to Light | Read Only | N/A | T15 |



| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | TYPE |
|-----------------------------------|---------------------------------|---|-----------|------------|------------------------|
| 1657 | 41658 | Link alarm sent due to Trip | Read Only | N/A | T15 |
| 1658 | 41659 | Link alarm sent due to Trip fault - tripped Upstream | Read Only | N/A | T15 |
| Error Flags | | | - T | r | |
| 1700 | 41701 | Number of status flags available | Read Only | N/A | 16-bit word, always 58 |
| 1701 | 41702 | Not used | Read Only | N/A | T15 |
| 1702 | 41703 | Sensor 1 | Read Only | N/A | T15 |
| 1703 | 41704 | Sensor 2 | Read Only | N/A | T15 |
| 1704 | 41705 | Sensor 3 | Read Only | N/A | T15 |
| 1705 | 41706 | Sensor 4 | Read Only | N/A | T15 |
| 1706 | 41707 | Sensor 5 | Read Only | N/A | T15 |
| 1707 | 41708 | Sensor 6 | Read Only | N/A | T15 |
| 1708 | 41709 | Sensor front | Read Only | N/A | T15 |
| 1709 | 41710 | Analog OR of all sensors | Read Only | N/A | T15 |
| 1710 | 41711 | Current inhibit | Read Only | N/A | T15 |
| 1711 | 41712 | Current overload 1 | Read Only | N/A | T15 |
| 1712 | 41713 | Current overload 2 | Read Only | N/A | T15 |
| 1713 | 41714 | Not used | Read Only | N/A | T15 |
| 1714 | 41715 | Inhibit input | Read Only | N/A | T15 |
| 1715 | 41716 | Trip input | Read Only | N/A | T15 |
| 1716 | 41717 | Reset input | Read Only | N/A | T15 |
| 1717 | 41718 | Mode button | Read Only | N/A | T15 |
| 1718 | 41719 | Trip button long press | Read Only | N/A | T15 |
| 1719 | 41720 | Reset button | Read Only | N/A | T15 |
| 1720 | 41721 | Reset button long press | Read Only | N/A | T15 |
| 1721 | 41722 | Link trip | Read Only | N/A | T15 |
| 1722 | 41723 | Link command inhibit | Read Only | N/A | T15 |
| 1723 | 41724 | Link command trip | Read Only | N/A | T15 |
| 1724 | 41725 | Link command reset | Read Only | N/A | T15 |
| 1725 | 41726 | Modbus command inhibit | Read Only | N/A | T15 |
| 1726 | 41727 | Modbus command trip | Read Only | N/A | T15 |
| 1727 | 41728 | Modbus command reset | Read Only | N/A | T15 |
| 1728 | 41729 | Test or USB active | Read Only | N/A | T15 |
| 1729 | 41730 | State timeout | Read Only | N/A | T15 |
| 1730 | 41731 | Error timeout | Read Only | N/A | T15 |
| 1731 | 41732 | State done | Read Only | N/A | T15 |
| 1732 | 41733 | Trip log complete | Read Only | N/A | T15 |
| 1733 | 41734 | Link command service | Read Only | N/A | T15 |
| 1734 | 41735 | Link command online | Read Only | N/A | T15 |
| 1735 | 41736 | Modbus command service | Read Only | N/A | T15 |
| 1736 | 41737 | Modbus command online | Read Only | N/A | T15 |
| 1737 | 41738 | Error link | Read Only | N/A | T15 |
| 1738 | 41739 | Error task failed | Read Only | N/A | T15 |
| 1739 | 41739 | Error power failure | Read Only | N/A | T15 |
| 1739 | 41740 | Error IGBT missing voltage | Read Only | N/A | T15 |
| 1740 | 41741 | Error sensor power failure | Read Only | N/A N/A | T15 |
| 1/41 | | · · · | | - | |
| 1742 | 41743 | Link command error | Read Only | N/A | T15 |

| 1/L | ittelfuse |
|-----|-----------|
|-----|-----------|

| PGR-8800 REGISTER (DECIMAL) | MODBUS REGISTER (DECIMAL) | DESCRIPTION | ACCESS | TERMINAL | TYPE |
|-----------------------------------|---------------------------------|---|-----------|----------|------|
| 1744 | 41745 | Trip button | Read Only | N/A | T15 |
| 1745 | 41746 | Output trip momentary command | Read Only | N/A | T15 |
| 1746 | 41747 | CB closed feedback | Read Only | N/A | T15 |
| 1747 | 41748 | CB clearing failure | Read Only | N/A | T15 |
| 1748 | 41749 | Current detect for CB failure | Read Only | N/A | T15 |
| 1749 | 41750 | Currently AC powered | Read Only | N/A | T15 |
| 1750 | 41751 | Currently DC powered | Read Only | N/A | T15 |
| 1751 | 41752 | Local CB tripped in this event | Read Only | N/A | T15 |
| 1752 | 41753 | Upstream CB tripped via Service relay | Read Only | N/A | T15 |
| 1753 | 41754 | Upstream CB tripped via Tripped relay | Read Only | N/A | T15 |
| 1754 | 41755 | Local CB tripped via Service relay | Read Only | N/A | T15 |
| 1755 | 41756 | Local CB tripped via Tripped relay | Read Only | N/A | T15 |
| 1756 | 41757 | Link alarm sent due to Light | Read Only | N/A | T15 |
| 1757 | 41758 | Link alarm sent due to Trip | Read Only | N/A | T15 |
| 1758 | 41759 | Link alarm sent due to Trip fault - tripped Upstream | Read Only | N/A | T15 |

