

# **[TLC5943](http://focus.ti.com/docs/prod/folders/print/tlc5943.html)**

# **16-Channel, 16-Bit PWM LED Driver with 7-Bit Global Brightness Control**

## **<sup>1</sup>FEATURES**

- **23 16 Channels, Constant Current Sink Output – LED Open Detection (LOD)**
- **50-mA Capability (Constant Current Sink) – Thermal Error Flag (TEF)**
- • **16-Bit (65,536 Steps) Grayscale Control with** • **Noise Reduction: Enhanced Spectrum (ES) PWM –**
- **7-Bit (128 Steps) Global Brightness Control for current All Channels with Sink Current**
- •**LED Power-Supply Voltage up to 17 V**
- • $V_{CC}$  = 3.0 V to 5.5 V
- - **– Channel-to-Channel <sup>=</sup> ±1.5%**
	- **– Device-to-Device <sup>=</sup> ±3%**
- •**CMOS Level I/O**
- •**30-MHz Data Transfer Rate**
- **33-MHz Grayscale Control Clock**
- •
- •**Auto Data Refresh**
- • **Continuous Base LED Open Detection (LOD):**
	- Detect LED opening and LED short to GND
- - **– Automatic shutdown at high temperature conditions**
	- **– Restart under normal temperature**
- **Readable Error Information:**
	-
	-
- - **4-channel grouped delay to prevent inrush**
- •**Operating Temperature: –40**°**C to +85**°**C**

## **APPLICATIONS**

- **Constant Current Accuracy: Monochrome, Multicolor, Full-Color LED Displays**
	- •**LED Signboards**
	- **Display Backlighting**

# **DESCRIPTION**

The TLC5943 is <sup>a</sup> 16-channel, constant current sink **Auto Display Repeat depart of the contract of the contract** 65,536 enhanced spectrum pulse-width modulated (PWM) steps controlled by grayscale (GS) data. All output drivers are adjustable with 128 constant sink **betable** current steps at same value controlled by brightness **during display during display control (BC)** data. Both GS data and BC data are **Thermal Shutdown (TSD):** writable via a serial interface port. The maximum current value of all 16 channels can be set by <sup>a</sup> single external resistor.





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# **DESCRIPTION, CONTINUED**

The TLC5943 has two error detection circuits for LED open detection (LOD) and <sup>a</sup> thermal error flag (TEF). LOD detects a broken or disconnected LED and shorted LED to GND during the display period. TEF indicates an over-temperature condition; when <sup>a</sup> TEF is set, all output drivers are turned off. When the TEF is cleared, all output drivers are restarted.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.





(1) For the most current package and ordering information see the Package Option Addendum at the end of this document, or see the TI web site at [www.ti.com](http://www.ti.com).

## **ABSOLUTE MAXIMUM RATINGS(1)(2)**

Over operating free-air temperature range, unless otherwise noted.



(1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not supported.

(2) All voltage values are with respect to network ground terminal.

# **RECOMMENDED OPERATING CONDITIONS**

At  $T_A$ = -40°C to +85°C, unless otherwise noted.



#### **DISSIPATION RATINGS**



(1) With PowerPAD soldered onto copper area on printed circuit board (PCB); 2 oz. copper. For more information, see [SLMA002](http://focus.ti.com/general/docs/techdocsabstract.tsp?abstractName=slma002a) (available for download at [www.ti.com](http://www.ti.com)).

(2) With PowerPAD not soldered onto copper area on PCB.

(3) The package thermal impedance is calculated in accordance with JESD51-5.

# **ELECTRICAL CHARACTERISTICS**

At V<sub>CC</sub> = 3.0 V to 5.5 V, and T<sub>A</sub> = -40°C to +85°C. Typical values at V<sub>CC</sub> = 3.3 V and T<sub>A</sub> = +25°C, unless otherwise noted.



