

General Description

8V97051 is a high performance Wideband RF Synthesizer optimized for use as the local oscillator (LO) in Multi-Carrier, Multi-mode FDD & TDD Base Station radio card. It is offered in a compact 5x5, 32-VFQFN package with 50 Ω differential RF output impedances for ease of integration into the receiver or transmitter lineup.

The 8V97051 Wideband RF synthesizer offers a default Fractional Mode with the option to use it with an Integer mode. It requires an external loop filter.

The 8V97051 with integrated voltage Controlled Oscillator (VCO) supports output frequencies from 34.375MHz to 4400MHz and maintains superior phase noise and spurious performance.

RF_OUT_[A:B] output drivers have independently programmable output power ranging from -4dBm to +7dBm. The RF_OUT outputs can be muted. The mute function is accessible via a SPI command or mute pin.

The operation of 8V97051 is controlled by writing to registers through a 3-wire SPI interface. 8V97051 also has an additional option that allows users to read back values from registers by configuring the MUX_OUT pin as a SDO for the SPI interface. The SPI interface is compatible with 1.8V logic and tolerant to 3.3V.

In multi-service base stations, very low noise oscillators are required to generate a large variety of frequencies to the mixers while maintaining excellent phase noise performance and low power. The 8V97051 offers a large tuning range capable of providing multiband local oscillator (LO) frequency synthesis in multi-mode base stations, thus limiting the use of multiple narrow band RF Synthesizers and reducing the BOM complexity and cost. The device can operate over -40°C to +85°C industrial temperature range.

Applications

- Wireless Infrastructure
- Test Equipment
- CATV Equipment
- Military and Aerospace
- Wireless LAN
- Clock Generation

Features

- Dual Differential Outputs
- Output frequency range: 34.375MHz to 4400MHz (continuous range)
- RF Output Divide by 1, 2, 4, 8, 16, 32, 64
- Open Drain Outputs (see [Output Distribution Section](#))
- Fractional-N synthesizer (also supports Integer-N mode)
- 16-bit integer and 12-bit fractional (16-bit fractional when using the extended registers)
- 3- or 4-wire SPI interface (compatible with 3.3V and 1.8V)
- Single 3.3V supply
- Logic compatibility: 1.8V
- Programmable output power level: -4dBm to +5dBm (up to +7 when using the extended registers)
- Mute Function
- Ultra low PN for 1.1GHz LO: -143dBc/Hz @ 1MHz Offset, (typical)
- Lock Detect Indicators
- Input Reference frequency: 5MHz to 310MHz
- Power Consumption: 380mW (typical) (RF_OUT_B disabled)
- 32-Lead, 5x5 VFQFN package
- Autocal feature for band select
- Pin Compatible with ADF4350, ADF4351, MAX2870
- -40°C to +85°C ambient operating temperature
- Lead-free (RoHS 6) packaging

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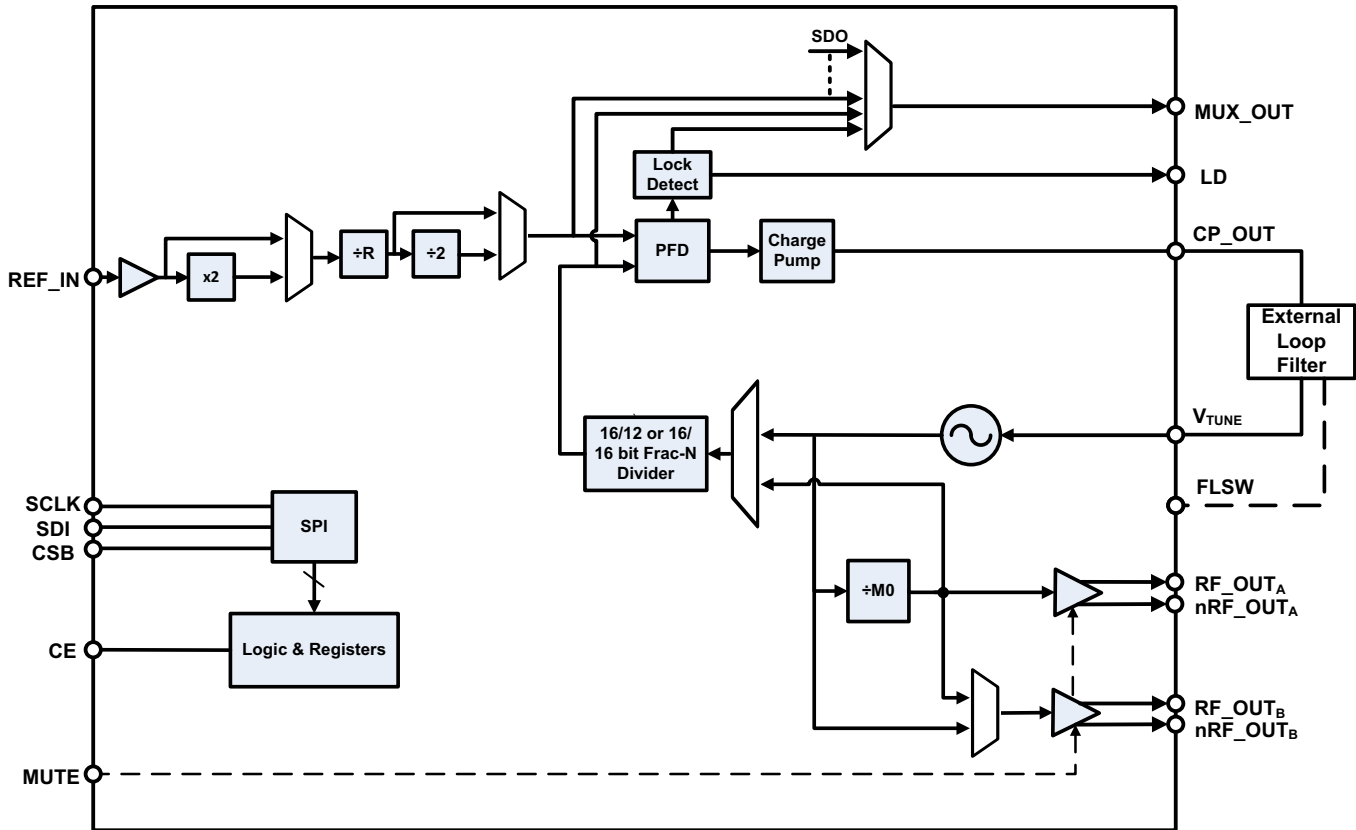
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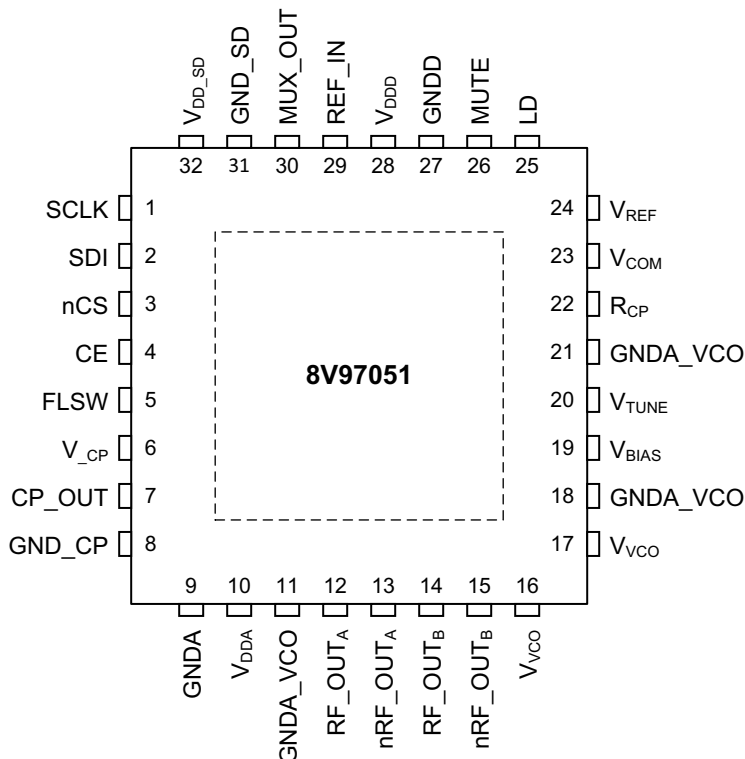
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8V97051 Block Diagram



NOTE: 16-Bit Integer / 16-Bit Fractional feedback divider is available when using extended register.

Pin Assignment



32-Lead 5mm x 5mm VFQFN

Pin Description and Characteristic Tables

Table 1. Pin Description¹

Pin	Name	Type		Description
1	SCLK	LVC MOS Input	Pulldown	Serial Clock Input. High-Impedance CMOS input. 1.8V logic. 3.3V tolerant.
2	SDI	LVC MOS Input	Pullup	Serial Data Input. High-Impedance CMOS input. 1.8V logic. 3.3V tolerant.
3	nCS	LVC MOS Input	Pulldown	Load Enable. High-Impedance CMOS input. 1.8V logic. 3.3V tolerant. Active Low.
4	CE	LVC MOS Input	Pullup	Chip Enable. Powers down the device on logic Low, with charge pump put into a High-Impedance mode. Powers up the device on logic High.
5	FLSW	Analog		Fast Lock Switch. A connection should be made from the loop filter to this pin when using the fast lock mode.
6	V _{CP}	Power		Charge Pump Power Supply. V _{CP} must have the same value as V _{DDA} . Place decoupling capacitors to the ground plane as close to this pin as possible.
7	CP_OUT	Analog		Charge Pump Output. When enabled, this output provides ±ICP to the external loop filter. The output of the loop filter is connected to VTUNE to drive the internal VCO.
8	GND_CP	Ground		Charge Pump Power Supply Ground.
9	GNDA	Ground		Analog Power Supply Ground.
10	V _{DDA}	Power		Analog Supply. This pin ranges from 3.3V ± 5%. V _{DDA} must have the same value as V _{DD} .
11	GNDA_VCO	Ground		VCO Analog Power Supply Ground.
12	RF_OUT _A	Output		Clock Output pair A. The output level is programmable.
13	nRF_OUT _A	Output		Clock Output pair A. The output level is programmable.
14	RF_OUT _B	Output		Clock Output pair B. The output level is programmable.
15	nRF_OUT _B	Output		Clock Output pair B. The output level is programmable.
16	V _{VCO}	Power		VCO Supply. This pin ranges from 3.3V ± 5%. V _{VCO} must have the same value as V _{DDA} .
17	V _{VCO}	Power		VCO Supply. This pin ranges from 3.3V ± 5%. V _{VCO} must have the same value as V _{DDA} .
18	GNDA_VCO	Ground		VCO Analog Power Supply Ground.
19	V _{BIAS}	Analog		Place decoupling capacitors (≥0.1μF) to ground, as close to this pin as possible.
20	V _{TUNE}			Control Input to tune the VCO.
21	GNDA_VCO	Ground		VCO Analog Power Supply Ground.
22	R _{CP}	Analog		Sets the charge pump current.Requires External Register.
23	V _{COM}	Analog		Place decoupling capacitors (≥0.1μF) to ground, as close to this pin as possible.
24	V _{REF}	Analog		Place decoupling capacitors (≥0.1μF) to ground, as close to this pin as possible.
25	LD	LVC MOS Output		Lock Detect. LD High indicates PLL lock. LD low indicates loss of PLL lock.