TYPES:

- T1: 16-bit word, 0-1023, approx 35 lux/unit; Offset at 0 Klux is dependent on software revision and sensor type.
- T2: 16-bit word, 0-1023, approx 100 mA/unit; Offset at 0 A is approximately 512.
- T3: Reading: 0=Not detected; 1=Detected; 2=Not possible, old sensor.
- T4: In mV, nominally 26 V.
- T5: In mV, range 8-48 V. May wrap on systems not capable of reading unsigned 16 bit values.
- T6: In mV, range 20-28V.
- T7: In mV, nominally 5V.
- T8: In mV, nominally 4.5V.
- T9: Reading: 0=Online mode; 1=Service mode; Writing: 0=Set online mode; 1=Set service mode, writing only allowed if explicitly enabled in configuration.
- T10: Reading: 0=AC present; 1=DC present; 2=On battery power; 3=Battery low.
- T11: Reading: 0=No errors; 1=Error.
- T12: Reading: 0=Inactive; 1=Active; 2=Cable Broken.
- T13: Reading: 0=Inactive; 1=Active; 2=Cable Broken; Writing: 1=Reset trip (self-resets), writing only allowed if explicitly enabled in configuration.
- T14: Reading: 0=Open; 1=Closed.
- T15: Reading: 0=Inactive; 1=Active.

APPENDIX C COORDINATED TRIPPING OF UPSTREAM BREAKERS

The PGR-8800 is designed to detect arc faults and trip the local circuit breaker, interrupting the energy supply to the arc and clearing the fault.

This appendix explains how to configure the PGR-8800 to detect if the local circuit breaker failed to operate, and to send a trip signal to the upstream breaker.

This appendix generally assumes that the reader is familiar with the standard operation and configuration of the PGR-8800.

C.1 SYSTEM OVERVIEW

Littelfuse

Circuit breaker failure detection is possible by using either an auxiliary contact from the local circuit breaker or by using the current sensor inputs on the PGR-8800 to detect phase currents after the local circuit breaker has been told to trip, or both.

The operation time of the local circuit breaker must be considered before the decision is made to trip the upstream breaker. Selecting the correct delay is described in Section C.1.3.

In the case where the PGR-8800 has detected that the local circuit breaker failed to open, the upstream breaker must be tripped. If an upstream PGR-8800 is already installed, the Link interface can be used to send a trip signal to this unit. The advantages are that only a TIA-485 connection is needed between units, and that a failure in the connection will be detected. This configuration is described in Section C.2.2.

If the unit is configured as a stand-alone device, the Service and Tripped output relays can be programmed to trip an upstream circuit breaker. See Section C.1.4.

C.1.1 Circuit Breaker Feedback Detection

An available auxiliary contact in a circuit breaker can be used to provide feedback of the main contact positions. The PGR-8800 trip inputs (T1 or T2) can be configured to detect the circuit breaker status. This function is programmed using the configuration software. See Section C.2.1 for a programming and wiring example.

C.1.2 Current Sensor Detection

The PGR-8800 current sensors can also be used to detect phase currents to verify if the local circuit breaker has operated as expected. See Section C.2.3 for a programming and wiring example.

C.1.3 Total Clearing Time

Several parameters are needed to estimate the total clearing time of a local and upstream circuit breaker. The total clearing time is defined as:

Total Clearing Time = Arc Detection Delay + Local Circuit Breaker Operating Time + Output Delay + Upstream Circuit Breaker Operating Time

C.1.3.1 Arc Detection Delay

The PGR-8800's default arc-flash detection time is one millisecond, but can be configured between 0 and 20,000 milliseconds (see section 12.2.5). This is referred to as arc detection delay. When configured to 0 ms, the effective trip time is less than 0.8 ms.



C.1.3.2 Circuit Breaker Operating Time

Circuit breakers have a predetermined operating time, dependent on the type of circuit breaker. Older circuit breakers have clearing times up to eight cycles, while modern circuit breakers are able to open in one to five cycles. Refer to the specifications of the installed circuit breaker.

| CIRCUIT BREAKER OPERATING TIME | 50 HZ | 60 HZ |
|-----------------------------------|--------|--------|
| 8 cycles | 160 ms | 133 ms |
| 5 cycles | 100 ms | 83 ms |
| 3 cycles | 60 ms | 50 ms |
| 2 cycles | 40 ms | 33 ms |
| 1½ cycles | 30 ms | 25 ms |
| 1 cycle | 20 ms | 17 ms |

TABLE C.1 CIRCUIT BREAKER OPERATING TIMES

C.1.3.3 Output Delay

An additional output delay can be caused by the switching time of the Service or Tripped mechanical relays (five milliseconds), or the reaction time of an upstream PGR-8800 trip coil output (when connected with the Link interface).