(1) The deviation of each output from the average of OUT0–OUT15 constant current. Deviation is calculated by the formula:

$$
\Delta (%) = \left[ \frac{I_{\text{OUTD}}}{\frac{(I_{\text{OUTD}} + I_{\text{OUT1}} + ... + I_{\text{OUT15}})}{16}} - 1 \right] \times 100
$$

. (2) The deviation of the OUT0–OUT15 constant current average from the ideal constant current value. Deviation is calculated by the following formula:

$$
\Delta (\%) = \left(\frac{\frac{(\text{I}_{\text{OUT0}} + \text{I}_{\text{OUT1}} + \dots \text{I}_{\text{OUT14}} + \text{I}_{\text{OUT15}})}{16} - (\text{Ideal Output Current})}{\text{Ideal Output Current}}\right) \times 100
$$
\nIdeal current is calculated by the formula:

\n
$$
\frac{\text{I}_{\text{total}}}{\text{Total Output Current}} = \frac{\text{I}_{\text{total}}}{\text{Total Output Current}}
$$

$$
I_{\text{OUT(IDEAL)}} = 41 \times \left[ \frac{1.20}{R_{\text{IREF}}} \right]
$$

(3) Line regulation is calculated by this equation:

$$
\Delta ( \% / V) = \left\{ \frac{(I_{\text{OUTn}} \text{ at } V_{\text{CC}} = 5.5 \text{ V}) - (I_{\text{OUTn}} \text{ at } V_{\text{CC}} = 3.0 \text{ V})}{(I_{\text{OUTn}} \text{ at } V_{\text{CC}} = 3.0 \text{ V})} \right\} \times \frac{100}{5.5 \text{ V} - 3 \text{ V}}
$$

(4) Load regulation is calculated by the equation:

$$
\Delta ( \%N) = \left( \frac{ (I_{\text{OUTn}} \text{ at } V_{\text{OUTn}} = 3 \text{ V}) - (I_{\text{OUTn}} \text{ at } V_{\text{OUTn}} = 1 \text{ V}) }{(I_{\text{OUTn}} \text{ at } V_{\text{OUTn}} = 1 \text{ V})} \right) \times \frac{100}{3 \text{ V} - 1 \text{ V}}
$$

(5) Not tested. Specified by design.

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## **SWITCHING CHARACTERISTICS**

At V<sub>CC</sub> = 3.0 V to 5.5 V, T<sub>A</sub> = –40°C to +85°C, C<sub>L</sub> = 15 pF, R<sub>L</sub> = 82 Ω, R<sub>IREF</sub> = 1 kΩ, and V<sub>LED</sub> = 5.0 V. Typical values at  $V_{CC}$  = 3.3 V and T<sub>A</sub> = +25°C, unless otherwise noted.



(1) Output on-time error is calculated by the following formula:  $T_{ON\_ERR}$  (ns) =  $t_{OUTON} - T_{GSCLK}$ .  $t_{OUTON}$  is the actual on-time of the constant current driver.  $T_{GSCLK}$  is the period of GSCLK.



**FUNCTIONAL BLOCK DIAGRAM**





## **DEVICE INFORMATION**







#### **TERMINAL FUNCTIONS**





## **PARAMETER MEASUREMENT INFORMATION**

### **PIN EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS**



**Figure 1. SIN, SCLK, XLAT, BCSEL, BLANK, GSCLK Figure 2. SOUT**



### **TEST CIRCUITS**



(1) C<sup>L</sup> includes measurement probe and jig (1) C<sup>L</sup> includes measurement probe and jig capacitance.<br>
Figure 5. Rise Time and Fall Time Test Circuit for OUTn Figure 6. Rise T



(1) C<sub>L</sub> includes measurement probe and jig capacitance.

**Figure 7. Rise Time and Fall Time Test Circuit for XERR**





**Figure 3. XERR Figure 4. OUT0 Through OUT15**



Figure 6. Rise Time and Fall Time Test Circuit for SOUT



**Figure 8. Constant Current Test Circuit for OUTn**

#### **TIMING DIAGRAMS**



(1) Input pulse rise and fall time is 1 ns to 3 ns.

**Figure 9. Input Timing**



- (1) Input pulse rise and fall time is 1 ns to 3 ns.
- (2) Input pulse high level is  $V_{CC}$  and low level is GND.

#### **Figure 10. Output Timing**

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SID are entered in the GS shift register at the first rising edge of SCLK after XLAT goes low. The SID readout consists of the saved LOD result at the 33rd GSCLK rising edge in the previous display period and the TEF data after the previous TEF data readout.



# **TYPICAL CHARACTERISTICS**

At  $V_{CC}$  = 3.3 V and  $T_A$  = +25°C, unless otherwise noted.