Table 1. Pin Description¹ (Continued)

26	MUTE	LVC MOS Input	Pullup	RF_OUT _A and RF_OUT _B Power-Down. A logic low on this pin mutes the RF_OUT outputs and puts them in High-Impedance. This function is also SPI controllable and in this case also allows the power down of either RF_OUT _A or RF_OUT _B .
27	GNDD	Ground		Digital Power Supply Ground.
28	V _{DDD}	Power		Digital Supply. V _{DDD} must have the same value as V _{DDA} .
29	REF_IN	LVC MOS Input	Analog	Reference Input. This CMOS input has a nominal threshold of V _{DDA} /2 and a DC equivalent input resistance of 100k Ω . This input can be driven from a TTL or CMOS crystal oscillator, or it can be AC-coupled.
30	MUX_OUT	LVC MOS Output		Multiplexed Output and Serial Data Out. Refer to Table 4C, Page 14 .
31	GND_SD	Ground		Digital Σ - Δ Modulator Power Supply Ground.
32	V _{DD_SD}	Power		Digital Σ - Δ Modulator Supply. V _{DD_SD} must have the same value as V _{DDA} .
EP	Exposed Pad	Ground		Must be connected to GND.

NOTE 1. *Pullup* and *Pulldown* refer to internal input resistors. See [Table 2, Pin Characteristics](#), for typical values.

Table 2. Pin Characteristics

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
C _{in}	Input Capacitance			4		pF
R _{OUT}	LVC MOS Output Impedance	MUX_OUT & LD		38		Ω
R _{PULLUP}	Input Pullup Resistor			51		k Ω
R _{PULLDOWN}	Input Pulldown Resistor			51		k Ω

Table 3. V_{DD} and Associated Current Return Paths

Power Pin	Pin Name	GND_RT Pin	GND_RT Pin Name
10	V _{DDA}	9	GNDA
28	V _{DDD}	27	GNDD
32	V _{DD_SD}	31	GND_SD
16, 17	V _{VCO}	11, 18, 21	GNDA_VCO
6	V _{CP}	8	GND_CP

Principles of Operation

Synthesizer Programming

The Fractional-N architecture is implemented via a cascaded programmable dual modulus prescaler. The N divider offers a division ratio in the feedback path of the PLL, and is given by programming the value of INT, FRAC and MOD in the following equation:

$$N = \text{INT} + \text{FRAC}/\text{MOD} \quad (1)$$

INT is the divide ratio of the binary 16-bits counter (refer to [Table 5B](#), [Page 18](#)).

FRAC is the numerator value of the fractional divide ratio. It is programmable from 0 to (MOD – 1). Refer to [Table 5C](#) when in 12-bit mode, or [Table 12J](#) when in 16-bit mode.

MOD is the preset fractional 12-bit modulus. It is programmable from 2 to 4095. Refer to [Table 6D](#) when in 12-bit mode, or [Table 12I](#) when in 16-bit mode.

The **VCO** frequency (f_{VCO}) at RF_OUT_A or RF_OUT_B is given by the following equation:

$$f_{\text{VCO}} = f_{\text{PFD}} \times (\text{INT} + \text{FRAC}/\text{MOD}) \quad (2)$$

f_{PFD} is the frequency at the input of the Phase and Frequency Detector (PFD), which is equal to the input reference frequency divided by the value programmed in the 10-bit input reference divider (R).

The user would need to factor in the Divide by 2 and the multiply by 2 available for the input stage if they are used.

The 8V97051 offers an Integer mode. To enable that mode, the user has to program the FRAC value to 0.

The device's VCO features three VCO band-splits to cover the entire range with sufficient margin for process, voltage, and temperature. These are automatically selected by invoking the Autocal feature. The charge pump current is also programmable via the ICP SETTING register for maximum flexibility.

In addition, one can select RF_OUT_A, RF_OUT_B, both outputs, and standby mode via the Register 4.

Reference Input Stage

The 8V97051 features one single-ended reference clock input (REF_IN). This single-ended input can be driven by an ac-coupled sine wave or square wave.

In Power Down mode this input is set to High-Impedance to prevent loading of the reference source.

The reference input signal path also includes an optional doubler.

Reference Doubler

To improve the phase noise performance of the device, the reference doubler can be used. By using the doubler, the PFD frequency is also doubled and the phase noise performance typically improves by 3dB. When operating the device in Fractional mode, the speed of the $\Sigma\Delta$ modulator of the N counter is limited to 125MHz, which is also the maximum PFD frequency that can be used in the fractional mode. When the part operates in Integer-N mode, the PFD frequency is limited to 310MHz.

The user has the possibility to select a higher PFD frequency (up to 310MHz in Integer mode) by doing the following steps using the extended registers (Register 6 and 7):

1. The user needs to increase the size of the Band Select Clock Divider (normally 8-bits) by setting the bit [D6:D3] in the Register 6 to divide down to a frequency lower than 500kHz and higher than 125kHz.
2. Use the Bit[D27:D26] to increase the lock detect precision for the faster PFD frequency.

The Lock Detect window should be set as large as possible but less than a period of the phase detector. The phase detector frequency should be greater than 500kHz.

Table 4A. Lock Detect Precision (LDP)

LDP_Ext2 (D27 of Register 6)	LDP_Ext1 (D26 of Register 6)	LDP (D7 of Register 2)	LDP value (ns)
0	0	0	10
0	0	1	6
Use of Extended Register 6			
0	1	0	3
0	1	1	3
1	0	0	4
1	0	1	4.5
1	1	0	1.5
1	1	1	1.5

Feedback Divider

The feedback divider N supports fractional division capability in the PLL feedback path. It consists in an integer N divider of 16-bits, and a Fractional divider of 12-bits (FRAC) over 12-bits (MOD). FRAC and MOD can be extended to 16-bits when using extended registers.

To select an integer mode only, the user sets FRAC to 0.

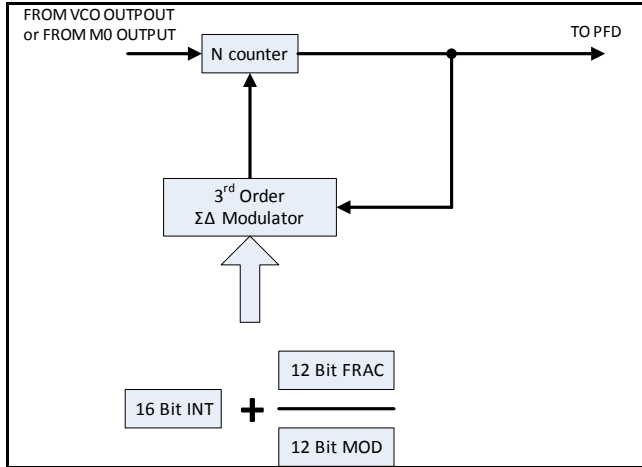


Figure 1. RF Feedback N Divider

The 16 INT bits (Bit[D30:D15] in Register 0) set the integer part of the feedback division ratio.

The 12 FRAC bits (Bit[D14:D3] in Register 0) set the numerator of the fraction that goes into the Σ - Δ modulator. FRAC can be extended to 16-bits using the EXT_FRAC bits in Register 7.

The 12 MOD bits (Bit[D14:D3] in Register 1) set the denominator of the fraction that goes into the Σ - Δ modulator.

Both register values as well as the R Counter determine the output frequency of the device according to the relation (2). The VCO frequencies can therefore separated by the programmed fractional ratio $(1/\text{MOD}) * f_{\text{PFD}}$.

FRAC values from 0 to $(\text{MOD} - 1)$ cover channels over a frequency range equal to the PFD reference frequency.

The PFD frequency is calculated as follow:

$$f_{\text{PFD}} = \text{REF}_{\text{CLK}} \frac{1+D}{R} \quad (3)$$

Use 2R instead of R if the Reference Divide by 2 is used.

REF_IN = the input reference frequency

D = the input reference doubler (0 if not active or 1 if active)

R = the 10-Bits programmable input reference pre-divider

The programmable modulus (MOD) is determined based on the input reference frequency (REF_IN) and the desired channelization (or output frequency resolution). The high resolution provided on the R counter and the Modulus allows the user to choose from several configuration (by using the doubler or not) of the PLL to achieve the same channelization. Using the doubler may offer better phase noise performance. The high resolution Modulus also allows to use the same input reference frequency to achieve different channelization requirements. Using a unique PFD frequency for several needed channelization requirements allows the user to design a loop filter for the different needed setups and ensure the stability of the loop.

$$\frac{f_{\text{PFD}}}{\text{MOD}}$$

The channelization is given by $\frac{f_{\text{PFD}}}{\text{MOD}}$ (4)

In low noise mode (dither disabled), the sigma delta modulator can generate some fractional spurs that are due to the quantization noise.

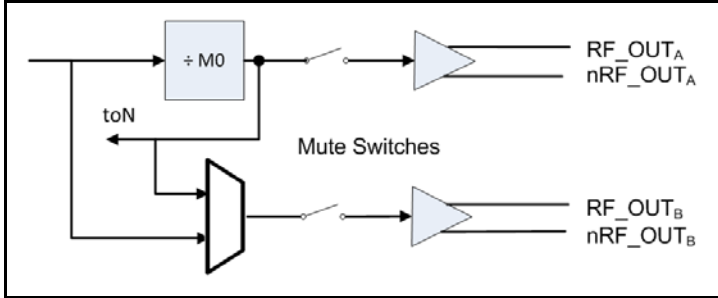
The spurs are located at regular intervals equals to f_{PFD}/L where L is the repeat length of the code sequence in the Sigma Delta modulator. That repeat length depends on the MOD value, as described in Table 4B.