C.1.3.4 Total Clearing Time Examples

Total Clearing Time Example 1:

Two 3-cycle breakers at 50 Hz, with the upstream breaker tripped by the Tripped relay in the local PGR-8800:

1 + 60 + 5 + 60 ms = 126 ms

Total Clearing Time Example 2:

Two 2-cycle breakers at 50 Hz, with the upstream circuit breaker tripped by an upstream PGR-8800 connected via Link interface:

1 + 40 + 1 + 40 = 82 ms

C.1.4 Relay Output

For smaller systems, one of the relay outputs can be configured to trip the upstream circuit breaker directly. The relay outputs are rated for pilot duty B300, and will trip most circuit breakers. See Section C.2.1 for a programming and wiring example.

C.1.5 Link Output

The Link feature can be configured to trip an upstream PGR-8800. This uses the solid state highspeed trip coil output, which eliminates the delay from the mechanical relay. See Section C.2.2 for a programming and wiring example.



C.1.6 PGA-1100 Diode Logic Unit

When several PGR-8800 protected zones are used and a common upstream circuit breaker should be tripped if any of the downstream zones experience a local clearing failure, the upstream circuit breaker may run out of inputs. The PGA-1100 Diode Logic Unit makes it possible to combine several trip outputs to the common circuit breaker. See Section C.2.6.

C.2 APPLICATION AND CONFIGURATION

The PGR-8800 is not configured for tripping the upstream circuit breaker in the default configuration shown below:

Configuration Software

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Outputs | | |
|--|----------------------------------|------------|
| Trip Coil Output | | |
| Circuit breaker type | Shunt coil (trips when powered) | Undo Reset |
| CB pulse time | 2 seconds | Undo Reset |
| Trip the CB in all modes, including Service | | Undo Reset |
| Report an error if trip coil is not detected | X | Undo Reset |
| Coordinated Tripping | | |
| Detect clearing failure by trip input | | Undo Reset |
| Detect clearing failure by current | | Undo Reset |
| Service Output | | |
| Service output function: | Indicate Service mode | Undo Reset |
| Tripped Output | | |
| Tripped output function: | Indicate that the unit tripped 🔹 | Undo Reset |

The configuration software hides the extra settings associated with Coordinated Tripping, as the feature is not yet enabled.

C.2.1 Single PGR-8800 Configuration

Figure C.1 shows an incoming feeder with a circuit breaker, a bus bar, and a zone protected with a PGR-8800. All sensors are downstream of the circuit breaker, but the upstream circuit breaker can be tripped if a local circuit-breaker failure occurs.



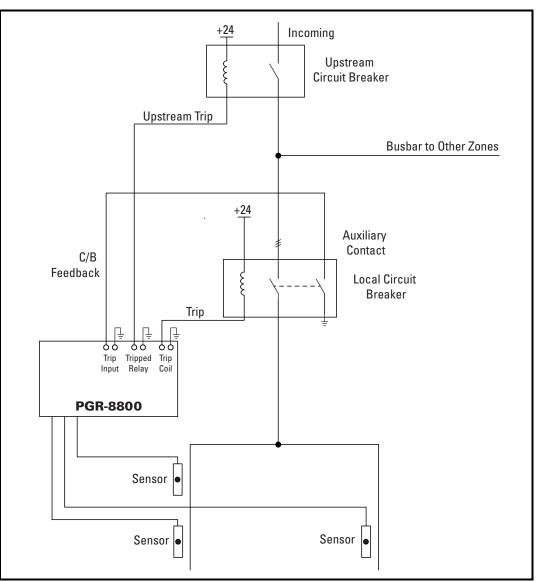


FIGURE C.1. Single PGR-8800 Configuration.

In this application, a circuit breaker with an auxiliary contact provides a trip input signal.

| Coordinated Tripping | | |
|---|--|------------------------------------|
| Detect clearing failure by trip input | ~ | Undo Reset |
| Detect clearing failure by current | _ | Undo Reset |
| Local CB worst case delay | 40 ms | Undo Reset |
| ERROR: Setup the trip input to read the ERROR: Enable Clearing Failure on eith the clearing failure | CB status in the Digital Inputs section er Link (see Communication section) or a re | elay output (below) to communicate |

The configuration software displays two warnings to configure a digital input as a feedback signal from the circuit breaker auxiliary contact and to configure a relay output to trip an upstream circuit breaker.

In the Tripped Output section, select Trip Upstream CB on Clearing Failure. This will remove the associated warning message.



| Coordinated Tripping | | |
|--|---|------------|
| Detect clearing failure by trip input | V | Undo Reset |
| Detect clearing failure by current | | Undo Reset |
| Local CB worst case delay | 40 ms | Undo Reset |
| ERROR: Setup the trip input to read the | CB status in the Digital Inputs section | |
| Service Output | | |
| Service output function: | Indicate Service mode | Undo Reset |
| Tripped Output | | |
| Tripped output function: | Trip upstream CB on clearing failure 💌 | Undo Reset |
| NOTE: The LED on the overlay will still indi | cate if the relav has tripped. | |

The trip coil on the upstream circuit breaker can now be connected to the Tripped output (terminals 54, 55, and 56). It is also possible to use the Service Output to trip the upstream circuit breaker.

