

# 60 A VRPower<sup>®</sup> Integrated Power Stage

## DESCRIPTION

The SiC789 and SiC789A are integrated power stage solutions optimized for synchronous buck applications to offer high current, high efficiency, and high power density performance. Packaged in Vishay's proprietary 6 mm x 6 mm MLP package, SiC789 and SiC789A enable voltage regulator designs to deliver up to 60 A continuous current per phase.

The internal power MOSFETs utilize Vishav's state-of-the-art Gen IV TrenchFET technology that delivers industry benchmark performance to significantly reduce switching and conduction losses.

The SiC789 and SiC789A incorporate an advanced MOSFET gate driver IC that features high current driving capability, adaptive dead-time control, an integrated bootstrap Schottky diode, a thermal warning (THWn) that alerts the system of excessive junction temperature, and skip mode (SMOD#) to improve light load efficiency. The drivers are also compatible with a wide range of PWM controllers and supports tri-state PWM, 3.3 V (SiC789A) / 5 V (SiC789) PWM logic.

# **FEATURES**

diode

 Thermally enhanced PowerPAK<sup>®</sup> MLP66-40L package



• Vishay's Gen IV MOSFET technology and a low-side MOSFET with integrated Schottky

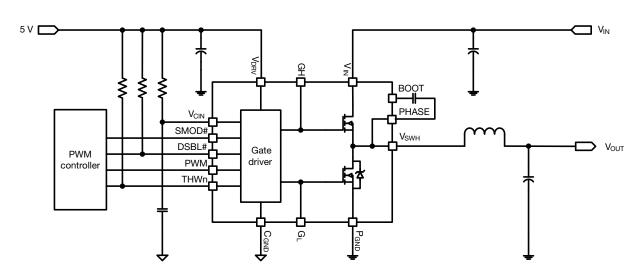


HALOGEN FREE

- Delivers up to 60 A continuous current
- 95 % peak efficiency
- · High frequency operation up to 1.5 MHz
- Power MOSFETs optimized for 12 V input stage
- 3.3 V (SiC789A) / 5 V (SiC789) PWM logic with tri-state and hold-off
- SMOD# logic for light load efficiency improvement
- Low PWM propagation delay (< 20 ns)</li>
- Thermal monitor flag
- Faster enable / disable
- Under voltage lockout for V<sub>CIN</sub>
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912

## APPLICATIONS

• Multi-phase VRDs for CPU, GPU, and memory



# TYPICAL APPLICATION DIAGRAM

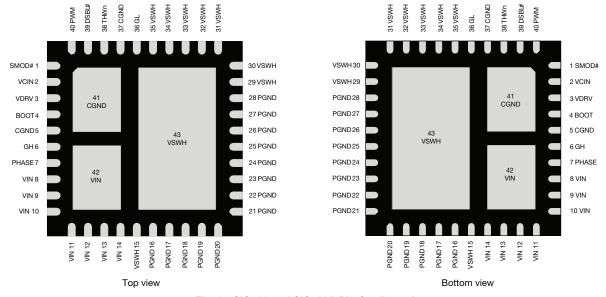
Fig. 1 - SiC789 and SiC789A Typical Application Diagram

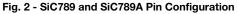
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# **PINOUT CONFIGURATION**





PIN DESCRIPTIO	IN DESCRIPTION				
PIN NUMBER	NAME	FUNCTION			
1	SMOD#	Low-side gate turn-off logic. Active low			
2	V <sub>CIN</sub>	Supply voltage for internal logic circuitry			
3	V <sub>DRV</sub>	Supply voltage for internal gate driver			
4	BOOT	High-side driver bootstrap voltage			
5, 37, 41	C <sub>GND</sub>	Analog ground for the driver IC			
6	GH	High-side gate signal			
7	PHASE	Return path of high-side gate driver			
8 to 14, 42	V <sub>IN</sub>	Power stage input voltage. Drain of high-side MOSFET			
15, 29 to 35, 43	V <sub>SWH</sub>	Switch node of the power stage			
16 to 28	P <sub>GND</sub>	Power ground			
36	GL	Low-side gate signal			
38	THWn	Thermal warning open drain output			
39	DSBL#	Disable pin. Active low			
40	PWM	PWM control input			

ORDERING INFORMATION					
PART NUMBER	PACKAGE	MARKING CODE	OPTION		
SiC789ACD-T1-GE3	PowerPAK <sup>®</sup> MI P66-40I	SiC789A	3.3 V PWM optimized		
SiC789CD-T1-GE3	FOWEIFAK* MILF00-40L	SiC789	5 V PWM optimized		
SiC789ADB and SiC789DB		Reference board			

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ELECTRICAL PARAMETER	CONDITIONS	LIMIT	UNIT	
Input Voltage	V <sub>IN</sub>	-0.3 to +25		
Control Logic Supply Voltage	V <sub>CIN</sub>	-0.3 to +7		
Drive Supply Voltage	V <sub>DRV</sub>	-0.3 to +7		
Switch Node (DC voltage)	N N	-0.3 to +25		
Switch Node (AC voltage) (1)	V <sub>SWH</sub>	-8 to +30	1	
BOOT Voltage (DC voltage)		32	V	
BOOT Voltage (AC voltage) (2)	V <sub>BOOT</sub>	38		
BOOT to PHASE (DC voltage)		-0.3 to +7		
BOOT to PHASE (AC voltage) (3)	VBOOT- PHASE	-0.3 to +8		
All Logic Inputs and Outputs (PWM, DSBL#, and THWn)		-0.3 to V <sub>CIN</sub> + 0.3		
Output Current I (4)	f <sub>S</sub> = 300 kHz, V <sub>IN</sub> = 12 V, V <sub>OUT</sub> = 1.8 V	60	^	
Output Current, I <sub>OUT(AV)</sub> <sup>(4)</sup>	$f_{S} = 1 \text{ MHz}, V_{IN} = 12 \text{ V}, V_{OUT} = 1.8 \text{ V}$	50	- A	
Max. Operating Junction Temperature	TJ	150		
Ambient Temperature	T <sub>A</sub>	-40 to +125	°C	
Storage Temperature	T <sub>stg</sub>	-65 to +150		
	Human body model, JESD22-A114	5000		
Electrostatic Discharge Protection	Charged device model, JESD22-C101	1000	- V	

Note

 $^{(1)}$  The specification values indicated "AC" is V<sub>SWH</sub> to P<sub>GND</sub>, -8 V (< 20 ns, 10 µJ), min. and 30 V (< 50 ns), max.

 $^{(2)}$  The specification value indicates "AC voltage" is V\_{BOOT} to P\_{GND}, 36 V (< 50 ns) max.

<sup>(3)</sup> The specification value indicates "AC voltage" is V<sub>BOOT</sub> to V<sub>PHASE</sub>, 8 V (< 20 ns) max.

<sup>(4)</sup> Output current rated with testing evaluation board at  $T_A = 25$  °C with natural convection cooling. The rating is limited by the peak evaluation board temperature,  $T_J = 150$  °C, and varies depending on the operating conditions and PCB layout. This rating may be changed with different application settings.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING RANGE						
ELECTRICAL PARAMETER	MINIMUM	TYPICAL	MAXIMUM	UNIT		
Input Voltage (V <sub>IN</sub> )	4.5	-	18			
Drive Supply Voltage (V <sub>DRV</sub> )	4.5	5	5.5	v		
Control Logic Supply Voltage (V <sub>CIN</sub> )	4.5	5	5.5	V		
BOOT to PHASE (V <sub>BOOT-PHASE</sub> , DC voltage)	4	4.5	5.5			
Thermal Resistance from Junction to PAD	-	1	-	°C/W		
Thermal Resistance from Junction to Case	-	2.5	-	C/W		