Table 4B. Fractional Spurs Due to the Quantization Noise

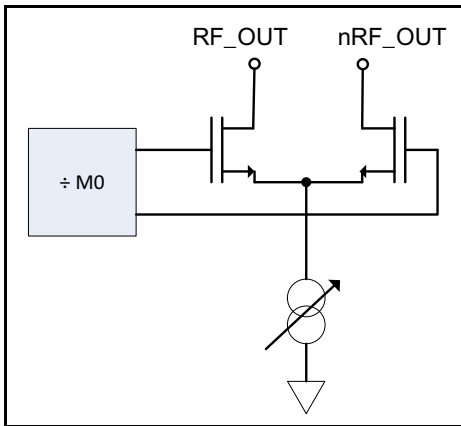
Condition (Dither Disabled)	L	Spur intervals
MOD can be divided by 2, but not by 3	$2 \times \text{MOD}$	$f_{\text{PFD}}/(2 \times \text{MOD})$
MOD can be divided by 3, but not by 2	$3 \times \text{MOD}$	$f_{\text{PFD}}/(3 \times \text{MOD})$
MOD can be divided by 6	$6 \times \text{MOD}$	$f_{\text{PFD}}/(6 \times \text{MOD})$
Other conditions	MOD	$f_{\text{PFD}}/\text{MOD}$ (channel step)

In order to reduce the spurs, the user can enable the dither function to increase the repeat length of the code sequence in the Sigma Delta modulator. The increased repeat length is 2^{21} cycles so that the resulting quantization error is spread to appear like broadband noise. As a result, the in-band phase noise may be degraded when using the dither function.

When the application requires the lowest possible phase noise and when the loop bandwidth is low enough to filter most of the undesirable spurs, or if the spurs won't affect the system performance, it is recommended to use the low noise mode with dither disabled.


Figure 3. Output Stage

RF_OUT and nRF_OUT are derived from the drain of an NMOS differential pair driven by the VCO output (or by the M0 Divider), as shown in [Figure 4, Output Stage](#).


Figure 4. Output Stage

Eight programmable output power levels can be programmed from -4dBm to +7dBm (see [RF Output Power](#) section).

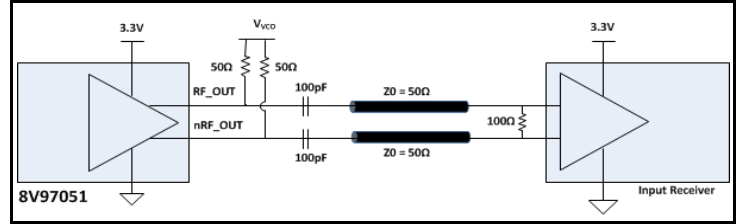
The 8V97051 offers an auxiliary output (RF_OUT_B). If the auxiliary output stage is not used, it can be powered down by using the RF_OutB_En bit in Register 4.

The supply current to the output stage can be shut down until the part achieves lock. To enable this mode, the user will set the MTL_D bit in Register 4. The MUTE pin can be used to mute all outputs and be used as a similar function.

Output Matching

The outputs of the 8V97051 are Open Drain Output and can be matched in different ways.

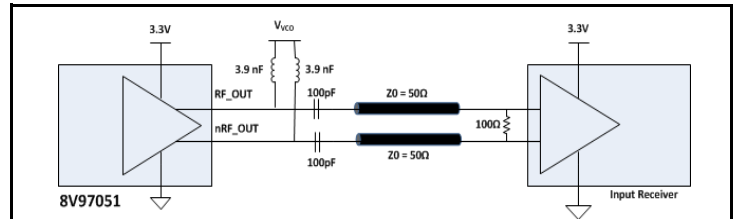
A simple broadband matching is to terminate the open drain RF_OUT output with a 50Ω to V_{VCO} , and with a AC coupling capacitor in series. An example of this termination scheme is shown on [Figure 5, Broadband Matching Termination](#).


Figure 5. Broadband Matching Termination

This termination scheme allows to provide one of the selected output power on the differential pair when connected to a 50Ω load. (See the [RF Output Power](#) section for more information about the output power selection).

The 50Ω resistance connected to V_{VCO} can also be replaced by a choke, for better performance and optimal power transmission.

The pull up inductor value is frequency dependent. For impedance of 50Ω pull-up, the inductance value can be calculated as $L = 50 / (2 * 3.14 * F)$, where F is operating frequency. In this example, $L = 3.9\text{nF}$ is for an operating frequency of approximately 2GHz.


Figure 6. Optimal Matching Termination

See [Applications Information](#) section for more recommendations on the termination scheme.

Band Selection Disable

For a given frequency, the output phase can be adjusted when using the Band_Sel_Disable bit (Bit D28 in Register 1). When this bit is enabled (Bit D28 set to 1), the part does not do a VCO band selection or phase resync after an update to Register 0.

When the Band_Sel_Disable bit is set to 0, and when Register 0 is updated, the part proceeds to a VCO band selection, and to a phase resync if phase_resync is also enabled in Register 3 (Bits[D16:D15] set to D16 = 1 and D15 = 0).

The “Band_Sel_Disable” bit is useful when the user wants to make small changes in the output frequency (<1MHz from the nominal frequency) without recalibrating the VCO and minimizing the settling time.

Phase Adjust

The output phase is controlled by the 12-Bit phase value Bits[D26:D15] in Register 1. The output phase can vary over 360° with a 360/MOD step. For dynamic adjustments of the phase after an initial phase setting, it is recommended to select the BAND_SEL_DISABLE function by setting the Band_Sel_Disable bit (D28 in Register 1) to 1.

The PHASE value can be extended to 16-bits when using the extended registers. In this 16 bit mode, both registers 1 and 7 define the PHASE value.

Phase Resync

The phase alignment function operates based on adjusting the “fractional” phase, so the phase can settle to any one of the MOD phase offsets, MOD being the modulus of the fractional feedback divider.

The phase adjustment can provide a 0-360° of phase adjust, assuming that the output divider ratio is set to 1.

The phase step is TVCO/MOD for the normal case of fundamental feedback. TVCO is the period of the VCO.

The feedback select bit (FbkSel bit, Bit D23 in Register 4) gives the choices of fundamental feedback or divided feedback. This bit controls the mux that sends the VCO signal or the output divider signal to the feedback loop. The user can get larger phase steps in the divided mode, but the phase noise may be degraded, especially in fractional mode. Should the user select this option, the phase adjustment step would be $\sim T_{OUT}/MOD$, where T_{OUT} is the output signal period.

When the part is in fractional mode, the device is dithering the feedback divider value. As an example, when using a 4GHz VCO frequency, the feedback divider value may dither between Div-by-20 and Div-by-21. Since the period is 250ps, there will be 250ps of jitter added to the phase detector. This jitter is filtered by the loop, but can still show up at the output if the loop bandwidth is high. When using a divider before the feedback divider, the effective VCO period is increased. If a Div-by-64 is used for example, the period becomes $64 \times 250ps = 16ns$. This means that there could be an additional 16ns of jitter at the PFD, rather than 250ps. It is more challenging for the loop to filter this larger amount of jitter and this will degrade the overall performance of the part, unless the user chooses to use a very low loop bandwidth. With normal loop bandwidth configurations (for optimal noise), the phase noise would be degraded when using a divided feedback mode.

The Phase Resync is controlled by setting Bits[D16:D15] in Register 3 to D16 = 1 and D15 = 0. When phase resync is used, an internal timer generates sync signals every T_{SYNC} where:

$$T_{SYNC} = ClkDiv \times MOD \times T_{PFD} \quad (5)$$

In Equation 5 above, the minimum of either MOD value or 4095 is used for calculating T_{SYNC} when in 16-bit mode.

Where as:

ClkDiv = the value (from 1 and 4095) programmed in the 12-bit clock counter in Bits[D14:D3] in Register 3. The 12-bit counter is used as a timer for Fast Lock and for the Phase Resync function.

MOD = the Modulus value (Bits[D14:D3] of Register 1)

T_{PFD} = the PFD period

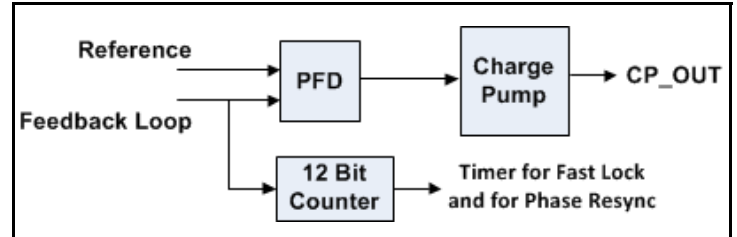


Figure 7. 12-bit Counter for Fast Lock and Phase Resync

After the user program a frequency, the second sync pulse coming from the 12-bit counter, after the nCS is asserted high, is used to resynchronize the output phase to the input phase. To ensure that the PLL is locked before to resynchronize the output phase, T_{SYNC} must be larger than the worst case lock time.

Fast Lock Function

The device uses a fast-lock mode to decrease lock time.

In order to allow the Fast Lock mode, the Fast Lock Switch (FLSW) is shorted to Ground and the charge pump current (ICP) is changed temporarily until the Fast Lock mode is disabled.

The loop bandwidth needs to be increased temporarily in order to allow a faster lock time. By doing this, the loop filter needs to be initially designed so that it addresses the risk of instability of having the zero and the poles too close to the actual bandwidth knee, when the user switches to a fast lock mode.

The loop bandwidth is proportional to:

$$RS \text{ and } ICP \quad (BW \sim RS \times ICP)$$

Where:

BW = the loop bandwidth

RS = the damping resistor

ICP = the programmable charge pump current

In order to enable the fast lock mode, the charge pump current is increased to the maximum value in order to increase the loop bandwidth. In parallel, the FLSW filter is set to ON so that the RS value is $\frac{1}{4}$ of its initial value in order to maintain the loop stability. By doing so, the zero and the first pole are moved (by a factor of 4x in the example below), so that the zero and the pole are kept at a suitable distance around the loop bandwidth.