On the Digital Inputs tab, set the Trip Input Main function to Circuit breaker feedback.

| General | Optical Sensors | Current Sensors | Digital Inputs | Outputs | Communication | Advanced A | bout |
|---------|-----------------|-----------------|----------------|---------|---------------|------------|------|

| Digital Inputs | | |
|----------------|---------------------------------------|--------------------------|
| Inhibit Inputs | | |
| Function: | Inhibit when low (switch closed) | Undo Reset |
| Trip Inputs | | |
| Main function: | Circuit breaker feedback 💌 | <u>Undo</u> <u>Reset</u> |
| Function: | CB is closed when low (switch closed) | Undo Reset |
| Reset Inputs | | |
| Function: | Reset when low (switch closed) | Undo Reset |

Select CB is closed when low (switch closed). When Trip Input T1 or T2 (terminal 41 and 42 respectively) is connected to Common (terminal 45), the monitored circuit breaker is determined to be closed.

This will remove the warning message and the configuration can be saved.



Configuration Software

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Outputs | | |
|--|--|------------|
| Trip Coil Output | | |
| Circuit breaker type | Shunt coil (trips when powered) | Undo Reset |
| CB pulse time | 2 seconds | Undo Reset |
| Trip the CB in all modes, including Service | | Undo Reset |
| Report an error if trip coil is not detected | 2 | Undo Reset |
| Coordinated Tripping | | |
| Detect clearing failure by trip input | | Undo Reset |
| Detect clearing failure by current | | Undo Reset |
| Local CB worst case delay | 40 ms | Undo Reset |
| Service Output | | |
| Service output function: | Indicate Service mode | Undo Reset |
| Tripped Output | | |
| Tripped output function: | Trip upstream CB on clearing failure 🚽 | Undo Reset |
| NOTE: The LED on the overlay will still indicate | if the relay has tripped. | |

Ensure the delay time for the local circuit breaker is set correctly for the circuit breaker type. The default is a 2-cycle circuit breaker delay. See Section C.1.3.2 for instructions on how to determine the circuit breaker operating time.



C.2.2 Dual PGR-8800 Configuration using Link Interface

The single line diagram shows an incoming feeder with a circuit breaker, a bus bar, and a zone protected with a PGR-8800. The upstream circuit breaker can be tripped by the local PGR-8800 via the Link interface if the local circuit breaker fails to operate.

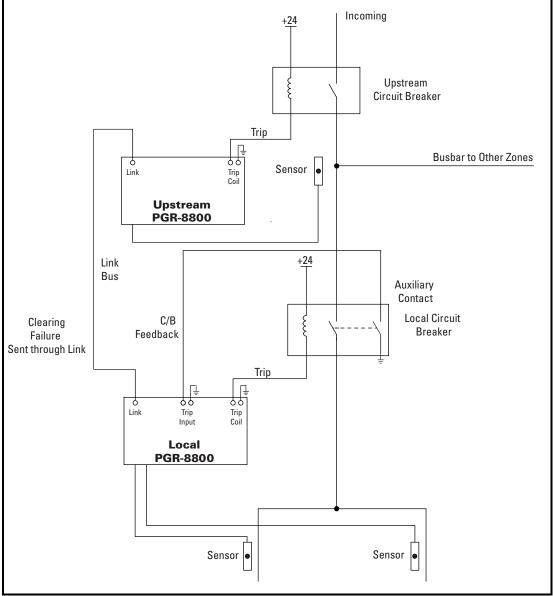


FIGURE C.2. Dual PGR-8800 Configuration using Link Interface.

The local circuit breaker auxiliary contact feedback is configured as in Section C.2.1.

Configure the local PGR-8800 to use the Link Interface. The unit address must be unique, and the number of linked units in the system must be configured.

Select Clearing Failure to allow the PGR-8800 to send the Link alarm signal to the upstream PGR-8800.

The Received Link alarm signal trips this unit is not selected. This makes it possible to have several downstream units trip a common upstream unit without tripping each other.



General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Communication | | |
|--|---|------------|
| Link Interface | | |
| Is used for | Linking multiple units 💌 | Undo Reset |
| NOTE: Changes to this parameter will reboot th | e unit to complete the change. | |
| Link Configuration | | |
| Unit address | Must be unique, lowest must be 1 | Undo Reset |
| Number of linked units in the system | 2 Report an error if any unit is missing. | Undo Reset |
| Send Link alarm signal on | Clearing failure | Undo Reset |
| Received Link alarm signal trips this unit | | Undo Reset |
| Link sends and receives the user interface | | Undo Reset |
| Link sends and receives errors | | Undo Reset |

The unit controlling the upstream circuit breaker is configured to receive a link alarm. The upstream PGR-8800 is configured to send a Link alarm signal, but in the current configuration, this has no effect as the local PGR-8800 is not configured to receive the Link alarm.

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

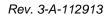
| Communication | | |
|--|---|------------|
| Link Interface | | |
| Is used for | Linking multiple units 💌 | Undo Reset |
| NOTE: Changes to this parameter will reboot th | e unit to complete the change. | |
| Link Configuration | | |
| Unit address | 2 Must be unique, lowest must be 1 | Undo Reset |
| Number of linked units in the system | Report an error if any unit is missing. | Undo Reset |
| Send Link alarm signal on | Trip | Undo Reset |
| Received Link alarm signal trips this unit | | Undo Reset |
| Link sends and receives the user interface | V | Undo Reset |
| Link sends and receives errors | × | Undo Reset |

The LINK cable wires must be connected to both units using terminals 37 and 38. The maximum length and cable type is described in Section 11.