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SiC789, SiC789A

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PARAMETERSYMBOLTEST CONDITIONPOWER SUPPLYControl Logic Supply Current $V_{UCIN}$ $V_{DSBL#} = 5 V, no switching, V_{PVM} = FLOADrive Supply CurrentV_{UCIN}V_{DSBL#} = 5 V, no switching, V_{PVM} = FLOADrive Supply CurrentV_{UCIN}f_S = 300 kHz, D = 0.1f_S = 1 MHz, D = 0.1f_S = 1 MHz, D = 0.1V_{DSBL#} = 5 V, no switchingBOOTSTRAP SUPPLYBootstrap Diode Forward VoltageV_FI_F = 2 mAPWM CONTROL INPUT (SIC399)Rising ThresholdV_{TH, PWM, F}Tri-state Rising ThresholdV_{TH, IP, H, R}Tri-state Rising ThresholdV_{TH, IP, H, R}Tri-state Falling ThresholdV_{HYS, TRL, F}PWM CONTROL INPUT (SIC399)Rising ThresholdV_{TH, IP, MM, F}Tri-state Falling ThresholdV_{TH, IP, R, R}Tri-state Falling ThresholdV_{TH, IP, R, R}PWM CONTROL INPUT (SIC394)Rising ThresholdV_{TH, IP, R, R}Tri-state Falling ThresholdV_{TH, IP, R, R}Tri-state Rising ThresholdV_{TH, IP, R, R}Tr$		LIMITS		
Control Logic Supply Current $V_{VCN}$ $V_{DSBL#} = 6 V$ , no switching, $V_{PVM} = FLOA$ Drive Supply Current $V_{DSBL} = 5 V$ , fs = 300 kHz, D = 0.1 $f_S = 300 kHz, D = 0.1$ Drive Supply Current $V_{DSBL} = 5 V$ , fs = 300 kHz, D = 0.1 $f_S = 1 MHz, D = 0.1$ BOOTSTRAP SUPPLY         Bootstrap Diode Forward Voltage $V_F$ $I_F = 2 mA$ PWM CONTROL INPUT (SiC789)         I         I         Falling Threshold           NTri-state Rising Threshold         VTH_PWM_F         I         I           Tri-state Falling Threshold         VTRI_TH_F         I         I           Tri-state Falling Threshold         VHYS_TRLR         VPWM = FLOAT         I           Hysteresis         VHYS_TRLR         I         I         I           PWM CONTROL INPUT (SiC789A)         I <th>MIN.</th> <th>TYP.</th> <th>MAX.</th> <th></th>	MIN.	TYP.	MAX.	
Control Logic Supply Current $V_{UCIN}$ $V_{DSBL#} = 5 V$ , no switching, $V_{PWM} = FLOA$ Drive Supply Current $V_{DSBL#} = 5 V$ , fs = 300 kHz, D = 0.1fs = 1 MHz, D = 0.1fs = 1 MHz, D = 0.1Mise SUPPLYBootstrap Diode Forward VoltageVFIF = 2 mAPWM CONTROL INPUT (SiC789)Rising ThresholdVTH_PWM, FTri-state Rising ThresholdVTRI_TH_RTri-state Rising ThresholdVHYS_TRILRVPWM CONTROL INPUT (SiC7894)Rising ThresholdVHYS_TRILRTri-state Rising ThresholdVHYS_TRILRVPWM CONTROL INPUT (SiC7894)Rising ThresholdVHYS_TRILRPWM CONTROL INPUT (SiC7894)Rising ThresholdVH_PWM, FTri-state Rising ThresholdVHYS_TRILRPWM CONTROL INPUT (SiC7894)Rising ThresholdVH_PWM, FTri-state Rising ThresholdVH_PWM, FTri-state Rising ThresholdVHYS_TRILRTri-state Rising ThresholdVHYS_TRILRTri-state Rising ThresholdVHYS_TRILRTri-state Rising Threshold <td></td> <td></td> <td></td> <td></td>				
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fs = 300 kHz, D = 0.1Drive Supply Current $V_{DRV}$ $f_S = 1 MHz, D = 0.1$ $V_{DSRL#} = 0 V, no switchingBOOTSTRAP SUPPLYBootstrap Diode Forward VoltageV_FI_F = 2 mAPWM CONTROL INPUT (SIC789)Rising ThresholdV_{TH_LPWM, R}Falling ThresholdV_{TH_LPWM, F}Tri-state VoltageV_{TR}VTRIV_{PWM} = FLOATTri-state Falling ThresholdV_{TH_LPWM, F}Tri-state Falling ThresholdV_{TH_LTH, R}Tri-state Falling ThresholdV_{HYS_TRLR}PWM Ioput CurrentI_{PWM}VPWM = 5 VPWM Ioput CurrentIPWMPWM CONTROL INPUT (SIC789A)Rising ThresholdVTRIVPWM = 5 VVPWM = 0 VPWM CONTROL INPUT (SIC789A)Rising ThresholdVTRIVPWM CONTROL INPUT (SIC789A)$	ΑT -	290	-	μA
Drive Supply Current $I_{VDRV}$ $f_S = 1 \text{ MHz}, D = 0.1$ $V_{DSBL#} = 0 \text{ V, no switching}}$ $V_{DSBL#} = 5 \text{ V, no switching}$ BOOTSTRAP SUPPLYBootstrap Diode Forward Voltage $V_F$ IF = 2 mAPWM CONTROL INPUT (SIC789)Rising Threshold $V_{TH, PWM, F}$ Tri-state Falling Threshold $V_{TH, PWM, F}$ Tri-state Falling Threshold $V_{TH, TH, F}$ Tri-state Falling Threshold $V_{TH, TH, F}$ Tri-state Falling Threshold $V_{HYS, TRL, R}$ Hyper Sign Threshold $V_{HYS, TRL, R}$ Very colspan="2">Very colspan="2"Very colspan="2">Very colspan="2" <td>-</td> <td>295</td> <td>-</td> <td></td>	-	295	-	
Drive Supply Current $V_{VPV}$ $V_{DSBL#} = 0 V, no switching$ Work Vision Supply Constrant of the system of	-	16	25	
HereVorseVorseVorseBOOTSTRAP SUPPLYBootstrap Diode Forward Voltage $V_F$ $I_F = 2 \text{ mA}$ PWM CONTROL INPUT (Sic789)Rising Threshold $V_{TH_PWM_F}$ Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TH_I}$ Vrait $V_{PWM} = FLOAT$ Tri-state Falling Threshold $V_{TH_ITH_R}$ Tri-state Falling Threshold $V_{TH_ITH_F}$ Tri-state Falling Threshold $V_{HYS_TRLF}$ PWM CONTROL INPUT (Sic789A)Rising Threshold $V_{TH_PWM_F}$ Tri-state Falling Threshold $V_{TH_PWM_R}$ PWM CONTROL INPUT (Sic789A)Rising Threshold $V_{TH_PWM_R}$ Falling ThresholdVTRI $V_{PWM} = 5 V$ VPWM CONTROL INPUT (Sic789A)Rising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_R}$ Tri-state Voltage $V_{TH_R}$ Tri-state Voltage $V_{TH_R}$ Tri-state Falling Threshold $V_{TH_R}$ Tri-state Falling Threshold	-	50	-	- mA
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BOOTSTRAP SUPPLY         Bootstrap Diode Forward Voltage $V_F$ $I_F = 2 \text{ mA}$ PWM CONTROL INPUT (SiC789)       Ising Threshold $V_{TL,PWM,R}$ Falling Threshold $V_{TL,PWM,R}$ Ising Threshold         Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Falling Threshold $V_{TRI,TL,R}$ Tri-state Falling Threshold         Tri-state Falling Threshold $V_{HYS,TRLR}$ Tri-state Falling Threshold         Tri-state Falling Threshold $V_{HYS,TRLR}$ VPWM = 5 V         PWM Input Current       IPWM       VPWM = 0 V         PWM CONTROL INPUT (SiC789A)       Ising Threshold       VTH_PWM,R         Falling Threshold       VTH_PWM,R       Ealing Threshold       VTH_PWM,R         Falling Threshold       VTH_PWM,R       Ealing Threshold       VTH_PWM,R         Falling Threshold       VTH_PWM,R       Ealing Threshold       VTH_PWM,R         Tri-state Voltage       VTH,PWM,R       VPWM = 7LOAT       Tri-state Voltage         Tri-state Sing Threshold       VTH_PWM,R       VPWM = 7LOAT       Tri-state Falling Threshold       VTH,PWM,R         Tri-state Rising Threshold       VTH_PWM,R       VPWM = 7LOAT       Tri-state Falling Threshold       VHYS_TRLR       VPWM = 0 V </td <td>-</td> <td>60</td> <td>-</td> <td>μA</td>	-	60	-	μA
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Falling Threshold $V_{TL,PWM,F}$ Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Rising Threshold $V_{TRL,TL,R}$ Tri-state Falling ThresholdTri-state Falling Threshold $V_{TRL,TL,F}$ Tri-state Falling ThresholdHysteresis $V_{HYS,TRL,F}$ VPWM = 5 VPWM Input CurrentIPWM $V_{PWM} = 5 V$ PWM CONTROL INPUT (SiC789A)VHYS_TRLFRising Threshold $V_{TL,PWM,F}$ Tri-state Rising Threshold $V_{TL,PWM,F}$ Tri-state Voltage $V_{TRI}$ Tri-state Voltage $V_{TRI}$ Tri-state Voltage $V_{TRI}$ Tri-state Rising Threshold $V_{TR,TH,R}$ Tri-state Voltage $V_{TRI}$ Tri-state Rising Threshold $V_{TRI,TH,F}$ Tri-state Falling Threshold $V_{TRI,TH,F}$ Tri-state Rising Threshold $V_{TRI,TH,F}$ Tri-state Rising Threshold $V_{HYS,TRL,F}$ PWM Input CurrentIPWMIpwm $V_{PWM} = 3.3 V$ PWM Input CurrentIPWMIpwmVPWM = 0 VThi-State Indel-Off TimetrSHOGH - Turn Off Propagation DelaytpD_OFF_GHGL - Turn Off Propagation DelaytpD_OFF_GLGL - Turn Off Propagation DelaytpD_ON_GLDead time rising)tpD_ON_GLDSBL# Low to GH/GL FallingtpD_ON_				
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Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Rising Threshold $V_{TRL,TL,R}$ Tri-state Falling Threshold $V_{TRL,TL,R}$ Vristeresis $V_{HYS,TRL,R}$ PWM Input Current $V_{HYS,TRL,F}$ PWM Input Current $V_{PWM} = 5 V$ PWM CONTROL INPUT (SiC789A) $V_{PWM,R}$ Rising Threshold $V_{TL,PWM,R}$ Falling Threshold $V_{TRL,TL,R}$ Tri-state Voltage $V_{TRI}$ Vristate Rising Threshold $V_{TRI,TL,R}$ Tri-state Falling Threshold $V_{TRI,TL,R}$ Tri-state Falling Threshold $V_{TRI,TL,R}$ Tri-state Rising Threshold $V_{TRI,TL,R}$ Tri-state Rising Threshold $V_{HYS,TRL,R}$ Tri-state Falling Threshold $V_{HYS,TRL,R}$ PWM Input Current $I_{PWM}$ Verwm = 0.VThistate GH/GL Rising Propagation Delay $t_{PD,OR,GH}$ GH - Turn On Propagation Delay $t_{PD,OR,GH}$ GL - Turn On Propagation Delay $t_{PD,OR,GL}$ CH - Turn On Propagation Delay $t_{PD,OR,GL}$ DSBL# Low to GH/GL Falling $t_{PD,OR,GL}$	0.72	0.9	1.1	1
Tri-state Rising Threshold $V_{TRL_TH_R}$ Tri-state Falling Threshold $V_{TRL_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRL_R}$ Hysteresis $V_{HYS_TRL_F}$ PWM Input Current $I_{PWM}$ PWM CONTROL INPUT (Sic789A)Rising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_R}$ VTH_State Rising Threshold $V_{TRL_TH_R}$ Tri-state Voltage $V_{TRI}$ Vraste Falling Threshold $V_{TRL_TH_R}$ Tri-state Rising Threshold $V_{TRL_TH_R}$ Tri-state Rising Threshold $V_{TRL_TH_R}$ Tri-state Rising Threshold $V_{HYS_TRL_R}$ Tri-state Rising Threshold $V_{HYS_TRL_R}$ PWM Input Current $I_{PWM}$ Verwm = 3.3 VVpWM = 0 VTIMING SPECIFICATIONSTri-state to GH/GL Rising Propagation Delay $t_{PD_TRL_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Tum Off Propagation Delay $t_{PD_ON_GH}$ GL - Tum Off Propagation Delay $t_{PD_ON_GL}$ Call time falling) $t_{PD_ON_GL}$ Dead time falling) $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	2.3	-	v
Tri-state Falling Threshold $V_{TRL_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRL_R}$ Hysteresis $V_{HYS_TRL_F}$ PWM Input CurrentIPWMIPWM $V_{PWM} = 5 V$ PWM CONTROL INPUT (Sic789A) $V_{HYS_TRL_F}$ Rising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TRI}$ VPWM = FLOAT $V_{TRI_SIG_TRL_F}$ Tri-state Rising Threshold $V_{TRL_TH_F}$ Tri-state Rising Threshold $V_{TRL_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRL_F}$ Tri-state Falling Threshold $V_{HYS_TRL_F}$ Tri-state Rising Threshold $V_{HYS_TRL_F}$ PWM Input Current $I_{PWM}$ VPWM = 0 VTMING SPECIFICATIONSTri-State to GH/GL Rising Propagation Delay $t_{PD_TRL_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Tum Off Propagation Delay $t_{PD_ON_rGL}$ Quead time rising) $t_{PD_ON_rGL}$ Quead time rising) $t_{PD_ON_rGL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_rGL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_rGL}$	0.9	1.15	1.38	