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# **TYPICAL CHARACTERISTICS (continued)**

At  $V_{CC}$  = 3.3 V and  $T_A$  = +25°C, unless otherwise noted.



## **DETAILED DESCRIPTION**

#### **Setting for the Maximum Constant Sink Current Value**

On the TLC5943, the maximum constant current sink value for each channel,  $I_{\text{OLCMax}}$ , is determined by an external resistor,  $R_{IREF}$ , placed between the IREF and GND pins. The  $R_{IREF}$  resistor value is calculated with Equation 1:

$$
R_{IREF} (k\Omega) = \frac{V_{IREF} (V)}{I_{OLCMax} (mA)} \times 41
$$

(1)

Where:

•  $V_{IREF}$  = the internal reference voltage on the IREF pin (typically 1.20 V)

 $I_{OLCMax}$  is the largest current for all outputs. Each output sinks the  $I_{OLCMax}$  current when it is turned on and the brightness control data are set to the maximum value of 7Fh (127d). The sink current for each output can be reduced by lowering the brightness control data.

RIREF must be between 984  $\Omega$  (typ) and 9.84 k $\Omega$  (typ) in order to keep I<sub>OLCMax</sub> between 5 mA and 50 mA. The output may become unstable when I<sub>OLCMax</sub> is set lower than 5 mA. However, output currents lower than 5 mA can be achieved by setting  $I_{OLCMax}$  to 5 mA or higher, and then using brightness control to lower the output current.

[Figure](#page-12-0) 14 in the Typical Characteristics and Table 1 show the characteristics of the constant sink current versus the external resistor,  $R_{IREF}$ .



#### **Table 1. Maximum Constant Current Output versus External Resistor Value**

## **Brightness Control (BC) Function**

The TLC5943 is able to adjust the output current of all channels (OUT0 to OUT15). This function is called *brightness control* (BC). The BC function allows users to adjust the global brightness of LEDs connected to the outputs OUT0 to OUT15. All channel output currents can be adjusted in 128 steps from 0% to 100% of the maximum output current, I<sub>OLCMax</sub>. The brightness control data are entered into the TLC5943 via the serial interface.

Equation 2 determines the sink current for each output (OUTn):

$$
I_{\text{OUTn}} \text{ (mA)} = I_{\text{OLCMax}} \text{ (mA)} \times \left(\frac{\text{BCn}}{127d}\right)
$$

Where:

- $I_{\text{OLCMax}}$  = the maximum channel current for each channel determined by  $R_{\text{IREF}}$
- BCn <sup>=</sup> the programmed brightness control value for OUTn (BCn <sup>=</sup> 0 to 127d)

When the IC is powered on, the data in the Brightness Control Shift Register and data latch 1 and 2 are not set to any default values. Therefore, BC data must be written to the BC latch 1 and 2 before turning on the constant current output.

Table 2 summarizes the BC data versus current ratio and set current value.

#### **Table 2. BC Data versus Current Ratio and Set Current Value**



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(2)

#### **Grayscale (GS) Function (Enhanced Spectrum PWM Operation)**

The TLC5943 has an enhanced spectrum pulse-width modulation (ES PWM) function. In this PWM control, the total display period is divided to 128 display segments. *Total display period* means the timing from the first grayscale clock (GSCLK) input to the 65,536th grayscale clock input after BLANK goes low. Each display period has 512 grayscale as <sup>a</sup> maximum. The driver (OUTn) on time changes depending on the 16-bit grayscale data. Refer to Table 3 for sequence information and [Figure](#page-17-0) 23 for timing information.





<span id="page-17-0"></span>



**Figure 23. PWM Operation Timing**

<span id="page-18-0"></span>

When the IC powers on, the data in the Grayscale Shift Register and latch 1/2 are not set to any default value. Therefore, grayscale data must be written to the Grayscale latch before turning on the constant current output. Additionally, BLANK should be high when the device turns on, to prevent the outputs from turning on before the proper grayscale and brightness control values can be written. All constant current outputs are always off when BLANK is high. Equation 3 determines each output (OUTn) total on time  $(t_{\text{OUTON}})$ :

 $t_{\text{OUTON}}$  (ns) = T<sub>GSCLK</sub> (ns) × GSn (3)

Where:

- • $T_{GSCLK}$  = the period of GSCLK
- • $GSn =$  the programmed grayscale value for OUTn  $(GSn = 0$  to 65,535d)

Table 4 summarizes the GS data versus OUTn on duty and on time.