C.2.3 Single PGR-8800 Configuration with Current Sensor Input

The single line diagram in Fig. C.3 shows a local circuit breaker that does not have an available feedback auxiliary contact. The current-sensor inputs can be configured to verify that the local breaker successfully operated.

PGR-8800 Arc-Flash Relay





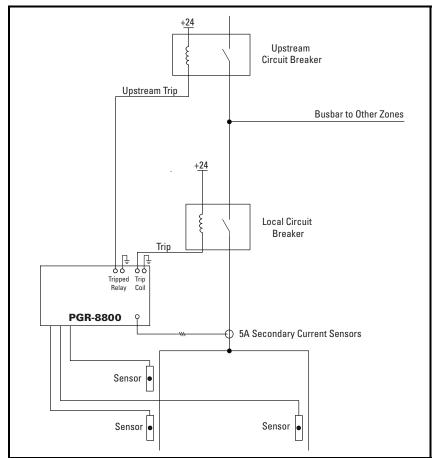


FIGURE C.3. Single PGR-8800 Configuration with Current Sensor Input.

NOTE: In this application, it is important that the current sensors are placed so that they only monitor current flowing through the local circuit breaker section. Otherwise, the upstream circuit breaker could trip even though the local circuit breaker cleared the fault.

NOTE: It is critical for the correct function of this application that three current sensors are connected.

In this case the current sensors are used as circuit feedback. This function is configured by selecting the Detect clearing failure by current check box.

| Coordinated Tripping | | |
|--|---|-------------------------------|
| Detect clearing failure by trip input | | Undo Reset |
| Detect clearing failure by current | | Undo Reset |
| Local CB worst case delay | 40 ms | Undo Reset |
| ERROR: Enable Clearing Failure on eith the clearing failure | her Link (see Communication section) or a relay | output (below) to communicate |
| Service Output | | |
| Service output function: | Indicate Service mode | Undo Reset |
| Tripped Output | | |
| Tripped output function: | Indicate that the unit tripped | Undo Reset |



The warning message refers to the output method, which has not yet been configured.

Select the Detect clearing failure by current checkbox.

| Setup | | |
|---------------------------------------|--------------------------|------------|
| Rated nominal load current | 4500 A RMS on CT primary | Undo Reset |
| CT transformation ratio | 5000 A to 5 A RMS | Undo Reset |
| Current sensor mode | AC 💌 | Undo Reset |
| Enable current inhibit | | Undo Reset |
| Trip on Overcurrent 1 | | Undo Reset |
| Trip on Overcurrent 2 | | Undo Reset |
| Indicator blinks when above | 100 % of rated current | Undo Reset |
| Trip Inhibit | | |
| Inhibit function disables trips below | 50 % of rated current | Undo Reset |

Rated nominal load current and CT transformation ratio should be set correctly. The rest of the setup does not influence the clearing failure function.

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Outputs | | |
|--|--|--|
| Trip Coil Output | | |
| Circuit breaker type | Shunt coil (trips when powered) | <u>Undo</u> <u>Reset</u> |
| CB pulse time | 2 seconds | Undo Reset |
| Trip the CB in all modes, including Service | | Undo Reset |
| Report an error if trip coil is not detected | | Undo Reset |
| Coordinated Tripping Detect clearing failure by trip input Detect clearing failure by current Local CB worst case delay | ✓ 40 ms | Undo Reset Undo Reset Undo Reset |
| Service Output | | |
| Service output function: | Indicate Service mode | Undo Reset |
| Tripped Output | | |
| Tripped output function: | Trip upstream CB on clearing failure 💌 | Undo Reset |
| NOTE: The LED on the overlay will still indicate | if the relay has tripped. | |

The relay output is configured as described in Section C.2.1. The warning message will disappear after selecting an output.

C.2.4 Dual PGR-8800 Configuration using Link Interface and Current Sensor Input

Littelfuse

The single line diagram in Fig. C.4 shows an incoming feeder with a circuit breaker, a bus bar, and a zone protected with an upstream PGR-8800. The upstream circuit breaker can be tripped in the event of a local circuit breaker failure.

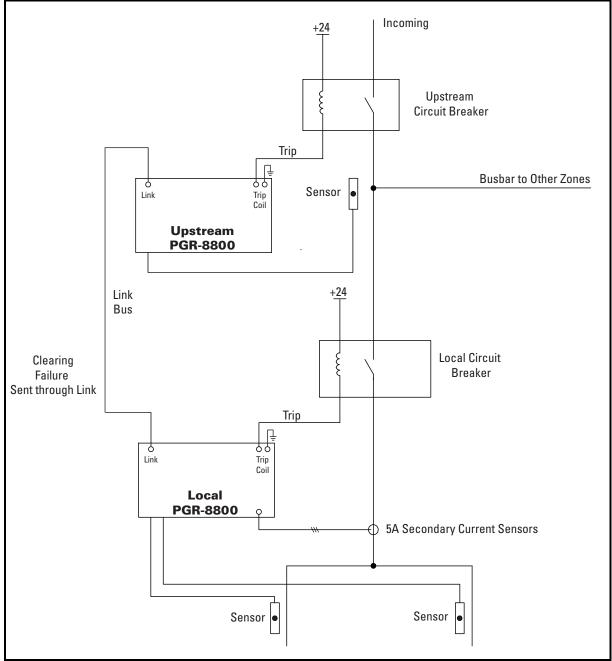


FIGURE C.4. Dual PGR-8800 Configuration using Link Interface and Current Sensor Input.