Tri-state Rising Threshold Hysteresis $V_{HYS_TRLR}$ Tri-state Falling Threshold Hysteresis $V_{HYS_TRLF}$ PWM Input CurrentIPWMPWM CONTROL INPUT (SiC789A)Rising Threshold $V_{TL,PWM_R}$ Falling Threshold $V_{TL,PWM_F}$ Tri-state Voltage $V_{TRI}$ VPWM = 5 VPristate Falling Threshold $V_{TL,PWM_F}$ Tri-state Voltage $V_{TRI}$ Vristate Falling Threshold $V_{TRL_TH_R}$ Tri-state Rising Threshold $V_{TRL_TH_R}$ Tri-state Falling Threshold $V_{TRL_TH_F}$ Tri-state Falling Threshold $V_{HYS_TRLR}$ PWM Input CurrentIPWMIpwim $V_{PWM} = 3.3 V$ PWM Input CurrentIPWMIpwim $V_{PWM} = 0 V$ Tri-state Falling Threshold $V_{HYS_TRLR}$ PWM Input CurrentIPWMIpwim $V_{PWM} = 0 V$ Tri-state Falling Threshold $V_{HYS_TRLF}$ PWM Input CurrentIPWMIpwim $V_{PWM} = 0 V$ Tri-state Falling Threshold $V_{HYS_TRLF}$ PWM Input CurrentIPWMIpwim $V_{PWM} = 0 V$ Tri-state Hold-Off TimetrshoGH - Turn Off Propagation DelaytpD_OFF_GHGL - Turn Off Propagation DelaytpD_OFF_GLGL - Turn Off Propagation DelaytpD_OFF_GLGL - Turn Off Propagation DelaytpD_OFF_GLDead time falling)tpD_OFF_GLDSBL# Low to GH/GL FallingtpD_OPT_GLThe comuceTop Set Set Set Set Set Set Set Set Set	3.1	3.35	3.6	
Hysteresis $V_{HYS_TRL_R}$ Tri-state Falling Threshold Hysteresis $V_{HYS_TRL_F}$ PWM Input CurrentIpwm $V_{PWM} = 5 V$ $V_{PWM} = 0 V$ PWM CONTROL INPUT (SiC789A)Import CurrentRising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_F}$ Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TRI_TH_R}$ Tri-state Rising Threshold $V_{TRL_TH_R}$ Tri-state Falling Threshold $V_{TRL_TH_F}$ Tri-state Falling Threshold $V_{TRL_TH_F}$ Tri-state Falling Threshold $V_{HYS_TRL_R}$ Tri-state Falling Threshold $V_{HYS_TRL_R}$ PWM Input CurrentIpwmIpwm $V_{PWM} = 3.3 V$ PWM Input CurrentIpmIpwm $V_{PWM} = 0 V$ Thing SPECIFICATIONSTri-state Hold-Off TimeTri-state Hold-Off Timetrp_D_TRL_RGH - Turn Off Propagation DelaytpD_OFF_GHGH - Turn Off Propagation DelaytpD_ON_GHGL - Turn Off Propagation DelaytpD_ON_GHGL - Turn Off Propagation DelaytpD_ON_GLDead time falling)tpD_ON_GLDSBL# Low to GH/GL Fallingtmp_pone_GFig. 5Fig. 5				
Hysteresis $V_{HYS_TRL_F}$ PWM Input CurrentIPWMIPWMVPWM = 5 VPWM CONTROL INPUT (SiC789A)Rising ThresholdVTH_PWM_RFalling ThresholdVTH_PWM_FFalling ThresholdVTH_PWM_FTri-state VoltageVTRIVPWM = FLOATTri-state Rising ThresholdVTRI_TH_RTri-state Falling ThresholdVTRI_TH_FTri-state Falling ThresholdVHYS_TRL_RTri-state Falling ThresholdVHYS_TRL_RTri-state Falling ThresholdVHYS_TRL_FPWM Input CurrentIPWMVPWM = 3.3 VPWM Input CurrentIPWMTri-State to GH/GL Rising Propagation DelaytpD_TRL_RTri-state Hold-Off TimetTSHOGH - Turn Off Propagation DelaytpD_OFF_GHGL - Turn Off Propagation DelaytpD_OFF_GLGL - Turn Off Propagation DelaytpD_ON_GLDSBL# Low to GH/GL Fallingtpp_ON_GLDSBL# Low to GH/GL Fallingtpp_on_GL	-	225	-	mV
PWM Input Current       IPWM       VPWM = 5 V         PWM CONTROL INPUT (SiC789A)       V         Rising Threshold       VTH_PWM_R         Falling Threshold       VTH_PWM_F         Tri-state Voltage       VTRI         VPWM = 5 V         VPWM CONTROL INPUT (SiC789A)         Rising Threshold       VTH_PWM_R         Falling Threshold       VTH_PWM_F         Tri-state Voltage       VTRI         Vpwm = 5 V       V         Tri-state Voltage       VTH_PWM_F         Tri-state Rising Threshold       VTRI_TH_R         Tri-state Falling Threshold       VHYS_TRLR         PVM Input Current       IPWM         VPWM = 0 V       V         Tri-state Falling Threshold       VHYS_TRLF         PWM Input Current       IPWM         VPWM = 0 V       VPWM = 0 V         TIMING SPECIFICATIONS       VPD_OFF_GH         Tri-state Hold-Off Time       trSHO         GH - Turn Off Propagation Delay       tPD_OFF_GH         GL - Turn Off Propagation Delay       tPD_ON_GH         GL - Turn Off Propagation Delay       tPD_ON_GL         GL - Turn Off Propagation Delay       tPD_ON_GL         GL - Turn Off Propagation Delay       tPD_ON_GL	-	325	-	
PWM Input CurrentIIVImage: PWM Control INPUT (SiC789A)Rising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_F}$ Falling Threshold $V_{TRI_PWM_F}$ Tri-state Voltage $V_{TRI}$ VPWM = FLOATTri-state Rising Threshold $V_{TRI_TH_R}$ Tri-state Rising Threshold $V_{TRI_TH_F}$ Tri-state Falling Threshold $V_{HYS_TRI_R}$ PWM Input CurrentIIpwm $V_{PWM} = 3.3 V$ PWM Input CurrentITri-state to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay (Dead time rising) $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay (Dead time rising) $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay (Dead time falling) $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	-	350	
Rising Threshold $V_{TH_PWM_R}$ Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TRI}$ Tri-state Voltage $V_{TRI}$ Tri-state Rising Threshold $V_{TRI_TH_R}$ Tri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRI_R}$ Pri-state Falling Threshold $V_{HYS_TRI_R}$ PWM Input Current $I_{PWM}$ VPWM = 3.3 VPWM Input Current $I_{PWM}$ Tri-State to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ SBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	-	-350	μA
Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Rising Threshold $V_{TRI_TH_R}$ Tri-state Rising ThresholdTri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Rising ThresholdTri-state Rising Threshold $V_{HYS_TRI_R}$ Tri-state Falling ThresholdHysteresis $V_{HYS_TRI_F}$ VPWM = 0.0000000000000000000000000000000000			<u> </u>	
Falling Threshold $V_{TH_PWM_F}$ Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Rising Threshold $V_{TRI_TH_R}$ Tri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Falling Threshold $V_{HYS_TRI_R}$ Tri-state Falling Threshold $V_{HYS_TRI_R}$ PWM Input Current $I_{PWM}$ $V_{PWM} = 3.3 V$ Tri-State to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ SBL# Low to GH/GL Falling $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	2.2	2.45	2.7	
Tri-state Voltage $V_{TRI}$ $V_{PWM} = FLOAT$ Tri-state Rising Threshold $V_{TRI_TH_R}$ Tri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRI_R}$ Hysteresis $V_{HYS_TRI_F}$ PWM Input Current $I_{PWM}$ Tri-State to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ Fig. 5Fig. 5	0.72	0.9	1.1	
Tri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Rising Threshold $V_{HYS_TRI_R}$ Hysteresis $V_{HYS_TRI_F}$ PWM Input Current $V_{HYS_TRI_F}$ PWM Input Current $I_{PWM}$ Tri-State to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay (Dead time rising) $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay (Dead time falling) $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$ Fig. 5	-	1.8	-	V
Tri-state Falling Threshold $V_{TRI_TH_F}$ Tri-state Rising Threshold Hysteresis $V_{HYS_TRI_R}$ Tri-state Falling Threshold Hysteresis $V_{HYS_TRI_F}$ PWM Input Current $I_{PWM}$ PWM Input Current $I_{PWM}$ Tri-State to GH/GL Rising Propagation Delay $t_{PD_TRI_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	0.9	1.15	1.38	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1.95	2.2	2.45	
Tri-state Falling Threshold Hysteresis $V_{HYS_TRL_F}$ PWM Input Current $I_{PWM}$ $V_{PWM} = 3.3 V$ PWM Input Current $I_{PWM}$ $V_{PWM} = 0 V$ TIMING SPECIFICATIONSTri-State to GH/GL Rising Propagation Delay $t_{PD_TRL_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	225	-	
Hysteresis $V_{PWM}$ PWM Input Current $I_{PWM}$ $V_{PWM} = 3.3 V$ PWM Input Current $V_{PWM} = 0 V$ TIMING SPECIFICATIONSTri-State to GH/GL Rising Propagation DelayTri-state Hold-Off Time $t_{PD_TRL,R}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$		075		mV
PWM Input CurrentIPWM $V_{PWM} = 0 V$ TIMING SPECIFICATIONSTri-State to GH/GL Rising Propagation Delay $t_{PD_TRL_R}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GH - Turn On Propagation Delay $t_{PD_ON_GH}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_ON_GH}$ GL - Turn On Propagation Delay $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	275	-	
TimeVPWM = 0 VTIMING SPECIFICATIONSTri-State to GH/GL Rising Propagation Delay $t_{PD_TRLR}$ Tri-state Hold-Off Time $t_{TSHO}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GH - Turn Off Propagation Delay $t_{PD_OFF_GH}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_OFF_GL}$ GL - Turn Off Propagation Delay $t_{PD_ON_GL}$ DSBL# Low to GH/GL Falling $t_{PD_ON_GL}$	-	-	225	μA
Tri-State to GH/GL Rising       tPD_TRI_R         Propagation Delay       tTPD_TRI_R         Tri-state Hold-Off Time       tTSHO         GH - Turn Off Propagation Delay       tPD_OFF_GH         GH - Turn On Propagation Delay       tPD_ON_GH         GL - Turn Off Propagation Delay       tPD_OFF_GL         GL - Turn On Propagation Delay       tPD_ON_GL         DSBL# Low to GH/GL Falling       tap_popure r	-	-	-225	μ. ι
Propagation Delay     IPD_TRI_R       Tri-state Hold-Off Time     tTSHO       GH - Turn Off Propagation Delay     tPD_OFF_GH       GH - Turn On Propagation Delay     tPD_ON_GH       GL - Turn Off Propagation Delay     tPD_OFF_GL       GL - Turn On Propagation Delay     tPD_OFF_GL       GL - Turn On Propagation Delay     tPD_OFF_GL       DSBL + Low to GH/GL Falling     tap_popure		-	1	
GH - Turn Off Propagation Delay     tpD_OFF_GH       GH - Turn On Propagation Delay     tpD_OFF_GH       GL - Turn Off Propagation Delay     tpD_OFF_GL       GL - Turn Off Propagation Delay     tpD_OFF_GL       GL - Turn On Propagation Delay     tpD_OFF_GL       DSBL + Low to GH/GL Falling     tpD_ON_GL	-	30	-	
GH - Turn On Propagation Delay (Dead time rising)     tpD_ON_GH       GL - Turn Off Propagation Delay (Dead time falling)     tpD_OFF_GL       GL - Turn On Propagation Delay (Dead time falling)     tpD_ON_GL	-	130	-	
(Dead time rising)     tPD_ON_GH       GL - Turn Off Propagation Delay     tPD_OFF_GL       GL - Turn On Propagation Delay     tPD_ON_GL       (Dead time falling)     tPD_ON_GL	-	18	-	
GL - Turn Off Propagation Delay     t <sub>PD_OFF_GL</sub> GL - Turn On Propagation Delay (Dead time falling)     t <sub>PD_ON_GL</sub> DSBL# Low to GH/GL Falling     tap_popum_F	-	10	-	
GL - Turn On Propagation Delay (Dead time falling)     tpD_ON_GL       DSBL# Low to GH/GL Falling     tpD_pon_rs	-	12	-	
DSBL# Low to GH/GL Falling	-	10	_	_ ns
Propagation Delay		15	-	1
Propagation Delay     Image: Constraint of the second		20	-	-
PWM Minimum On-Time t <sub>PWM ON MIN</sub>	30	-	<u> </u>	-