#### **Table 4. GS Data versus OUTn Total On Duty**

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### **Auto Display Repeat Function**

This function can repeat the total display period without a BLANK signal as long as GSCLK is input as Figure 24 shows. This function can be switched on or off by the data of bit 7 in the first latch of the Brightness Control. When bit 7 is '1', Auto Repeat is enabled and the entire display period repeats without <sup>a</sup> BLANK signal. When bit 7 is '0', Auto Repeat is disabled and the entire display period executes only one time after the falling edge of BLANK.



**Figure 24. Auto Repeat Display Function Timing**



#### **Auto Data Refresh Function**

This function allows users to input Grayscale (GS) data or Brightness Control (BC) data any time without synchronizing the input to the BLANK signal. If GS data or BC data are input during <sup>a</sup> display period, the input data are held in the first latch for each data register. Data are then transferred to the second latch when the 65,536th GSCLK occurs. The second latch data are used for the next display period. Figure 25 through [Figure](#page-22-0) 27 show the timing.

However, when the high level signal of BLANK occurs before the 65,536th GSCLK, then the first latch data upload to the second latch immediately. Also, when the XLAT rising edge inputs while BLANK is at <sup>a</sup> high level, then the selected shift register data are transferred to the first and second latch at the same time. Bit 7 data of BC update immediately whenever the data are written into the first latch.



If there is no BLANK input when Auto Repeat is enabled.









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**Figure 27. Auto Refresh Data Function Timing 3**

## **Grayscale (GS) Shift Register and Data Latch**

The Grayscale (GS) Shift Register and data latch 1 and 2 are each 256 bits in length, and set the PWM timing for each constant current driver. See [Table](#page-18-0) 4 for the ON time duty of each GS data bit. Figure 28 shows the shift register and latch configuration. Refer to [Figure](#page-10-0) 11 for the timing diagram for writing data into the GS shift register and latch.

The driver on time is controlled by the data in the GS second data latch. GS data can be set into the latch by the rising edge of XLAT with BCSEL <sup>=</sup> low after writing data into the GS shift register with SIN and GSCLK with BCSEL = low. A BCSEL level change occurs during SCLK = low, and after 100 ns from the rising edge of XLAT. When the device powers up, the data in the GS shift register and latches are not set to any default value. Therefore, GS data must be written to the GS latch before turning on the constant current output. Also, BLANK should be at <sup>a</sup> high level when powering on the device, because the constant current may be turned on as well. All constant current output is off when BLANK is at <sup>a</sup> high level.



**Figure 28. Grayscale Shift Register and Data Latch Configuration**

## **Brightness Control (BC) Shift Register and Data Latch**

The Brightness Control (BC) data shift register and the first latch are each 8 bits long; the second latch is 7 bits long. The lower 7 bits in the latch are used to adjust the constant current value for all channels of the constant current driver. The MSB of the first latch is used for the auto repeat mode setting. Table 5 shows the ratio of setting the current value against the maximum current value for each BC data point. Figure 29 shows the shift register and latch configuration for BC data. [Figure](#page-11-0) 12 shows the timing for writing data.

The driver constant current value is controlled by the data in the second BC data latch. BC data can be set into the latch at the rising edge of XLAT with BCSEL = high after writing the data into the BC Shift Register by SIN and SCLK with BCSEL <sup>=</sup> high. A BCSEL level change occurs during SCLK <sup>=</sup> low and after 100 ns from the rising edge of XLAT. When powered up, the data in the BC Shift Register and latches are not set to any default value. Therefore, brightness data must be written to the BC latch before turning on the constant current output.









#### **Status Information Data (SID)**

Status information data (SID) are 17-bit, read-only data. Both the LED open detection (LOD) error and the thermal error flag (TEF) are shifted out onto the SOUT pin with each rising edge of the shift clock, SCLK. The 16 LOD bits for each channel and the TEF bit are written into the 17 most significant bits of the Grayscale Shift Register at the rising edge of the first SCLK after XLAT goes low. As <sup>a</sup> result, the previous data in the 17 most significant bits are lost at the same time. No data are loaded into the other 175 bits. Figure 30 shows the bit assignments. [Figure](#page-11-0) 13 illustrates the read timing for the status information data.