Configure clearing failure as in Section C.2.3, and output as in Section C.2.2.

In this case the current sensors are used as circuit feedback. This function is configured by selecting the Detect clearing failure by current check box.



| Coordinated Tripping | | | |
|--|---------------------------------------|----------------------|----------------------|
| Detect clearing failure by trip input | | | Undo Reset |
| Detect clearing failure by current | | | Undo Reset |
| Local CB worst case delay | 40 ms | | Undo Reset |
| ERROR: Enable Clearing Failure on eith the clearing failure | er Link (see Communication section) o | or a relay output (b | elow) to communicate |
| Service Output | | | |
| Service output function: | Indicate Service mode | • | Undo Reset |
| Tripped Output | | | |
| Tripped output function: | Indicate that the unit tripped | - | Undo Reset |

The warning message refers to the output method, which has not yet been configured.

Select the Detect clearing failure by current checkbox.

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Setup | | | |
|---------------------------------------|--------------------------|--------|-------|
| Rated nominal load current | 4500 A RMS on CT primary | Undo R | Reset |
| CT transformation ratio | 5000 A to 5 A RMS | Undo R | Rese |
| Current sensor mode | AC - | Undo R | Rese |
| Enable current inhibit | | Undo R | Reset |
| Trip on Overcurrent 1 | | Undo R | Rese |
| Trip on Overcurrent 2 | | Undo R | Reset |
| Indicator blinks when above | 100 % of rated current | Undo R | Reset |
| Trip Inhibit | | | |
| Inhibit function disables trips below | 50 % of rated current | Undo R | Rese |

The Rated Nominal load current and CT transformation ratio should be set correctly. The rest of the setup does not influence the clearing failure function.

Configure the local PGR-8800 to use the Link Interface. The unit address must be unique, and the number of linked units in the system must be configured.

Select Clearing Failure to allow the PGR-8800 to send the Link alarm signal to the upstream PGR-8800.

The Received Link alarm signal trips this unit is not selected. This makes it possible to have several downstream units trip a common upstream unit without tripping each other.



General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

| Communication | | |
|--|---|------------|
| Link Interface | | |
| Is used for | Linking multiple units 💌 | Undo Reset |
| NOTE: Changes to this parameter will reboot th | e unit to complete the change. | |
| Link Configuration | | |
| | | LINE DOLL |
| Unit address | Must be unique, lowest must be 1 | Undo Reset |
| Number of linked units in the system | 2 Report an error if any unit is missing. | Undo Reset |
| Send Link alarm signal on | Clearing failure | Undo Reset |
| Received Link alarm signal trips this unit | | Undo Reset |
| Link sends and receives the user interface | V | Undo Reset |
| Link sends and receives errors | | Undo Reset |

The unit controlling the upstream circuit breaker is configured to Receive Link alarm signal trips this unit. The upstream PGR-8800 is configured to send a Link alarm signal, but in the current configuration, this has no effect as the other downstream units are not configured to receive the Link alarm.

General Optical Sensors Current Sensors Digital Inputs Outputs Communication Advanced About

Communication

| Is used for | Linking multiple units 💌 | Undo Reset |
|--|---|------------|
| NOTE: Changes to this parameter will reboot th | e unit to complete the change. | |
| Link Configuration | | |
| Unit address | 2 Must be unique, lowest must be 1 | Undo Reset |
| Number of linked units in the system | | Undo Reset |
| | 2 Report an error if any unit is missing. | |
| Send Link alarm signal on | Trip | Undo Reset |
| Received Link alarm signal trips this unit | | Undo Reset |
| Link sends and receives the user interface | | Undo Reset |
| | | |

The link cable must be connected to both units, using terminals 37 and 38. The maximum length and cable type is described in the Section 14.

C.2.5 Configuration of Multiple Inputs and Outputs

It is possible to combine both input and output methods. For example, it is possible to use both the current sensor inputs and a circuit breaker auxiliary signal to detect a clearing failure. The relay will send the upstream trip signal if any of the criteria is met.

Likewise, it is possible to configure several outputs to react on a circuit breaker failure. The relay will simultaneously energize the two possible output relays and the Link Alarm signal, if so configured.