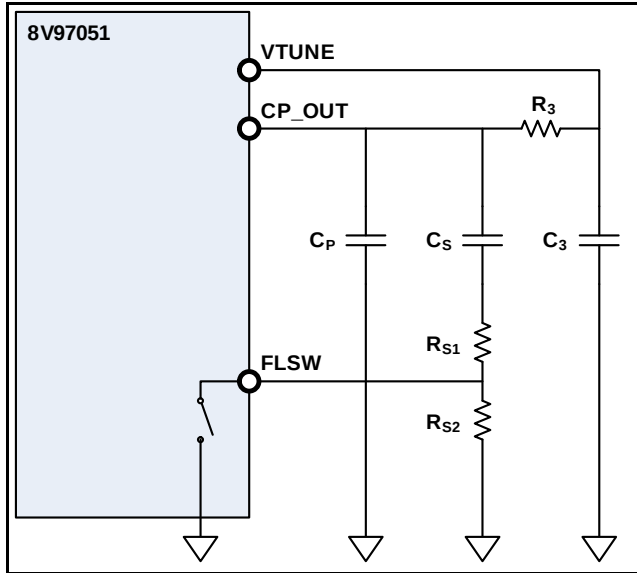


Figure 8. Example of Fast Lock Mode Loop Filter Topology

In the example of [Figure 8, Example of Fast Lock Mode Loop Filter Topology](#), the damping resistor RS is equal to: $RS1 + RS2$ in normal mode (FSLW switch OFF), with $RS2 = 3 * RS1$

When the FLSW switch is ON, the damping resistor value is reduced by $\frac{1}{4}$ of its initial value ($RS = RS1$).

The second pole defined by $R3$ and $C3$ need needs to be designed so that there is no risk of instability when widening the loop bandwidth.

RF Output Power

For RF_OUT_A and RF_OUT_B , the output power can be programmed from -4dBm to +7dBm.

Refer to [Table 9I, Page 26](#), [Table 9K, Table 11E, Page 30](#) and [Table 11F](#) in the [Register Map](#) section for more information.

MUX_OUT

MUX_OUT is a multipurpose output that can be programmed to provide the user with some internal status and values for test and debugging purpose. In addition, MUX_OUT can also be programmed to provide an additional Serial Data Out Pin for a 4-wire SPI interface when needed. The MUX_OUT function is described in the [Table 4C](#) and can be programmed in Bits[D28:D26] in Register 2.

Table 4C. MUX_OUT Pin Configuration

MUX Register Value	MUX_OUT Function
000	High-Impedance Output
001	V_{DDD}
010	GNDD
011	R Counter Output
100	N counter Output
101	Reserved
110	Lock Detect
111	MUX_OUT configured as SDO

Power-Down Mode

When power-down is activated, the following events occur:

1. Counters are forced to their load state conditions
2. VCO is powered down
3. Charge pump is forced into three-state mode
4. Digital lock detect circuitry is reset
5. RF_OUT buffers are disabled
6. The input stage is powered down and set to HiZ
7. Input registers remain active and capable of loading and latching data

Default Power-Up Conditions

All the RF outputs are muted at power up until the loop is locked. Refer to the [Register Map](#) section for default values in registers.

Program Modes

[Table 4D](#) and the [Register Map](#) indicate how the program modes are set up in the 8V97051.

Table 4D. Control Bits Configuration

Control Bits (CB)			Register
C3	C2	C1	
0	0	0	Register 0
0	0	1	Register 1
0	1	0	Register 2
0	1	1	Register 3
1	0	0	Register 4
1	0	1	Register 5
1	1	0	Extended Register 6
1	1	1	Extended Register 7

The following bits are Doubled Buffered:

1. **PHASE** (Bits[D26:D15] in Register 1)
2. **MOD** (Bits[D14:D3] in Register 1)
3. **REF DOUBLER** (Bit D25 in Register 2)
4. **REF DIV2** (Bit D24 in Register 2)
5. **R COUNTER** (Bits[D23:D14] in Register 2)
6. **ICP SETTING** (Bits[D12:D9] in Register 2)

The user must proceed to the following steps before any value written in these bits are used.

1. The new values are written in the double buffered bits
2. A new Write is performed on Register 0

The RF DIVIDER value in Register 4 (Bits[D22:D20]) is also double buffered, but only if the DOUBLE BUFFER bit (Bit D13 in Register 2) is set to 1.

Timing Characteristics

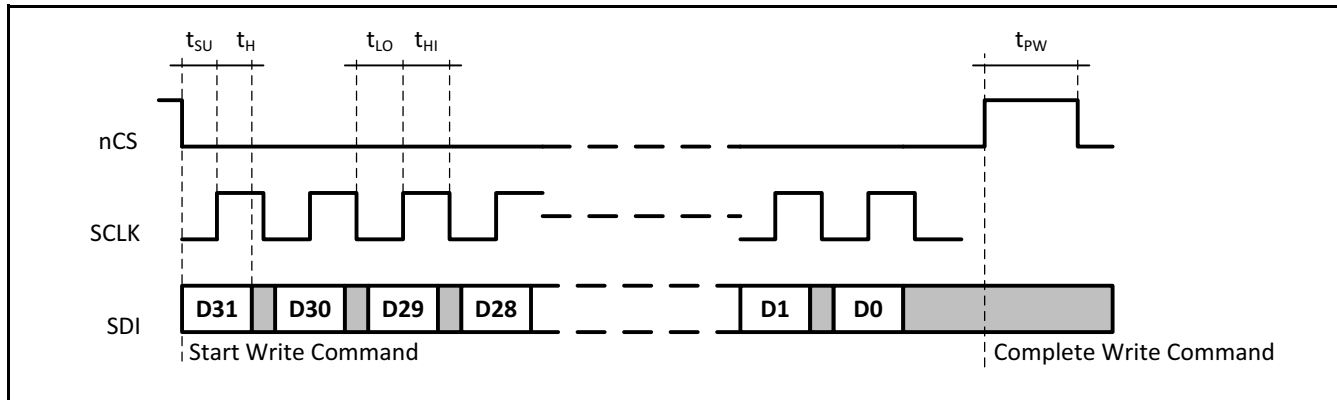


Figure 9. SPI Write Cycle Timing Diagram

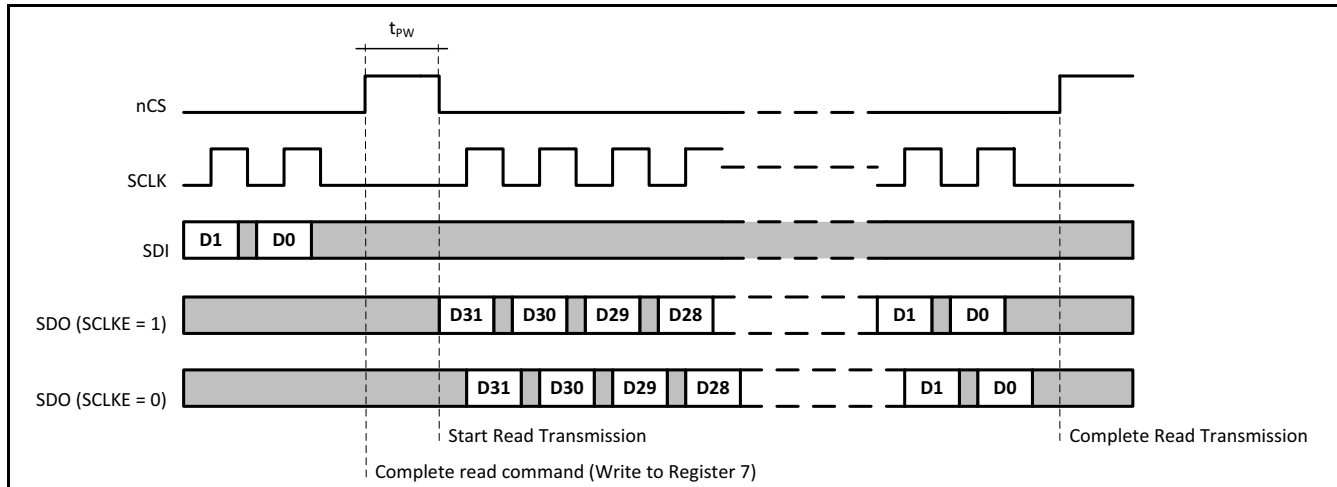


Figure 10. SPI Read Cycle Timing Diagram

Table 4E. SPI Read / Write Cycle Timing Parameters¹

Symbol	Parameter	Minimum	Maximum	Unit
f_{CLK}	SCLK Frequency	-	20	MHz
t_{SU}	nCS, SDI Setup Time to SCLK	10	-	ns
t_H	SCLK to nCS, SDI Hold Time	10	-	ns
t_{LO}	SCLK Low Period	-	-	ns
t_{HI}	SCLK High Period	-	-	ns
t_{PW}	nCS De-asserted Pulse Width	20	-	ns

NOTE 1. Design Target specifications.

3- or 4-Wire SPI Interface Description

The 8V97051 has a serial control port capable of responding as a slave in an SPI compatible configuration to allow access to any of the internal registers (see [section, “Register Map” on page 18](#)) for device programming or examination of internal status. See the specific sections for each register for details on meanings and default conditions.

SPI mode slave operation requires that some functions external to the 8V97051 has performed any necessary serial bus arbitration and/or address decoding at the level of the board or system. The 8V97051 begins a cycle by detecting an asserted (low) state on the nCS input at a rising edge of SCLK. This is also coincident with the first bit of data being shifted into the device. In SPI mode, the first bit is the Most Significant Bit (MSB) of the data word being written. Data must be written in 32-bit words, with nCS remaining asserted and one data bit being shifted in to the 8V97051 on every rising edge of SCLK. If nCS is de-asserted (high) at any time except after the complete 32nd SCLK cycle, this is treated as an error and the shift register contents are discarded. No data is written to any internal registers. If nCS is de-asserted (high) as expected at a time at least t_{SU} after the 32nd falling edge of SCLK, then this will result in the shift register contents being acted on according to the control bit in it.

The word format of the 32-bit quantity in the shift register is shown in [Table 4F](#). The register fields in the 8V97051 have been organized so that the three LSBs in each 32-bit register row are not used for data

transfer. Three of these bits will represent the base address for the 32-bit register row.

To perform a register Read, the user needs set the MUX_OUT bits (Bits[28:D26]) in Register 2 to 111 to configure the MUX_OUT pin as SDO. Register 7 (Instruction register) needs to be set for Read operation. Bit D3 of Register 7 will set the Read or Write command, and Bits[D4:D6] determine the read back address.

If a read operation is requested, 32-bits of read data will be provided in the immediately subsequent access. nCS must be de-asserted (high) for at least t_{PW} , and then reasserted (low).

If $sclke = 1$ (default condition), one data bit will be transmitted on the SDO output at the falling edge of nCS and each falling edge of SCLK as long as nCS remains asserted (low), and the master device should capture data on the rising edge of SCLK. If $sclke = 0$, one data bit will be transmitted on the SDO output at each rising edge of SCLK as long as nCS remains asserted (low), and the master device should capture data on the falling edge of SCLK.

If nCS is de-asserted (high) before 32-bits of read data have been shifted out, the read cycle will be considered to be completed. If nCS remains asserted (low) longer than 32-bit times, then the data during those extra clock periods will be undefined. The MSB of the data will be presented first.