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PARAMETER	SYMBOL	TEST CONDITION		LIMITS				
FARAMETER	STWIDOL			TYP.	MAX.			
DSBL# SMOD# INPUT								
DSPL # Logic Input Voltage	V <sub>IH_DSBL#</sub>	Input logic high	2	-	-			
DSBL# Logic Input Voltage	V <sub>IL_DSBL#</sub>	Input logic low	-	-	0.8	v		
	V <sub>IH_SMOD#</sub>	Input logic high	2	-	-	] `		
SMOD# Logic Input Voltage	VIL_SMOD#	Input logic low	-	-	0.8			
PROTECTION								
Under Voltage Lockout	V	V <sub>CIN</sub> rising, on threshold	-	3.7	4.1	v		
Under Voltage Lockout	V <sub>UVLO</sub>	V <sub>CIN</sub> falling, off threshold	2.7	3.1	-	V		
Under Voltage Lockout Hysteresis	V <sub>UVLO_HYST</sub>		-	575	-	mV		
THWn Flag Set <sup>(2)</sup>	T <sub>THWn_SET</sub>		-	160	-			
THWn Flag Clear <sup>(2)</sup>	T <sub>THWn_CLEAR</sub>		-	135	-	°C		
THWn Flag Hysteresis <sup>(2)</sup>	T <sub>THWn_HYST</sub>		-	25	-	1		
THWn Output Low	V <sub>OL THWn</sub>	I <sub>THWn</sub> = 2 mA	-	0.02	-	V		