C.2.6 Tripping Common Upstream Circuit Breaker from Several Zones using PGA-1100

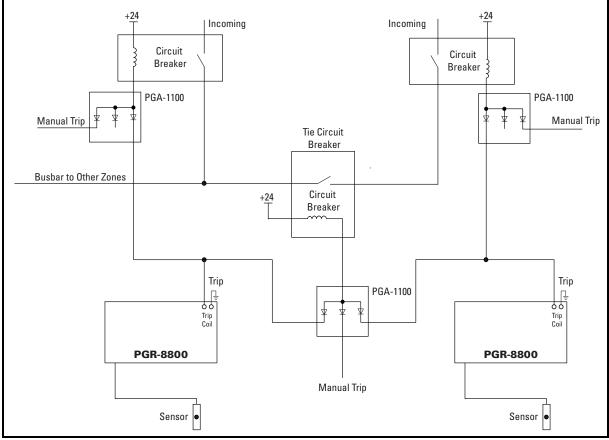


Fig. C.5. Tripping Common Upstream Circuit Breaker from Several Zones using PGA-1100.

Fig C.5 shows two incoming feeders and a tie breaker. Each incoming circuit breaker trip coil is connected to an independent PGR-8800 through a PGA-1100 Diode Logic Unit. The tie breaker trip coil is also connected to the trip coil of each PGR-8800 through a separate PGA-1100.

If a trip occurs at either PGR-8800, both the tie circuit breaker and the corresponding circuit breaker will trip.



APPENDIX D SYSTEM PARAMETERS AND SETUP RECORD¹

| GENERAL INSTALLATION SETTINGS | MIN | DEFAULT | МАХ | UNIT | COMMENTS |
|------------------------------------|-------------------|--------------------------|--------|--------------|--|
| Date installed | | | | | |
| Operator | | | | | |
| Front panel trip level (1-9) | 1 | 9 | 9 | | |
| Comment 1 | | | | | |
| Comment 2 | | | | | |
| PARAMETER AND SETTINGS | MIN | DEFAULT | МАХ | UNIT | PROGRAM SELECTION |
| GENERAL | | | | | · |
| System Name | | | | | |
| Description of this unit | | PGR-8800 Arc-Flash Relay | | | |
| Date and Time | | | | | |
| Synchronize to PC clock | | Disabled | | | Enabled Disabled |
| OPTICAL SENSORS | | | | | • |
| Common Settings | | | | | |
| Arc Detection time before tripping | 0 (effective 0.8) | 1 | 20,000 | ms | |
| LED flashes green when above | 50 | 75 | 90 | % Trip Level | |
| Sensor 1 | | | | | |
| Sensor description | | Sensor 1 | | | |
| Ignore sensor check errors | | Disabled | | | Enabled Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |
| Sensor 2 | | | | | · |
| Sensor description | | Sensor 2 | | | |
| Ignore sensor check errors | | Disabled | | | Enabled Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |
| Sensor 3 | | | | | |
| Sensor description | | Sensor 3 | | | |
| Ignore sensor check errors | | Disabled | | | Enabled Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |
| Sensor 4 | | | | | |
| Sensor description | | Sensor 4 | | | |
| Ignore sensor check errors | | Disabled | | | Enabled Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |
| Sensor 5 | | | | | |
| Sensor description | | Sensor 5 | | | |
| Ignore sensor check errors | | Disabled | | | □ Enabled □Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |
| Sensor 6 | | | | | |
| Sensor description | | Sensor 6 | | | |
| Ignore sensor check errors | | Disabled | | | □ Enabled □Disabled |
| Change configuration | | No change | | | No change No sensor expected Sensor expected |



| PARAMETER AND SETTINGS | MIN | DEFAULT | MAX | UNIT | PROGRAM SELECTION |
|---|-----|---|---------|---------------------------------|---|
| Local Sensor | | | | | |
| Sensor Description | | Local Sensor | | | |
| Local sensor causes trip | | Disabled | | | Enabled Disabled |
| CURRENT SENSORS | | | | | |
| Setup | | | | | |
| Rated nominal load current | 5 | 100 | 100,000 | Amperes RMS on CT Primary | |
| CT transformation ratio | 5 | 100 | 100,000 | Ratio x: 5 A RMS | |
| Current sensor mode | | AC | | | AC DC |
| Enable current inhibit | | Disabled | | | Enabled Disabled |
| Trip on Overcurrent 1 | | Disabled | | | Enabled Disabled |
| Trip on Overcurrent 2 | | Disabled | | | Enabled Disabled |
| Trip Inhibit (if enabled) | | | | | |
| Inhibit function disables trips below | 10 | 50 | 1,000 | % | |
| Overcurrent 1 Protection (if enabled) | | | | | |
| Trip on current above | 150 | 150 | 1,000 | % of rated current | |
| Time delay | 1 | 500 | 20,000 | ms | |
| Overcurrent 2 Protection (if enabled) | | | | | |
| Trip on current above | 150 | 150 | 1,000 | % of rated current | |
| Time delay | 1 | 500 | 20,000 | ms | |
| DIGITAL INPUTS | | | | | |
| Inhibit Inputs | | | | | |
| Function | | Inhibit when low (switch closed) | | | Inhibit when low (switch closed) Inhibit when low with circuit check Inhibit when not low (switch open) Disabled |
| Trip Inputs | | | | | |
| Main function | | Trip input | | | Trip input Circuit breaker feedback Disabled |
| Function (with Trip Input main function) | | Trip the output when low (switch closed) | | | Trip the output when low (switch closed) Trip the output when low with circuit check Trip the output when not low (switch open) |
| Function (with circuit breaker feedback) | | CB is closed when low (switch closed) | | | CB is closed when low (switch closed) CB is closed when low with circuit check CB is closed when not low (switch open) |
| Trip on this input can be inhibited | | Disabled | | | Enabled Disabled |
| Reset Inputs | | | | | |
| Function | | Reset when low (switch closed) | | | □ Reset when low (switch closed) □ Reset when low with circuit check □ Reset when not low (switch open) □ Disabled |