Table 4F. SPI Mode Serial Word Structure

Bit #	MSB							LSB
	31	...	5	4	3	2	1	0
Meaning	D[31:3]						Control Bits	
Width	29						3	

Register Map

Register 0

Table 5A. Register 0-Bit Allocation

DESCRIPTION	NAME	BITS	
FEEDBACK DIVIDER INTEGER VALUE (INT)	RESERVED	D31	
	NDiv16	D30	
	NDiv15	D29	
	NDiv14	D28	
	NDiv13	D27	
	NDiv12	D26	
	NDiv11	D25	
	NDiv10	D24	
	NDiv9	D23	
	NDiv8	D22	
	NDiv7	D21	
	NDiv6	D20	
	NDiv5	D19	
	NDiv4	D18	
	NDiv3	D17	
	NDiv2	D16	
FEEDBACK DIVIDER FRACTIONAL VALUE (FRAC)	NDiv1	D15	
	FDiv12	D14	
	FDiv11	D13	
	FDiv10	D12	
	FDiv9	D11	
	FDiv8	D10	
	FDiv7	D9	
	FDiv6	D8	
	FDiv5	D7	
	FDiv4	D6	
	FDiv3	D5	
	FDiv2	D4	
	FDiv1	D3	
	CONTROL BITS	CB3	D2
		CB2	D1
		CB1	D0

Table 5B. Register 0_ 16-Bit Feedback Divider Integer Value (INT) Function Description

Name	Description	Factory Default	Function
NDiv[16:1]	Feedback Divider Integer Value (INT)	0000 0000 0110 0100 (INT = 100)	0000 0000 0000 0000 = Not allowed 0000 0000 0000 0001 = Not allowed ... = Not allowed 0000 0000 0000 0111 = 7 ... 0000 0000 0001 0111 = 23 0000 0000 0001 1000 = 24 ... 1111 1111 1111 1111 = 65,535

Table 5C. Register 0_ 12-Bit Feedback Divider Fractional Value (FRAC) Function Description¹

Name	Description	Factory Default	Function
FDiv[12:1]	Feedback Divider Fractional Value (FRAC)	0000 0000 0000 (FRAC = 0)	0000 0000 0000 = 0 0000 0000 0001 = 1 ... 1111 1111 1111 = 4095

NOTE 1. This table is used when bit 16b_12b_sel is set to 0 (default). If the 16b_12b_sel is set to 1, refer to [Table 12J, Page 34](#).

Table 5D. Register 0_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	Control Bits	000 = Register 0 is programmed

NOTE 1. The user has to set CB[3:1] to 000 in order to write to Register 0.

Register 1

Table 6A. Register 1-Bit Allocation

DESCRIPTION	NAME	BITS
RESERVED	Reserved	D31
	Reserved	D30
	Reserved	D29
BAND_SEL_DISABLE	Band_Sel_Disable	D28
UNUSED	Unused	D27
	Phase12	D26
	Phase11	D25
	Phase10	D24
	Phase9	D23
	Phase8	D22
	Phase7	D21
	Phase6	D20
	Phase5	D19
	Phase4	D18
	Phase3	D17
	Phase2	D16
	Phase1	D15
	Mod12	D14
	Mod11	D13
	Mod10	D12
	Mod9	D11
Mod8	D10	
Mod7	D9	
Mod6	D8	
Mod5	D7	
Mod4	D6	
Mod3	D5	
Mod2	D4	
Mod1	D3	
CONTROL BITS	CB3	D2
	CB2	D1
	CB1	D0

Table 6B. Register 1_ 1-Bit BAND_SEL_DISABLE Function Description

Name	Description	Factory Default	Function
Band_Sel_Disable	BAND_SEL_DISABLE	0	0 = VCO Band Selection occurs after a Write to Register 0 1 = VCO Band selection is not active and hold to previous VCO band selection

Table 6C. Register 1_ 12-Bit Phase Value (PHASE) Function Description¹

Name	Description	Factory Default	Function
Phase [12:1]	PHASE	0000 0000 0001	0000 0000 0000 = 0 0000 0000 0001 = 1 (Recommended) ... 1111 1111 1111 = 4095

NOTE 1. This table is used when bit D20 in Register 7 (16b_12B_sel) is set to 0 (default). If the 16b_12b_sel is set to 1, refer to [Table 12H, Page 33](#).

Table 6D. Register 1_ 12-Bit Modulus Value (MOD) Function Description¹

Name	Description	Factory Default	Function
Mod[12:1]	MOD	0000 0000 0010	0000 0000 0000 = Not Allowed 0000 0000 0001 = Not Allowed 0000 0000 0010 = 2 ... 1111 1111 1111 = 4095

NOTE 1. This table is used when bit D20 in Register 7 (16b_12B_sel) is set to 0 (default). If 16b_12b_sel is set to 1, refer to [Table 12I, Page 34](#).

Table 6E. Register 1_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	Control Bits	001 = Register 1 is programmed

NOTE 1. The user has to set CB[3:1] to 001 in order to write to Register 1.

Register 2

Table 7A. Register 2-Bit Allocation

DESCRIPTION	NAME	BITS	
RESERVED	RESERVED	D31	
NOISE MODE	ModeNoise1	D30	
	ModeNoise2	D29	
	MUX_OUT3	D28	
MUX_OUT	MUX_OUT2	D27	
	MUX_OUT1	D26	
	RefDoub	D25	
REF DOUBLER	RDiv2	D24	
REF DIV2	R10	D23	
	R9	D22	
	R8	D21	
	R7	D20	
	R6	D19	
	R5	D18	
	R4	D17	
	R3	D16	
	R2	D15	
	R1	D14	
	DOUBLE BUFFER	DoubBuff1	D13
	ICP SETTING	ChrgPmp4	D12
		ChrgPmp3	D11
		ChrgPmp2	D10
		ChrgPmp1	D9
	LDF	LDF	D8
LDP	LDP	D7	
PD POLARITY	PD_pol	D6	
POWER DOWN	PwrDwn	D5	
CP HIGHZ	CP_HIGHZ	D4	
UNUSED	Unused	D3	
CONTROL BITS	CB3	D2	
	CB2	D1	
	CB1	D0	

Table 7B. Register 2_ 2-Bit NOISE MODE Function Description

Name	Description	Factory Default	Function
ModeNoise[2:1]	NOISE MODE	00	00 = Low Noise Mode (Dither OFF) 01 = Reserved 10 = Reserved 11 = Low Spur Mode (Dither Enabled)

Table 7C. Register 2_ 3-Bit MUX_OUT Function Description

Name	Description	Factory Default	Function
MUX_OUT[3:1]	MUX_OUT	000	000 = High-Impedance output 001 = V_{DD} 010 = GNDD 011 = R counter output 100 = N counter output 101 = Reserved 110 = Lock Detect 111 = MUX_OUT configured as SDO

Table 7D. Register 2_ 1-Bit REF DOUBLER Function Description

Name	Description	Factory Default	Function
RefDoub	REF DOUBLER	0	0 = Disabled 1 = Enabled

Table 7E. Register 2_ 1-Bit REF DIV2 Function Description

Name	Description	Factory Default	Function
RDIV2	REF DIV2	0	0 = Disabled 1 = Enabled

Table 7F. Register 2_ 10-Bit R COUNTER (R) Function Description

Name	Description	Factory Default	Function
R[10:1]	R	00 0000 0001	00 0000 0000 = Not Allowed 00 0000 0001 = 1 00 0000 0010 = 2 ... 11 1111 1111 = 1023

Table 7G. Register 2_ 1-Bit DOUBLE BUFFER Function Description¹

Name	Description	Factory Default	Function
DoubBuff1	DOUBLE BUFFER	0	0 = Disabled 1 = Enabled

NOTE 1. Bit D13 enables or disables Double Buffering of Bits[D22:D20] in Register 4. Refer to [Program Modes](#) section.

Table 7H. Register 2_ 4-BIT Charge Pump Setting (ICP SETTING) Function Description

Name	Description	Factory Default	Function
ChrgPmp[4:1]	ICP SETTING	0000	Icp (mA) assuming RCP = 5.1k Ω 0000 = 0.31 0001 = 0.63 0010 = 0.94 0011 = 1.25 0100 = 1.56 0101 = 1.88 0110 = 2.19 0111 = 2.50 1000 = 2.81 1001 = 3.13 1010 = 3.44 1011 = 3.75 1100 = 4.06 1101 = 4.38 1110 = 4.69 1111 = 5.00

Table 7I. Register 2_ 1-Bit Lock Detect Function (LDF) Description¹

Name	Description	Factory Default	Function
LDF	LDF	0	0 = 40 consecutive cycles (recommended for FRAC-N mode) 1 = 5 consecutive cycles (recommended for INT-N mode)

NOTE 1. LDF controls the number of PFD cycles that needs to be considered by the Lock Detect function to decide if the part has achieved lock.

Table 7J. Register 2_ 1-Bit LDP Function Description

Name	Description	Factory Default	Function
LDP	LDP	0	0 = 10ns 1 = 6ns

Table 7K. Register 2_ 1-Bit PD Polarity Function Description

Name	Description	Factory Default	Function
PD_Pol	PD POLARITY	1	0 = NEGATIVE 1 = POSITIVE

Table 7L. Register 2_ 1-Bit Power Down Function Description

Name	Description	Factory Default	Function
PwrDwn	POWER DOWN	0	0 = Disabled 1 = Enabled

Table 7M. Register 2_ 1-Bit CP_High-Impedance Function Description

Name	Description	Factory Default	Function
CP_HIGHZ	CP HIGHZ	0	0 = Disabled 1 = Enabled

Table 7N. Register 2_ 3-Bit Control Bits Function Description NOTE1

Name	Description	Function
CB[3:1]	Control Bits	010 = Register 2 is programmed

NOTE1: The user has to set CB[3:1] to 010 in order to write to Register 2.