**Figure 30. Status Information Data Configuration**

The LOD data update at the rising edge of the 33rd GSCLK pulse after BLANK goes low; the LOD data are retained until the next 33rd GSCLK. LOD data are only checked for outputs that are turned on during the rising edge of the 33rd GSCLK pulse. A '1' in an LOD bit indicates an open LED or short LED to GND condition for the corresponding channel. A '0' indicates normal operation. LOD shows <sup>a</sup> '0' even if the LED is open or shorted to GND when the grayscale data are less than 1000h (4096d). Therefore, grayscale data must be greater than 1001h (4097d) to correctly receive LOD data.

The TEF bit indicates that the IC temperature is too high. The flag also indicates that the IC has turned off all drivers to avoid damage by overheating the device. A '1' in the TEF bit means that the IC temperature has exceeded the detect temperature threshold  $(T_{(TEF)})$  and the driver is turned off. A '0' in the TEF bit indicates normal operating temperature conditions. The IC automatically turns the drivers back on when the IC temperature decreases to less than  $T_{(TEF)} - T_{(HYS)}$ . When the IC powers on, LOD data do not show correct values. Therefore, LOD data must be read from the 33rd GSCLK pulse input after BLANK goes low. Table 6 shows a truth table for both LOD and TEF.







### **Noise Reduction**

Large surge currents may flow through the IC and the printed circuit board (PCB) on which the device is mounted if all 16 LED channels turn on simultaneously at the start of each grayscale cycle. These large current surges could introduce detrimental noise and electromagnetic interference (EMI) into other circuits. The TLC5943 turns on the LED channels in <sup>a</sup> series delay to provide <sup>a</sup> circuit soft-start feature. The output current sinks are grouped into four groups of four channels each. The first group is OUT0,4,8,12; the second group is OUT1,5,9,13; the third group is OUT2,6,10,14; and the fourth group is OUT3,7,11,15. Each group is turns on sequentially with <sup>a</sup> small delay between groups; see [Figure](#page-10-0) 11. Both turn-on and turn-off are delayed.

### **Continuous Base LED Open Detection**

When the 33rd GSCLK goes high in the first display period after <sup>a</sup> BLANK falling edge, the LED open detection (LOD) circuit checks the voltage of each constant current output (OUT0 through OUT15 <sup>=</sup> OUTn) that is turned on to detect open LEDs and short LEDs to GND. Then, if the voltage of OUTn is less than the LED open detection threshold (V<sub>LOD</sub> = 0.3 V<sub>TYP</sub>), it sets '1' as the error flag to the LOD error bit that corresponds with the error channel in the Status Information Data (SID) register. Also, the XERR pin level moves from Hi-Z at the same time. As <sup>a</sup> result, GS data should be over 1001h (4097d) to get the LOD result. The OUTn channel that has the detected LOD error is forced off to avoid an increase in the  $V_{CC}$  supply current. OUTn turns on at the first GSCLK after <sup>a</sup> BLANK falling edge again. LOD data are kept until the next 33rd rising edge of GSCLK in the first display period after <sup>a</sup> BLANK falling edge. LOD is always '0' when grayscale data are less than 1001h (4097d). XERR is forced to <sup>a</sup> Hi-Z state while BLANK is high. When powered up, LOD data are not set to any default value. Therefore, SID data must be used after OUTn turns on with over 1001h GS data. Figure 31 shows the LED Open Detection timing.



**Figure 31. LED Open Detection (LOD) Timing**



### **Auto Output Off**

If the active OUTn channel is not connected to an LED or if LED is shorted to GND, then  $V_{CC}$  consumption current increases. In order to avoid this event, the device has an auto output off function. This function turns off channel OUTn with <sup>a</sup> detected LED opening or LED shorting to GND at the 33rd GSCLK after BLANK goes low automatically. V<sub>CC</sub> current can be saved by this function. OUTn is controlled normally again after BLANK goes low. Figure 32 illustrates the auto output off function.