| PARAMETER AND SETTINGS | MIN | DEFAULT | МАХ | UNIT | PROGRAM S | ELECTION |
|--|-------|---------------------------------|--------|--------------|--|--------------------------------|
| OUTPUTS | | | | | | |
| Trip Coil Output | | | | | | |
| Circuit breaker type | | Shunt Coil (opens when powered) | | | Shunt Coil (oppowered) Undervoltage when powered) | |
| Circuit breaker pulse time | 1 | 1 | 5 | seconds | | |
| Trip in service mode | | Disabled | | | Enabled | Disabled |
| Report an error if trip coil is not detected | | Enabled | | | Enabled | Disabled |
| Coordinated Tripping | | | | | | |
| Detect clearing failure by trip input | | Disabled | | | Enabled | Disabled |
| Detect clearing failure by current | | Disabled | | | Enabled | Disabled |
| Maximum local circuit breaker clearing time (if Coordinated Tripping is enabled) | 0 | 40 | 500 | ms | | |
| Service Output | | | | | | |
| Service output function | | Indicate service mode | | | Indicate servi Follow trip co Trip upstream on clearing failure | il output i circuit breaker |
| Tripped Output | | | | | | |
| Tripped output function | | Indicate that the unit tripped | | | Indicate that the unit tripped Follow trip coil output Trip upstream circuit breaker on clearing failure | |
| COMMUNICATIONS | | | | | Jee e e e e e e e e e e e | - |
| Link Interface | | | | | | |
| Is used for | | Nothing | | | Nothing Linking multiple units MODBUS | |
| Link Configuration (if enabled) | | | | | | |
| Unit address | 1 | 1 | 4 | Unit address | | |
| Number of linked units in the system | 1 | 1 | 4 | | | |
| Send Link alarm signal on | | Trip | | | Never Light above th Trip Clearing failure | |
| Received Link alarm signal trips this unit | | Enabled | | | □ Enabled | Disabled |
| Link sends and receives the user interface | | Enabled | | | Enabled | Disabled |
| Link sends and receives errors | | Enabled | | | Enabled | Disabled |
| MODBUS Configuration (if enabled) | | | | | | |
| Unit address | 1 | 1 | 247 | Unit address | | |
| Baud rate | 1,200 | 19,200 | 19,200 | | □ 1200 □ 4800 □ 19200 | □2400 □9600 |
| Parity | | Even | | | None Even | □Odd |
| Allows writes via MODBUS | | Disabled | | | Enabled | Disabled |
| ADVANCED | | | | | | |
| Logging | | | | | | |
| Enable data logging | | Disabled | | | Enabled | Disabled |
| Enabled waveform capture (beta) | | Disabled | | | Enabled | Disabled |



| PARAMETER AND SETTINGS | MIN | DEFAULT | MAX | UNIT | PROGRAM S | ELECTION |
|--|-----|----------|-----|------|-----------|----------|
| Internal Drives | | | | | | |
| Reset configuration drive to factory default | | Disabled | | | Enabled | Disabled |
| Reset log drive to factory default | | Disabled | | | Enabled | Disabled |
| Configuration | | | | | | |
| Reset configuration to factory defaults | | Disabled | | | Enabled | Disabled |

NOTES:

¹ Firmware reference 1.03.09.



| PGR-8800 REVISION HISTORY | | | | | | | |
|---------------------------|-----------------|--|-------------------|--|--|--|--|
| MANUAL RELEASE DATE | MANUAL REVISION | HARDWARE REVISION (REVISION NUMBER ON PRODUCT LABEL) | FIRMWARE REVISION | | | | |
| November 29, 2013 | 3-A-112913 | 2.1 | 1.03.11 | | | | |
| December 14, 2012 | 2 | 2 | 1.03.10 | | | | |
| | E | - | 1.03.09 | | | | |

A DDENIDIV E

MANUAL REVISION HISTORY

Revision 3-A-112913

Section 3

Updated power supply information.

Section 4

Updated Figs. 6 and 8.

Section 14

Added EMC test specifications.

Section 15

Updated ordering information.

Appendix B

Updated Modbus database table.

Appendix E

Added revision history.

Revision 2

Significant manual update for most sections. Added UL certification.

HARDWARE REVISION HISTORY

Hardware Revision 2.1

Combines CE and UL conformance in the same PCB revision. No changes in functionality, performance, or components.

Hardware Revision 2

Changed protection components for UL conformance. Added screw fasteners to current sensor inputs.

FIRMWARE REVISION HISTORY

Firmware Revision 1.03.11

Added feature to keep circuit check running and visible when tripping in service mode is selected and USB is inserted.

Firmware Revision 1.03.10

Added Internet Explorer support in event viewer.

Firmware Revision 1.03.09

Removed trip terminal from Link Sharing.