Register 3

Table 8A. Register 3-Bit Allocation

DESCRIPTION	NAME	BITS
RESERVED	RESERVED	D31
	RESERVED	D30
	RESERVED	D29
	RESERVED	D28
	RESERVED	D27
	RESERVED	D26
	RESERVED	D25
	RESERVED	D24
BAND SELECT	BandSelCM	D23
UNUSED	Unused	D22
UNUSED	Unused	D21
RESERVED	RESERVED	D20
	RESERVED	D19
UNUSED	Unused	D18
RESERVED	RESERVED	D17
CLK DIV MODE	ClkDivMode2	D16
	ClkDivMode1	D15
CLOCK COUNTER VALUE	ClkDiv12	D14
	ClkDiv11	D13
	ClkDiv10	D12
	ClkDiv9	D11
	ClkDiv8	D10
	ClkDiv7	D9
	ClkDiv6	D8
	ClkDiv5	D7
	ClkDiv4	D6
	ClkDiv3	D5
	ClkDiv2	D4
	ClkDiv1	D3
CONTROL BITS	CB3	D2
	CB2	D1
	CB1	D0

Table 8B. Register 3_ 1-Bit Band Select Clock Mode Function Description¹

Name	Description	Factory Default	Function
BandSelCM	BAND SELECT (CLOCK RATE)	0	0 = LOW (125kHz) 1 = HIGH (up to 500kHz logic sequence for Faster Lock applications)

NOTE 1. BAND SELECT (CLOCK RATE) selects the speed of the logic sequence for the band selection. BandSelCM = 1 sets the logic sequence rate faster, which is recommended for fast lock operation and when high PFD frequencies are used. BandSelCM = 0 is recommended when low PFD frequencies (125kHz) are used. When using BandSelCM = 1, the value of the BAND SELECT CLOCK COUNTER (BndSelDiv[8:1]) must be less than or equal to 254.

Table 8C. Register 3_ 2-Bit Clock Divider Mode Function Description

Name	Description	Factory Default	Function
ClkDivMode[2:1]	CLK DIV MODE	00	00 = Clock Divider OFF 01 = Fast Lock Enabled 10 = Resync Enabled 11 = Reserved

Table 8D. Register 3_ 12-Bit Clock Divider Value (CLKDIV) Function Description

Name	Description	Factory Default	Function
ClkDiv[12:1]	CLKDIV	0000 0000 0001	0000 0000 0000 = Not allowed 0000 0000 0001 = 1 0000 0000 0010 = 2 ... 1111 1111 1111 = 4095

Table 8E. Register 3_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	CONTROL BITS	011 = Register 3 is programmed

NOTE 1. The user has to set CB[3:1] to 011 in order to write to Register 3.

Register 4

Table 9A. Register 4-Bit Allocation

DESCRIPTION	NAME	BITS
RESERVED	RESERVED	D31
	RESERVED	D30
	RESERVED	D29
	RESERVED	D28
	RESERVED	D27
	RESERVED	D26
	RESERVED	D25
	RESERVED	D24
FEEDBACK SELECT	FbkSel	D23
RF DIVIDER	RFDiv3	D22
	RFDiv2	D21
	RFDiv1	D20
	BndSelDiv8	D19
BAND SELECT CLOCK COUNTER	BndSelDiv7	D18
	BndSelDiv6	D17
	BndSelDiv5	D16
	BndSelDiv4	D15
	BndSelDiv3	D14
	BndSelDiv2	D13
	BndSelDiv1	D12
VCO POWER DOWN	VCOPwrDwn	D11
MTLD	MTLD	D10
RF_OUTB SELECT	RF_OUTB_Sel	D9
RF_OUTB ENABLE	RF_OUTB_En	D8
RF_OUTB OUTPUT POWER	RF_OUTB_Pwr	D7
	RF_OUTB_Pwr	D6
RF_OUTA ENABLE	RF_OutA_En	D5
RF_OUTA OUTPUT POWER	RF_OUTA_Pwr	D4
	RF_OUTA_Pwr	D3
CONTROL BITS	CB3	D2
	CB2	D1
	CB1	D0

Table 9B. Register 4_ 1-Bit Feedback Select Function Description

Name	Description	Factory Default	Function
FbkSel	FEEDBACK SELECT	1	0 = Divided 1 = Fundamental

Table 9C. Register 4_ 3-Bit RF Output Divider ($\div$ MO) Select Function Description

Name	Description	Factory Default	Function
RFDiv[3:1]	RF OUTPUT DIVIDER	000	000 = Div by 1 001 = Div by 2 010 = Div by 4 011 = Div by 8 100 = Div by 16 101 = Div by 32 110 = Div by 64 111 = Reserved

Table 9D. Register 4_ 8-Bit Band Select Clock Counter Function Description¹

Name	Description	Factory Default	Function
BndSelDiv[8:1]	BAND SELECT CLOCK COUNTER	0000 0001	0000 0000 = Not Allowed 0000 0001 = 1 0000 0010 = 2 ... 1111 1111 = 255

NOTE 1. BAND SELECT CLOCK COUNTER sets the value of the divider for the band select logic clock input. By default, the output frequency of the R counter is used to clock the band select logic. If this frequency is larger than 125kHz, the Band Select Clock counter can be used to divide the R counter output to a smaller frequency suitable for the band selection logic.

Table 9E. Register 4_ 1-Bit VCO Power Down Function Description

Name	Description	Factory Default	Function
VCOPwrDwn	VCO POWER DOWN	0	0 = VCO Powered Up 1 = VCO Powered Down

Table 9F. Register 4_ 1-Bit Mute Till Lock Detect Function Description

Name	Description	Factory Default	Function
MTLD	MTLD	0	0 = Mute Disabled 1 = Mute Enabled

Table 9G. Register 4_ 1-Bit RF_OUTB Select Function Description

Name	Description	Factory Default	Function
RF_OUTB_Sel	RF_OUTB SELECT	0	0 = Divided Output 1 = Fundamental

Table 9H. Register 4_ 1-Bit RF_OUTB Enable Function Description

Name	Description	Factory Default	Function
RF_OUTB_En	RF_OUTB ENABLE	0	0 = Disabled (High-Impedance) 1 = Enabled ¹

NOTE 1. RF_OUT_A must also be enabled.

Table 9I. Register 4_ 2-Bit RF_OUTB Output Power Function Description¹

Name	Description	Factory Default	Function
RF_OUTB_Pwr[2:1]	RF_OUTB OUTPUT POWER	10	00 = -4dBm 01 = -1dBm 10 = +2dBm 11 = +5dBm

NOTE 1. $f_{RF_OUT} = 34.375\text{MHz}$.

Table 9J. Register 4_ 1-Bit RF_OUTA Enable Function Description

Name	Description	Factory Default	Function
RF_OUTA_En	RF_OUTA ENABLE	0	0 = Disabled ¹ (High-Impedance) 1 = Enabled

NOTE 1. RF_OUT_B will also disable.

Table 9K. Register 4_ 2-Bit RF_OUTA Output Power Function Description¹

Name	Description	Factory Default	Function
RF_OUTA_Pwr[2:1]	RF_OUTA OUTPUT POWER	10	00 = -4dBm 01 = -1dBm 10 = +2dBm 11 = +5dBm

NOTE 1. $f_{RF_OUT} = 34.375\text{MHz}$.

Table 9L. Register 4_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	CONTROL BITS	100 = Register 4 is programmed

NOTE 1. The user has to set CB[3:1] to 100 in order to write to Register 4.

Register 5

Table 10A. Register 5-Bit Allocation¹

DESCRIPTION	NAME	BITS
RESERVED	RESERVED	D31
	RESERVED	D30
	RESERVED	D29
	RESERVED	D28
	RESERVED	D27
	RESERVED	D26
	RESERVED	D25
	RESERVED	D24
LD PIN MODE	LDPinMode2	D23
	LDPinMode1	D22
RESERVED	RESERVED	D21
	RESERVED	D20
	RESERVED	D19
	RESERVED	D18
	RESERVED	D17
	RESERVED	D16
	RESERVED	D15
	RESERVED	D14
	RESERVED	D13
	RESERVED	D12
	RESERVED	D11
	RESERVED	D10
	RESERVED	D9
	RESERVED	D8
	RESERVED	D7
	RESERVED	RESERVED
RESERVED		D5
RESERVED		D4
RESERVED		D3
CONTROL BITS	CB3	D2
	CB2	D1
	CB1	D0

NOTE 1. D19 and D20 must be set to 1.

Table 10B. Register 5_ 2-Bit LD PIN MODE Function Description

Name	Description	Factory Default	Function
LDPInMode[2:1]	LD PIN MODE	01	00 = Low 01 = Digital Lock Detect 10 = Low 11 = High

Table 10C. Register 5_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	CONTROL BITS	101 = Register 5 is programmed

NOTE 1. The user has to set CB[3:1] to 101 in order to write to Register 5.

Extended Registers, (Registers 6 and 7)

Register 6

Table 11A. Register 6-Bit Allocation^{1 2 3}

DESCRIPTION	NAME	BITS
DIGITAL LOCK (RO)	DigLock	D31
BAND_SELECT_DONE (RO)	Band_select_done	D30
RESERVED (RO)	Reserved	D29
RESERVED (RO)	Reserved	D28
LDP_EXT	LDP_Ext2	D27
	LDP_Ext1	D26
RF_OUTB_HI_PWR	rfoutb_hi_pwr	D25
RF_OUTA_HI_PWR	rfouta_hi_pwr	D24
SDM_ORDER	SDMOrder2	D23
	SDMOrder1	D22
DITHER GAIN	DitherG	D21
SHAPE_DITHER_EN	ShapeDitherEn	D20
DSM_TYPE	DSMType1	D19
	DSMType0	D18
BAND_SELECT_ACC	band_select_acc2	D17
	band_select_acc1	D16
RESERVED (RO)		D15
		D14
		D13
		D12
		D11
		D10
		D9
		D8
RESERVED	Reserved	D7
EXT_BND_SEL_DIV	ExtBndSelDiv4	D6
	ExtBndSelDiv3	D5
	ExtBndSelDiv2	D4
	ExtBndSelDiv1	D3
CONTROL BITS	CB3	D2
	CB2	D1
	CB1	D0

NOTE 1. It is recommended that the user writes to Register 0 after writing to Register 6.

NOTE 2. Bit D7 must be set to 0 for correct operation.

NOTE 3. RO Bits are Read Only Bits.

Table 11B. Register 6_ 1-Bit Digital Lock Detect Function Description

Name	Description	Function
DigLock	DIGITAL LOCK	0 = PLL Not Locked 1 = PLL Locked (according LDF and LDP in Register 2)

Table 11C. Register 6_ 1-Bit Band Select Status (Read Only)

Name	Description	Function
Band_select_done	BAND_SELECT_DONE	0 = Band Selection Not Complete 1 = Band Selection Complete

Table 11D. Register 6_ 2-Bit Extra Lock Detect Precision Function Description¹

Name	Description	Factory Default	Function		
			Extra Bit	LDP Bits in Register 2	Value
LDP_Ext[2:1]	LDP_EXT Extra Lock Detect Precision	00	00	0	10ns
				1	6ns
			01	0	3ns
				1	3ns
			10	0	4ns
				1	4.5ns
			11	0	1.5ns
				1	1.5ns

NOTE 1. LDP_Ext[2:1] are Extra Lock Detect Precision bits. When these bits are set to 00, then the precision of the Lock Detect precision only relies on the LDP bit in Register 2, so that the lock detect window is 10ns or 6ns, depending on the LDP bit in Register 2. For high PFD frequencies, the 6ns window may be larger than the entire ref/FB period. The LDP_ext bits reduce the size of the lock detect window to the value described in [Table 11B, Page 29](#), allowing an accurate lock detection with higher PFD frequencies.