#### Notes

<sup>(1)</sup> Typical limits are established by characterization and are not production tested.

<sup>(2)</sup> Guaranteed by design.

# **DETAILED OPERATIONAL DESCRIPTION**

#### **PWM Input with Tri-state Function**

The PWM input receives the PWM control signal from the VR controller IC. The PWM input is designed to be compatible with standard controllers using two state logic (H and L) and advanced controllers that incorporate tri-state logic (H, L and tri-state) on the PWM output. For two state logic, the PWM input operates as follows. When PWM is driven above V<sub>PWM TH B</sub> the low-side is turned OFF and the high-side is turned ON. When PWM input is driven below VPWM TH F the high-side is turned OFF and the low-side is turned ON. For tri-state logic, the PWM input operates as previously stated for driving the MOSFETs when PWM is logic high and logic low. However, there is a third state that is entered as the PWM output of tri-state compatible controller enters its high impedance state during shut-down. The high impedance state of the controller's PWM output allows the SiC789 and SiC789A to pull the PWM input into the tri-state region (see definition of PWM logic and Tri-State, fig. 4). If the PWM input stays in this region for the Tri-state Hold-Off Period, t<sub>TSHO</sub>, both high-side and low-side MOSFETs are turned OFF. The function allows the VR phase to be disabled without negative output voltage swing caused by inductor ringing and saves a Schottky diode clamp. The PWM and tri-state regions are separated by hysteresis to prevent false triggering. The SiC789A incorporates PWM voltage thresholds that are compatible with 3.3 V logic and the SiC789 thresholds are compatible with 5 V logic.

## Disable (DSBL#)

In the low state, the DSBL# pin shuts down the driver IC and disables both high-side and low-side MOSFETs. In this state, standby current is minimized. If DSBL# is left unconnected, an internal pull-down resistor will pull the pin to  $C_{GND}$  and shut down the IC.

## **Pre-Charger Function**

When DSBL# is driven from below  $V_{IL_DSBL#}$  to above  $V_{IH_DSBL#}$  the low-side is turned ON for a short duration (60 ns typical) to refresh the BOOT capacitor in case it has been discharged due to the driver being in standby for a long period of time.

## Diode Emulation Mode (SMOD#)

When SMOD# is logic low diode emulation mode is enabled and the low-side is turned OFF. This is a non-synchronous conversion mode that improves light load efficiency by reducing switching losses. Conducted losses that occur in synchronous buck regulators when inductor current is negative can also be reduced. Circuitry in the external controller IC detects when inductor current crosses zero and drives SMOD# below  $V_{IL_SMOD#}$  turning the low-side MOSFET OFF. The function can be also be used for a pre-biased output voltage. If SMOD# is left unconnected, an internal pull up resistor will pull the pin to  $V_{CIN}$  (logic high) to disable the SMOD# function.

## Thermal Shutdown Warning (THWn)

The THWn pin is an open drain signal that flags the presence of excessive junction temperature. Connect, with a maximum of 20 k $\Omega$ , to V<sub>CIN</sub>. An internal temperature sensor detects the junction temperature. The temperature threshold is 160 °C. When this junction temperature is exceeded the THWn flag is set. When the junction temperature drops below 135 °C the device will clear the THWn signal. The SiC789 and SiC789A do not stop operation when the flag is set. The decision to shutdown must be made by an external thermal control function.

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# **Vishay Siliconix**

## Voltage Input (VIN)

This is the power input to the drain of the high-side power MOSFET. This pin is connected to the high power intermediate BUS rail.

## Switch Node (V<sub>SWH</sub> and PHASE)

The switch node,  $V_{SWH}$ , is the circuit power stage output. This is the output applied to the power inductor and output filter to deliver the output for the buck converter. The PHASE pin is internally connected to the switch node,  $V_{SWH}$ . This pin is to be used exclusively as the return pin for the BOOT capacitor. A 20 k $\Omega$  resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET in the event that  $V_{CIN}$  goes to zero while  $V_{IN}$  is still applied.