**Figure 32. Auto Output Off Function**

**[TLC5943](http://focus.ti.com/docs/prod/folders/print/tlc5943.html)**

#### **Thermal Shutdown and Thermal Error Flag**

The Thermal Shutdown (TSD) function turns off all of the constant current outputs on the IC immediately when the junction temperature (T<sub>J</sub>) exceeds the threshold (T<sub>(TEF)</sub> = +162°C, typ) and sets the thermal error flag (TEF) to '1'. The XERR pin goes low at the same time. The XERR pin level and the TEF level are kept until the first SCLK falling edge after an XLAT falling edge of grayscale data. Then if T<sub>J</sub> is still greater than T<sub>(TEF)</sub>, TEF continues at '1' while XERR remains low. If T<sub>J</sub> becomes less than T<sub>(TEF)</sub> –T<sub>(HYS)</sub>, TEF is set to '0' and XERR becomes Hi-Z. XERR is not forced to <sup>a</sup> Hi-Z state while BLANK is high. Therefore, the error type TEF or LOD can be distinguished from the BLANK signal control. OUTn is turned on at the first GSCLK after the BLANK falling edge if T<sub>J</sub> becomes less than  $T_{(TEF)} - T_{(HYS)}$  at the BLANK rising edge.

When the IC powers on, TEF may be set and all output is forced off. Therefore, an XLAT pulse and <sup>a</sup> BLANK rising edge should be input once to turn on the output. Figure 33 illustrates the TEF/TSD/XERR timing sequence.



**Figure 33. TEF/TSD/XERR timing**

## **POWER DISSIPATION CALCULATION**

The device power dissipation must be below the power dissipation rate of the device package (illustrated in [Figure](#page-12-0) 15) to ensure correct operation. Equation 4 calculates the power dissipation of the device:

$$
P_D = (V_{CC} \times I_{CC}) + \left(V_{OUT} \times I_{MAX} \times N \times \frac{BCn}{127d} \times d_{PWM}\right)
$$

Where:

• $V_{\text{CC}}$  = device supply voltage

 $\epsilon$ 

- • $I_{CC}$  = device supply current
- • $V_{\text{OUT}}$  = OUTn voltage when driving LED current
- • $I_{MAX}$  = LED current adjusted by  $R_{(IREF)}$  resistor
- •BCn <sup>=</sup> maximum BC value for OUTn
- • $N =$  number of OUTn driving LED at the same time
- • $d_{PWM}$  = duty ratio defined by BLANK pin or GS PWM value

(4)



## **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

**(3)** MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.



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**(4)** Only one of markings shown within the brackets will appear on the physical device.

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# **PACKAGE MATERIALS INFORMATION**

Texas<br>Instruments

## **TAPE AND REEL INFORMATION**





# **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





TEXAS<br>INSTRUMENTS

# **PACKAGE MATERIALS INFORMATION**

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\*All dimensions are nominal



PWP (R-PDSO-G28)

PowerPAD<sup>™</sup> PLASTIC SMALL OUTLINE



All linear dimensions are in millimeters. NOTES: A.

- This drawing is subject to change without notice. В.
- Body dimensions do not include mold flash or protrusions. Mold flash and protrusion shall not exceed 0.15 per side. C.
- This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad D. Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding<br>recommended board layout. This document is available at www.ti.com <http://www.ti.com>.<br>E. See the additional figure in the Pro
	-
- E. Falls within JEDEC MO-153

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#### THERMAL INFORMATION

This PowerPAD<sup>TM</sup> package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively,<br>can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating<br>abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: A. All linear dimensions are in millimeters  $\sqrt{B}$ . Exposed tie strap features may not be present.

PowerPAD is a trademark of Texas Instruments





NOTES:

- $A_{-}$ All linear dimensions are in millimeters.
- **B.** This drawing is subject to change without notice.
- Customers should place a note on the circuit board fabrication drawing not to alter the center C. solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets.
- E. For specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil
- F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.





NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

B. This drawing is subject to change without notice.

C. QFN (Quad Flatpack No-Lead) Package configuration.

D. The package thermal pad must be soldered to the board for thermal and mechanical performance.

E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

F. Falls within JEDEC MO-220.



# RHB (S-PVQFN-N32)

# PLASTIC QUAD FLATPACK NO-LEAD

#### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



#### NOTE: A. All linear dimensions are in millimeters



# RHB (S-PVQFN-N32)

# PLASTIC QUAD FLATPACK NO-LEAD



All linear dimensions are in millimeters. NOTES: А.

- This drawing is subject to change without notice. **B.**
- Publication IPC-7351 is recommended for alternate designs. C.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



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