Table 11E. Register 6_1 Extra Bit of RF_OUTB Power - Function Description^{1 2}

Name	Description	Factory Default	Function		
			Extra Bit	RF_OUTB OUTPUT POWER Bits in Register 4	Value (dBm)
rf_outb_hi_pwr	RF_OUTB_HI_PWR	0	0	00	-4
				01	-1
				10	+2
				11	+5
			1	00	+2
				01	+5
				10	+6
				11	+7

NOTE 1. RF_OUTB_HI_PWR is an Extra Bit of RF_OUTB Power that increases the output power to the RF_OUT_B output.NOTE 2. $f_{RF_OUT} = 34.375\text{MHz}$.**Table 11F. Register 6_1 Extra Bit of RF_OUTA Power - Function Description^{1 2}**

Name	Description	Factory Default	Function		
			Extra Bit	RF_OUTA OUTPUT POWER Bits in Register 4	Value (dBm)
rf_outa_hi_pwr	RF_OUTA_HI_PWR	0	0	00	-4
				01	-1
				10	+2
				11	+5
			1	00	+2
				01	+5
				10	+6
				11	+7

NOTE 1. RF_OUTA_HI_PWR is an Extra Bit of RF_OUTA Power that increases the output power to the RF_OUT_A output.NOTE 2. $f_{RF_OUT} = 34.375\text{MHz}$.**Table 11G. Register 6_2-Bit SDM Order Configuration**

Name	Description	Factory Default	Function
SDMOrder[2:1]	SDM_ORDER	11	00 = OFF. The device operates in integer mode and the fractional part is ignored. 01 = 1 st order 10 = 2 nd order 11 = 3 rd order

Table 11H. Register 6_ 2-Bit Dither Gain Configuration

Name	Description	Factory Default	Function
DitherG	DITHER_GAIN	0	0 = LSB Dither (Recommended) 1 = LSB x4 Dither

Table 11I. Register 6_ 1-Bit Dither Noise Shaping Configuration

Name	Description	Factory Default	Function
ShapeDitheren	SHAPE_DITHER_EN	1	0 = Dither Noise Shaping Disabled 1 = Dither Noise Shaping Enabled

Table 11J. Register 6_ 1-Bit DSM Type Configuration

Name	Description	Factory Default	Function
DSMType[2:1]	DSM_TYPE	01	00 = MASH 01 = SSMF-II 10 = SSMF-I 11 = SSMF-B

Table 11K. Register 6_ 2-Bit VCO Band Selection Accuracy Configuration

Name	Description	Factory Default	Function
band_select_acc[2:1]	BAND_SELECT_ACC	00	00 = 1 cycle of the band select clock (output of the Band Select Divider) 01 = 2 cycles 10 = 4 cycles 11 = Reserved

Table 11L. Register 6_ 4 Extra MSB of Band Select Divider - Function Description^{1 2}

Name	Description	Factory Default	Value	Function
ExtBndSelDiv[4:1]	EXT_BND_SEL_DIV	0000	BSCC_R4 + [EXT_BND_SEL_DIV]x256	0000 = [BSCC_R4]
				0001 = [BSCC_R4]+256
				0010 = [BSCC_R4] + 512
				
				1111 = [BSCC_R4]+3840

NOTE 1. EXT_BND_SEL_DIV are Extra 4 MSBs that extend the Band Select Clock Counter in Register 4. These additional bits are necessary for band selection to divide down to <500kHz when high PFD frequencies are used.

NOTE 2. BSCC_R4 is the BAND SELECT CLOCK COUNTER value in Register 4.

Table 11M. Register 6_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	CONTROL BITS	110 = Register 6 is programmed

NOTE 1. The user has to set CB[3:1] to 110 in order to write to Register 6.

Register 7

Table 12A. Register 7-Bit Allocation^{1 2}

BITS	NAME	DESCRIPTION
D31	Loss_Dig_Lock	LOSS_DIG_LOCK (SB)
D30	Loss_Anlg_Lock	LOSS_ANLG_LOCK (SB)
D29	Spi_error	SPI_ERROR (SB)
D28	Reserved	RESERVED
D27	Rev_ID3	REV_ID (RO)
D26	Rev_ID2	
D25	Rev_ID1	
D24	Dev_ID4	DEV_ID (RO)
D23	Dev_ID3	
D22	Dev_ID2	
D21	Dev_ID1	16b_12b_SEL
D20	16b_12b_sel	
D19	ext_phase4	EXT_PHASE
D18	ext_phase3	
D17	ext_phase2	
D16	ext_phase1	EXT_MOD
D15	ext_mod4	
D14	ext_mod3	
D13	ext_mod2	
D12	ext_mod1	EXT_FDIV
D11	ext_fdiv4	
D10	ext_fdiv3	
D9	ext_fdiv2	
D8	ext_fdiv1	SCLKE
D7	sclke	
D6	Rd_Addr3	READBACK_ADDR
D5	Rd_Addr2	
D4	Rd_Addr1	
D3	SPI_R_WN	SPI_R_WN
D2	CB3	CONTROL BITS
D1	CB2	
D0	CB1	

NOTE 1. SB Bits are Sticky Bits and need to be cleared.

NOTE 2. RO Bits are Read Only Bits.

Table 12B. Register 7_ 1-Bit Loss of Digital Lock Function Description¹

Name	Description	Function
Loss_Dig_Lock	LOSS_DIG_LOCK	0 = Locked since last time register was cleared 1 = Loss of Digital Lock since last time register was cleared

NOTE 1. This bit is a sticky bit and needs to be cleared with a SPI write of 1 to detect further Loss of Digital Lock occurrences.

Table 12C. Register 7_ 1-Bit Loss of Digital Lock Function Description¹

Name	Description	Function
Loss_Anlg_Lock	LOSS_ANLG_LOCK	0 = Band Selection remained the same since last time register was cleared 1 = Band selection occurred since last time register was cleared

NOTE 1. This bit is a sticky bit and needs to be cleared with a SPI write of 1 to detect further Band Selection occurrences.

Table 12D. Register 7_ 1-Bit Loss of Digital Lock Function Description¹

Name	Description	Function
Spi_error	SPI_ERROR	0 = No SPI write error detection 1 = SPI Write error

NOTE 1. Spi_error Bit goes high if the SPI interface detects a cycle with the incorrect number of SCLK cycles between nCS asserted Low and nCS asserted High. The SPI interface expects 32 clock cycles between nCS asserted Low and nCS asserted High. Any Read/Write via the SPI interface with more or less than 32 clock cycles will result in the Spi_error Bit switched to 1. This bit is a sticky bit and needs to be cleared with a SPI write of 1 in order to detect further possible SPI Write/Read errors.

Table 12E. Register 7_ 3-Bit Revision ID Description

Name	Description	Factory Default
Rev_ID[3:1]	REV_ID	001

Table 12F. Register 7_ 4-Bit Device ID Description

Name	Description	Factory Default
Dev_ID[4:1]	DEV_ID	0110

Table 12G. Register 7_ 1-Bit Resolution Select - Function Description

Name	Description	Factory Default	Function
16b_12b_sel	16b_12b_SEL	0	0 = FRAC, PHASE and MOD set to 12-Bit resolution, Bit[D19:D8] set to 0 and unused
			1 = FRAC, PHASE and MOD set to 16-Bit resolution

Table 12H. Register 7_ 4 Extra Bits of PHASE Value - Function Description¹

Name	Description	Factory Default	Function		
			PHASE	EXT_PHASE	Value
ext_phase[4:1]	EXT_PHASE	0000	0000 0000 0000	0000	0
					
				1111	15
			0000 0000 0001	0000	16
					
				1111	31
					
			1111 1111 1111	0000	65520
					
				1111	65535

NOTE 1. Bit D20 in Register 7 (16b_12b_SEL) is required to be set to 1 when using this table. If Bit D20 in Register 7 (16b_12b_SEL) is set to 0, refer to [Table 6C, Page 19](#).

Table 12I. Register 7_4 Extra Bits of MOD Value - Function Description¹

Name	Description	Factory Default	Function		
			MOD	EXT_MOD	Value
ext_mod[4:1]	EXT_MOD	0000	0000 0000 0000	0000	Not Allowed
				0001	Not Allowed
				0010	2
					
				1111	15
			0000 0000 0001	0000	16
					
				1111	31
					
			1111 1111 1111	0000	65520
					
				1111	65535

NOTE 1. Bit D20 in Register 7 (16b_12b_SEL) is required to be set to 1 when using this table. If Bit D20 in Register 7 (16b_12b_SEL) is set to 0, refer to [Table 6D, Page 20](#).

Table 12J. Register 7_4 Extra Bits of FRAC Value - Function Description¹

Name	Description	Factory Default	Function		
			PHASE	EXT_FDIV	Value
ext_fdiv[4:1]	EXT_FDIV	0000	0000 0000 0000	0000	0
				0001	1
					
				1111	15
			0000 0000 0001	0000	16
					
				1111	31
					
			1111 1111 1111	0000	65520
					
				1111	65535

NOTE 1. Bit D20 in Register 7 (16b_12b_SEL) is required to be set to 1 when using this table. If Bit D20 in Register 7 (16b_12b_SEL) is set to 0, refer to [Table 5C, Page 18](#).

Table 12K. Register 7_ 1-Bit SCLKE Function Description

Name	Description	Factory Default	Function
Sclke	SCLKE	1	0 = Output Data in a Read Cycle on a Rising Edge of SCLK 1 = Output Data in a Read Cycle on a Falling Edge of SCLK

Table 12L. Register 7_ 1-Bit READBACK_ADDR Function Description¹

Name	Description	Function
Rd_Addr[3:1]	READBACK_ADDR	000 = Register 0 001 = Register 1 010 = Register 2 011 = Register 3 100 = Register 4 101 = Register 5 110 = Register 6 111 = Register 7

NOTE 1. In order to Read a register, the user must write to Register 7 first and set the SPI_R_WN Bit to 1 (READ) and indicate the address of the register to read in the READBACK_ADDR Bit (Bits[D6:D4]).