## Ground Connections (C<sub>GND</sub> and P<sub>GND</sub>)

 $\mathsf{P}_{\mathsf{GND}}$  (power ground) should be externally connected to  $\mathsf{C}_{\mathsf{GND}}$  (control signal ground). The layout of the printed circuit board should be such that the inductance separating  $\mathsf{C}_{\mathsf{GND}}$  and  $\mathsf{P}_{\mathsf{GND}}$  is minimized. Transient differences due to inductance effects between these two pins should not exceed 0.5 V

## Control and Drive Supply Voltage Input (V<sub>DRV</sub>, V<sub>CIN</sub>)

 $V_{\text{CIN}}$  is the bias supply for the gate drive control IC.  $V_{\text{DRV}}$  is the bias supply for the gate drivers. It is recommended to separate these pins through a resistor. This creates a low pass filtering effect to avoid coupling of high frequency gate drive noise into the IC.

# Bootstrap Circuit (BOOT)

The internal bootstrap diode and an external bootstrap capacitor form a charge pump that supplies voltage to the BOOT pin. An integrated bootstrap diode is incorporated so that only an external capacitor is necessary to complete the bootstrap circuit. Connect a boot strap capacitor with one leg tied to BOOT pin and the other tied to PHASE pin.

#### **Shoot-Through Protection and Adaptive Dead Time**

The SiC789 and SiC789A have an internal adaptive logic to avoid shoot through and optimize dead time. The shoot through protection ensures that both high-side and low-side MOSFETs are not turned ON at the same time. The adaptive dead time control operates as follows. The high-side and low-side gate voltages are monitored to prevent the MOSFET turning ON from tuning ON until the other MOSFET's gate voltage is sufficiently low (< 1 V). Built in delays also ensure that one power MOSFET is completely OFF, before the other can be turned ON. This feature helps to adjust dead time as gate transitions change with respect to output current and temperature.

#### Under Voltage Lockout (UVLO)

During the start up cycle, the UVLO disables the gate drive, holding high-side and low-side MOSFET gates low, until the supply voltage rail has reached a point at which the logic circuitry can be safely activated. The SiC789 and SiC789A also incorporate logic to clamp the gate drive signals to zero when the UVLO falling edge triggers the shutdown of the device. As an added precaution, a 20 k $\Omega$  resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET.

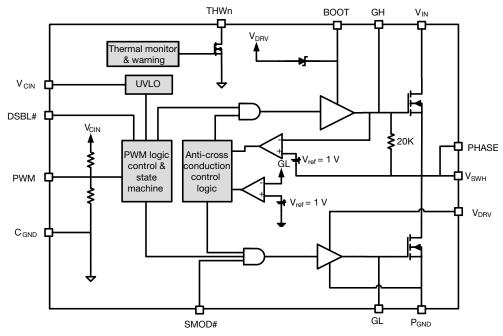


Fig. 3 - SiC789 and SiC789A Functional Block Diagram

# FUNCTIONAL BLOCK DIAGRAM



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DEVICE TRUTH TABLE						
DSBL#	SMOD#	PWM	GH	GL		
Open	Х	Х	L	L		
L	Х	Х	L	L		
Н	L	L	L	L		
Н	L	Н	Н	L		
Н	L	Tri-state	L	L		
Н	Н	L	L	Н		
Н	Н	Н	Н	L		
Н	Н	Tri-state	L	L		

# **PWM TIMING DIAGRAM**

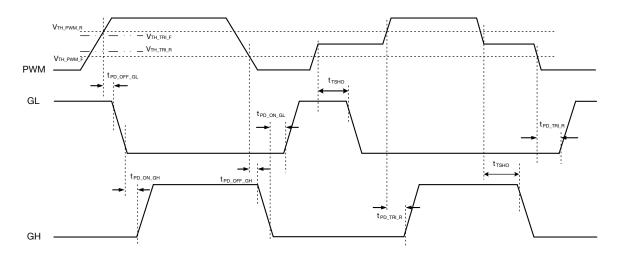
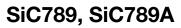
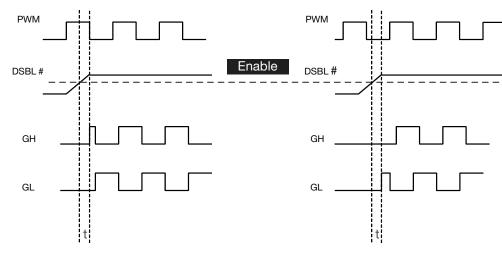


Fig. 4 - Definition of PWM Logic and Tri-State



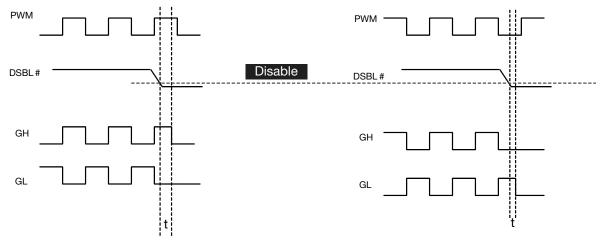


# **OPERATION TIMING DIAGRAM: DSBL#**



DSBL# High to GH Rising Propagation Delay





DSBL# Low to GH Falling Propagation Delay

DSBL# Low to GL Falling Propagation Delay

Fig. 5 - DSBL# Propagation Delay

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# SiC789, SiC789A

MHz

500 kHz

40 45

 $V_{OUT} = 0.7 V$ 

V<sub>OUT</sub> = 0.8 V

 $V_{OUT} = 0.9 V$ 

 $V_{OUT} = 1.0 V$ 

40 45 50 55

I MHz

PCB Temperature, T<sub>PCB</sub> (°C)

Fig. 11 - Safe Operating Area

800 kHz

30 35

Output Current, I<sub>OUT</sub> (A)

f<sub>s</sub> = 500 kHz

30 35

Output Current, I<sub>OUT</sub> (A)

15

20 25

10

10 15 20 25

30 45 60 75 90

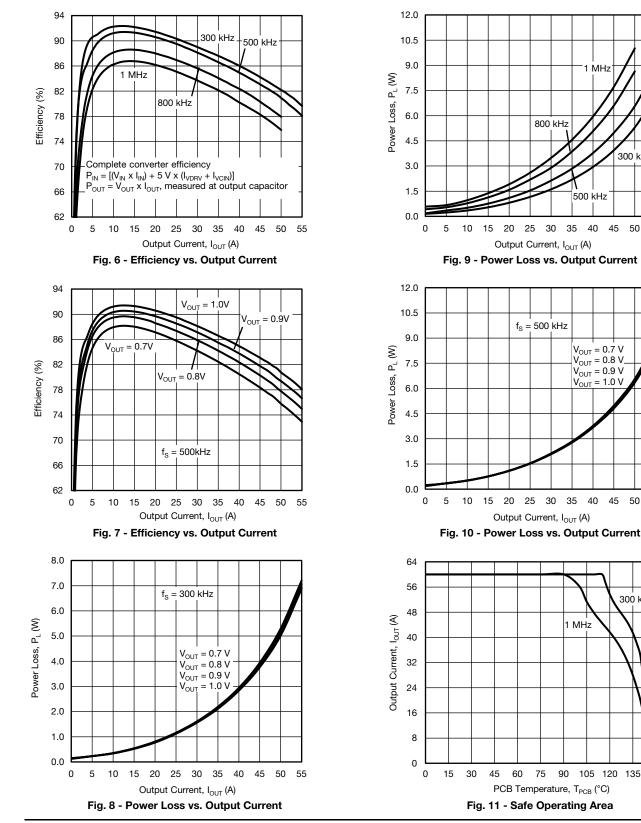
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300 kHz

50 55

# **ELECTRICAL CHARACTERISTICS**

Test condition: V<sub>IN</sub> = 12 V, V<sub>DRV</sub> = V<sub>CIN</sub> = 5 V, DSBL# = SMOD# = 5 V, V<sub>OUT</sub> = 1 V, L<sub>OUT</sub> = 270 nH (DCR = 0.32 mΩ), T<sub>A</sub> = 25 °C (All power loss and normalized power loss curves show SiC789 and SiC789A losses only unless otherwise stated)



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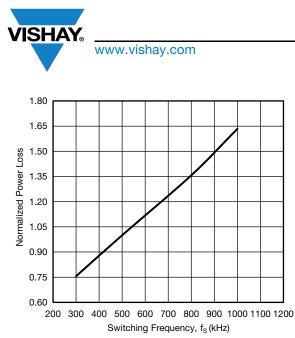
Document Number: 62972

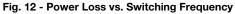
105 120 135 150

300 kHz

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SiC789, SiC789A





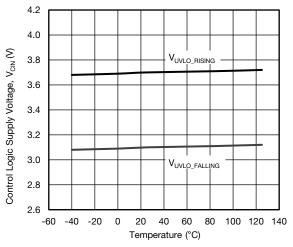


Fig. 13 - UVLO Threshold vs. Temperature

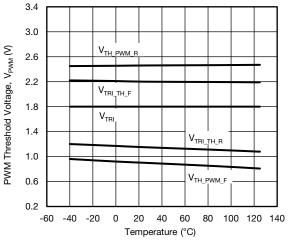


Fig. 14 - PWM Threshold vs. Temperature (SiC789A)

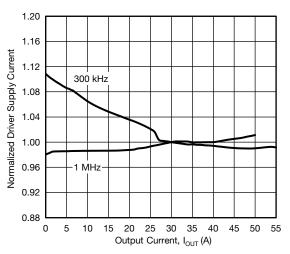


Fig. 15 - Driver Supply Current vs. Output Current

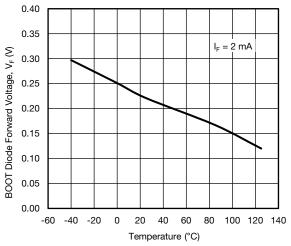


Fig. 16 - BOOT Diode Forward Voltage vs. Temperature

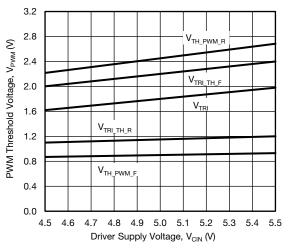


Fig. 17 - PWM Threshold vs. Driver Supply Voltage (SiC789A)

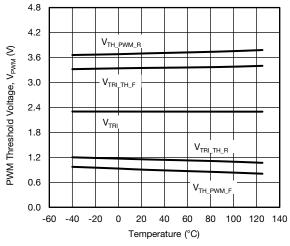
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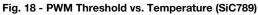
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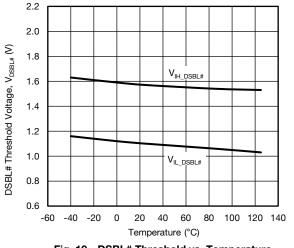
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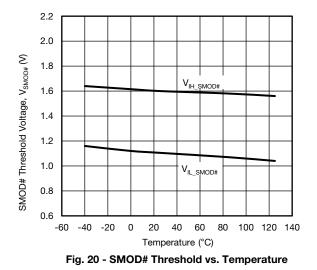
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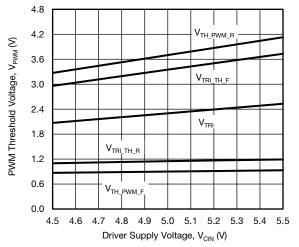


Fig. 21 - PWM Threshold vs. Driver Supply Voltage (SiC789)

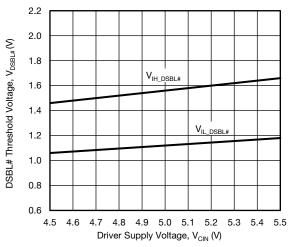


Fig. 22 - DSBL# Threshold vs. Driver Supply Voltage

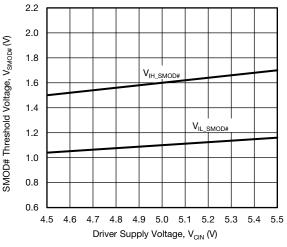


Fig. 23 - SMOD# Threshold vs. Driver Supply Voltage

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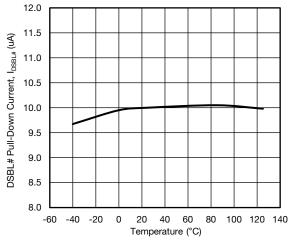


Fig. 24 - DSBL# Pull-down Current vs. Temperature

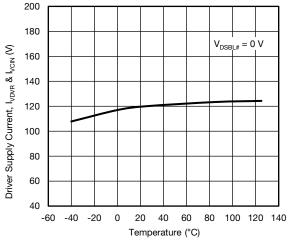


Fig. 25 - Driver Shutdown Current vs. Temperature

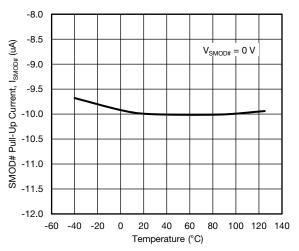


Fig. 26 - SMOD# Pull-up Current vs. Temperature

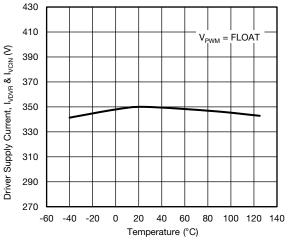


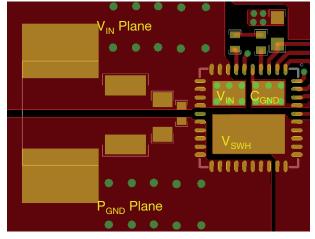
Fig. 27 - Driver Quiescent Current vs. Temperature

12

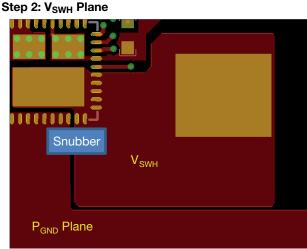


# PCB LAYOUT RECOMMENDATIONS

## Step 1: V<sub>IN</sub> / P<sub>GND</sub> Planes and Decoupling

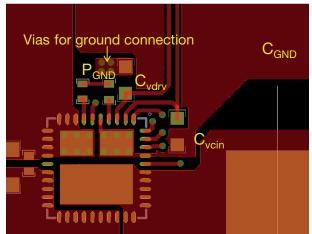


- 1. Layout  $V_{IN}$  and  $P_{GND}$  planes as shown above
- 2. Ceramic capacitors should be placed directly between VIN and PGND, and as close as possible to IC for best decoupling effect
- 3. Different ceramic capacitor values and packages should be used to cover entire decoupling spectrum, e.g. 1210, 0805, 0603, and 0402
- 4. Smaller capacitance values, placed closer to the IC's VIN pin(s), result in better high frequency noise absorbing



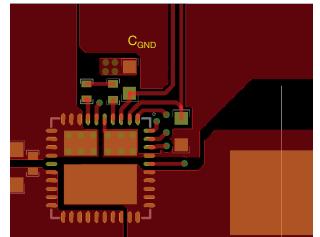
- 1. Connect output inductor to IC with large plane to lower resistance
- 2. V<sub>SWH</sub> plane also serves as a heat-sink for low-side MOSFET. Please make the plane wide and short to achieve best thermal path
- 3. If a snubber network is required, place components as shown above

## Step 3: V<sub>CIN</sub> / V<sub>DRV</sub> Input Filter



- 1.  $V_{\text{CIN}}$  /  $V_{\text{DRV}}$  input filter ceramic capacitors should be placed as close as possible to IC. It is recommended to connect two capacitors separately
- 2. V<sub>CIN</sub> capacitor should be placed between pin 2 and pin 37 (C<sub>GND</sub> of driver IC) to achieve best noise filtering
- 3. V<sub>DRV</sub> capacitor should be placed between pin 3 and P<sub>GND</sub> to provide maximum instantaneous driver current for low-side MOSFET during switching cycle. PGND can be connected to inner ground plane through vias, as shown above
- 4. Pin 5 and pin 37 should be connected with CGND pad, as shown above
- 5. For connecting  $V_{CIN}$  to  $C_{GND}$ , it is recommended to use a large plane to reduce parasitic inductance

## Step 4: BOOT Resistor and Capacitor Placement



- 1. The components need to be placed as close as possible to IC, directly between PHASE (pin 7) and BOOT (pin 4)
- 2. To reduce parasitic inductance, 0402 package size can be used

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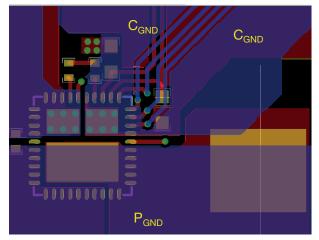
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## Step 5: Signal Routing



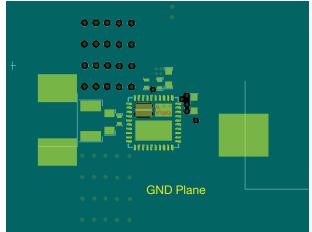
- 1. Route the PWM, SMOD#, DSBL#, and THWn signal traces out of the top right corner, next to pin 1
- 2. The PWM signal is a very important signal, both signal and return traces should not cross any power nodes on any layer
- 3. It is best to "shield" these traces from power switching nodes, e.g.  $V_{\rm SWH},$  with a GND island to improve signal integrity

# V<sub>IN</sub> Plane

Step 6: Adding Thermal Relief Vias

- 1. Thermal relief vias can be added to the  $V_{\text{IN}}$  and  $C_{\text{GND}}$  pads to utilize inner layers for high-current and thermal dissipation
- 2. To achieve better thermal performance, additional vias can be added to  $V_{\text{IN}}$  and  $P_{\text{GND}}$  planes
- 3. The  $V_{\text{SWH}}$  pad is a noise source and it is not recommended to place vias on this pad
- 4. 8 mil drill for pads and 10 mils drill for planes are the optional via sizes. Vias on pad may drain solder during assembly and cause assembly issues. Please consult with the assembly house for guidelines

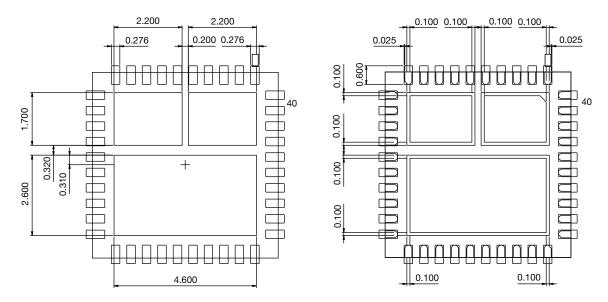
# Step 7: Ground Connection



- 1. It is recommended to make the entire first inner layer (below top layer) the ground plane
- 2. The ground plane provides analog ground and power ground connections
- 3. The ground plane provides shielding between noise source on top layer and signal traces on bottom layer

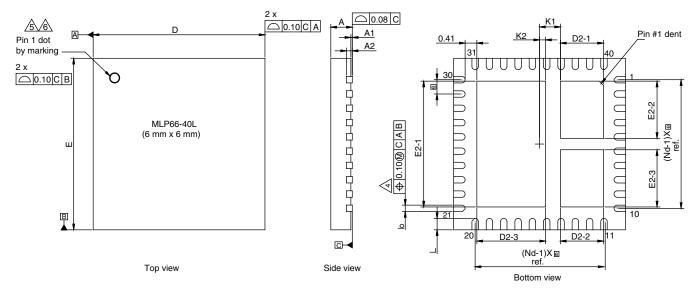


# **RECOMMENDED LAND PATTERN PowerPAK® MLP66-40L** in millimeters





# PACKAGE OUTLINE DRAWING MLP66-40L

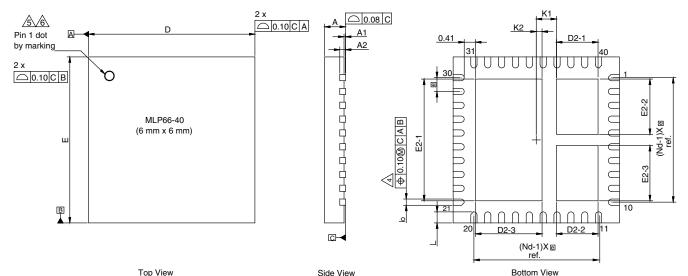


DIM.		MILLIMETERS			INCHES		
DIM.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
А	0.70	0.75	0.80	0.027	0.029	0.031	
A1	0.00	-	0.05	0.000	-	0.002	
A2		0.20 ref.			0.008 ref.		
b	0.20	0.25	0.30	0.078	0.098	0.011	
D		6.00 BSC			0.236 BSC		
е		0.50 BSC			0.019 BSC		
E		6.00 BSC			0.236 BSC		
L	0.35	0.40	0.45	0.013	0.015	0.017	
Ν	40		40				
Nd		10		10			
Ne		10			10		
D2-1	1.45	1.50	1.55	0.057	0.059	0.061	
D2-2	1.45	1.50	1.55	0.057	0.059	0.061	
D2-3	2.35	2.40	2.45	0.095	0.094	0.096	
E2-1	4.35	4.40	4.45	0.171	0.173	0.175	
E2-2	1.95	2.00	2.05	0.076	0.078	0.080	
E2-3	1.95	2.00	2.05	0.076	0.078	0.080	
K1		0.73 BSC			0.028 BSC		
K2		0.21 BSC			0.008 BSC		

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# PowerPAK<sup>®</sup> MLP66-40 Case Outline



DIM.	MILLIMETERS			INCHES		
Diwi.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A <sup>(8)</sup>	0.70	0.75	0.80	0.027	0.029	0.031
A1	0.00	-	0.05	0.000	-	0.002
A2		0.20 ref.			0.008 ref.	
b <sup>(4)</sup>	0.20	0.25	0.30	0.078	0.098	0.011
D		6.00 BSC			0.236 BSC	
е		0.50 BSC			0.019 BSC	
E		6.00 BSC			0.236 BSC	
L	0.35	0.40	0.45	0.013	0.015	0.017
N <sup>(3)</sup>		40 40		40	<b>.</b>	
Nd <sup>(3)</sup>		10		10		
Ne <sup>(3)</sup>		10		10		
D2-1	1.45	1.50	1.55	0.057	0.059	0.061
D2-2	1.45	1.50	1.55	0.057	0.059	0.061
D2-3	2.35	2.40	2.45	0.095	0.094	0.096
E2-1	4.35	4.40	4.45	0.171	0.173	0.175
E2-2	1.95	2.00	2.05	0.076	0.078	0.080
E2-3	1.95	2.00	2.05	0.076	0.078	0.080
K1		0.73 BSC			0.028 BSC	
K2	0.21 BSC 0.008 BSC					

Notes

1. Use millimeters as the primary measurement

2. Dimensioning and tolerances conform to ASME Y14.5M. - 1994

3. N is the number of terminals. Nd is the number of terminals in X-direction and Ne is the number of terminals in Y-direction

 $\Delta$ Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip

🛕 The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body

A Exact shape and size of this feature is optional

7. Package warpage max. 0.08 mm

Applied only for terminals

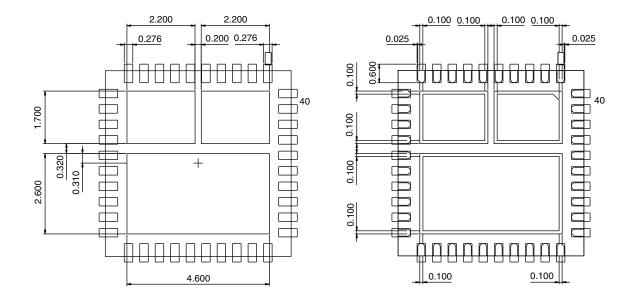
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# **Recommended Land Pattern PowerPAK® MLP66-40L**



All Dimensions are in milimeters



Vishay

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Please note that some Vishay documentation may still make reference to RoHS Directive 2002/95/EC. We confirm that all the products identified as being compliant to Directive 2002/95/EC conform to Directive 2011/65/EU.

Vishay Intertechnology, Inc. hereby certifies that all its products that are identified as Halogen-Free follow Halogen-Free requirements as per JEDEC JS709A standards. Please note that some Vishay documentation may still make reference to the IEC 61249-2-21 definition. We confirm that all the products identified as being compliant to IEC 61249-2-21 conform to JEDEC JS709A standards.