Table 12M. Register 7_ 1-Bit SPI_R_WN Function Description¹

Name	Description	Factory Default	Function
SPI_R_WN	SPI_R_WN	0	0 = WRITE 1 = READ

NOTE 1. Writing this bit to a '1' will allow the user to read back the register selected in READBACK_ADDR on the next 32 SCLK cycle. This bit will revert back to '0' once it is written with '1' and will not retain the '1' value.

Table 12N. Register 7_ 3-Bit Control Bits Function Description¹

Name	Description	Function
CB[3:1]	CONTROL BITS	111 = Register 7 is programmed

NOTE 1. The user has to set CB[3:1] to 111 in order to write to Register 7.

Absolute Maximum Ratings

NOTE: Stresses beyond those listed under **Absolute Maximum Ratings** may cause permanent damage to the device. These ratings are stress specifications only. Functional operation of product at these conditions or any conditions beyond

those listed in the **DC Characteristics or AC Characteristics** is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

Table 13. Absolute Maximum Ratings

Item	Rating
Supply Voltage, V_{DDX}	3.63V
Analog Supply Voltage, V_{DDA}	3.63V
Input, V_I REF_IN Other Inputs (Mute, SDI, FLSW, VTUNE)	$-0.5V_{DDA} + 0.5V$
Outputs, V_O RF_OUT _{A-B} , nRF_OUT _{A-B}	$-0.5V_{DDA} + 0.5V$
Outputs, V_O (SCLK, LD, nCS, MUX_OUT)	$-0.5V_{DDA} + 0.5V$
Outputs, I_O Continuous Current Surge Current	40mA 65mA
Outputs, I_O (SCLK, LD, nCS, MUX_OUT) Continuous Current Surge Current	8mA 13mA
Junction Temperature, T_J	125°C
Storage Temperature, T_{STG}	-65°C to 150°C

NOTE: V_{DDX} denotes V_{DDDD} , V_{CP} , V_{DD_SD} , V_{VCO} .

DC Electrical Characteristics

Table 14A. Power Supply DC Characteristics, $V_{DDX} = V_{DDA} = 3.3V \pm 5\%$, $T_A = -40^{\circ}C$ to $+85^{\circ}C$ ^{1 2 3}

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DDX}	Core Supply Voltage		3.135	3.3	3.465	V
V_{DDA}	Analog Supply Voltage		3.135	3.3	3.465	V
I_{DDX}	Power Supply Current			80		mA
I_{DDA} ⁴	Analog Supply Current	RF_OUT _A / nRF_OUT _A - Active RF_OUT _B / nRF_OUT _B - Muted		55		mA
		RF_OUT _A / nRF_OUT _A - Active RF_OUT _B / nRF_OUT _B - Active		82		mA
		RF_OUT _A / nRF_OUT _A - Muted RF_OUT _B / nRF_OUT _B - Muted		32		mA
I_{VCO}	VCO Supply Current			43		mA
	Power Down Mode			10		mA

NOTE 1. V_{DDX} denotes V_{DD} , V_{CP} , V_{DD_SD} , V_{VCO} .

NOTE 2. RF Outputs Terminated 50Ω to 3.3V.

NOTE 3. Output Power set to +2dBm.

NOTE 4. I_{DDA} is dependent on the value of the M0 output divider. The numbers indicated for I_{DDA} show the current consumption when using the output divider M0 = 64, for which I_{DDA} is higher than when using any other M0 divider value.

Table 14B. Output Divider Incremental Current¹

Parameter	Test Conditions	Minimum	Typical	Maximum	Units
Output Divider Supply Current	Divide by 2		6.5		mA
	Divide by 4		7		mA
	Divide by 8		1		mA
	Divide by 16		1.5		mA
	Divide by 32		2		mA
	Divide by 64		2		mA

NOTE 1. RF Output divider ($\div$ MO) has an incremental increase in current as the divider value increases. This specification is the incremental current change per output divider step. For example, current of divide-by-2 is 6.5mA more than divide-by-1, current of divide-by-4 is 7mA more than divide-by-2, and so on. The total increase from $\div 1$ to $\div 64$ is 20mA.

Table 14C. Typical Current for Each Power Pins¹

Pin Name	Pin Number	Typical Current	Unit
V _{CP}	6	24	mA
V _{VCO}	16, 17	30	mA
V _{DDD}	28	0.5	mA
V _{DD_SD}	32	6	mA
V _{DDA}	10	52	mA

NOTE 1. Operating conditions are:

REF_IN = 25MHz

INT = 100 (integer mode)

RF Divider = ÷1

RF_OUT_A = RF_OUT_B = 2.5GHzRF_{POWER} = -1dBm

Charge Pump = 0.31mA

Table 14D. LVCMOS DC Characteristics, $V_{DDX} = V_{DDA} = 3.3V \pm 5\%$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
V_{IH}	Input High Voltage			1.8		3.3	V
V_{IL}	Input Low Voltage			-0.3		0.8	V
I_{IH}	Input High Current	SDI, MUTE, CE	$V_{DDX} = 3.465V$, $V_{IN} = 1.8V$			5	μA
		SCLK, nCS	$V_{DDX} = 3.465V$, $V_{IN} = 1.8V$			150	
I_{IL}	Input Low Current	SDI, MUTE, CE	$V_{DDX} = 3.465V$, $V_{IN} = 0V$	-150			μA
		SCLK, nCS	$V_{DDX} = 3.465V$, $V_{IN} = 0V$	5			
V_{OH}	Output High Voltage	MUX_OUT, LD	$V_{DDX} = 3.465V$; $I_{OH} = -500\mu A$	$V_{DDX} - 0.4$			V
V_{OL}	Output Low Voltage	MUX_OUT, LD	$V_{DDX} = 3.465V$; $I_{OL} = 500\mu A$			0.4	V

NOTE: Outputs are not terminated.

NOTE: V_{DDX} denotes V_{DD} , V_{CP} , V_{DD_SD} , V_{VCO} .

AC Electrical Characteristics

Table 15A. AC Characteristics, $V_{DDX} = V_{DDA} = 3.3V \pm 5\%$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
REF_IN	Input Reference Frequency		REF_IN < 10MHz, The slew rate must be > 21V/ μ s	5		310	MHz
V _{PP}	Input Sensitivity	REF_IN	Biased at $V_{DDA}/2$; AC Coupling ensures $V_{DDA}/2$ Bias	0.7		V_{DDA}	V
f _{VCO}	VCO Frequency		Fundamental VCO Mode	2200		4400	MHz
f _{RF_OUT}	Output Frequency		Divider Values: 1, 2, 4, 8, 16, 32, 64	34.375		4400	MHz
f _{PFD}	PFD Frequency		Fractional Mode			125	MHz
			Integer Mode			310	MHz
K _{VCO}	VCO Sensitivity				40		MHz/V
t _{LOCK}	PLL Lock Time		Time from Low to High nCS until Low to High LD		1		ms
-	Output Power Variation				± 1		dB
-	RF Output Power		Muted		< -80		dBm
-	Min/Max VCO Tuning Voltage				0.5 / 2.5		V

NOTE: V_{DDX} denotes V_{DD} , V_{CP} , V_{DD_SD} , V_{VCO} .

Table 15B. RF_OUT_[A:B] Phase Noise and Jitter Characteristics, $V_{DDX} = V_{DDA} = 3.3V \pm 5\%$, $T_A = -40^\circ C$ to $85^\circ C$ ^{1 2}

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
tjit($\emptyset$)	RMS Phase Jitter (Random)	f = 156.25MHz Integration Range: 12kHz - 20MHz		161		fs
		f = 2.05GHz Integration Range: 12kHz - 20MHz		147		fs
		f = 1.76GHz Integration Range: 12kHz - 20MHz		125		fs
$\phi_N(100k)$	RF Output Phase Noise Performance @ 1.1GHz (Open Loop)	100kHz Offset from Carrier		-118.4		dBc/Hz
$\phi_N(800k)$		800kHz Offset from Carrier		-141		dBc/Hz
$\phi_N(1M)$		1MHz Offset from Carrier		-143		dBc/Hz
$\phi_N(5M)$		5MHz Offset from Carrier		-152.4		dBc/Hz
$\phi_N(10M)$		10MHz Offset from Carrier		-154		dBc/Hz
$\phi_N(\infty)$		Noise Floor (≥ 30 MHz from Carrier)		-154		dBc/Hz
$\phi_N(100k)$	RF Output Phase Noise Performance @ 1.65GHz (Open Loop)	100kHz Offset from Carrier		-112.7		dBc/Hz
$\phi_N(800k)$		800kHz Offset from Carrier		-137.4		dBc/Hz
$\phi_N(1M)$		1MHz Offset from Carrier		-139.7		dBc/Hz
$\phi_N(5M)$		5MHz Offset from Carrier		-151.8		dBc/Hz
$\phi_N(10M)$		10MHz Offset from Carrier		-153.7		dBc/Hz
$\phi_N(\infty)$		Noise Floor (≥ 30 MHz from Carrier)		-155.9		dBc/Hz
$\phi_N(100k)$	RF Output Phase Noise Performance @ 2.3GHz (Open Loop)	100kHz Offset from Carrier		-112.2		dBc/Hz
$\phi_N(800k)$		800kHz Offset from Carrier		-135.7		dBc/Hz
$\phi_N(1M)$		1MHz Offset from Carrier		-137.9		dBc/Hz
$\phi_N(5M)$		5MHz Offset from Carrier		-151.0		dBc/Hz
$\phi_N(10M)$		10MHz Offset from Carrier		-154.2		dBc/Hz
$\phi_N(\infty)$		Noise Floor (≥ 30 MHz from Carrier)		-156.2		dBc/Hz
$\phi_N(100k)$	RF Output Phase Noise Performance @ 3.8GHz (Open Loop)	100kHz Offset from Carrier		-106		dBc/Hz
$\phi_N(800k)$		800kHz Offset from Carrier		-130.5		dBc/Hz
$\phi_N(1M)$		1MHz Offset from Carrier		-132.5		dBc/Hz
$\phi_N(5M)$		5MHz Offset from Carrier		-148		dBc/Hz
$\phi_N(10M)$		10MHz Offset from Carrier		-152		dBc/Hz
$\phi_N(\infty)$		Noise Floor (≥ 30 MHz from Carrier)		-155		dBc/Hz
$\phi_N(100k)$	RF Output Phase Noise Performance @ 4.4GHz (Open Loop)	100kHz Offset from Carrier		-102		dBc/Hz
$\phi_N(800k)$		800kHz Offset from Carrier		-127		dBc/Hz
$\phi_N(1M)$		1MHz Offset from Carrier		-129.5		dBc/Hz
$\phi_N(5M)$		5MHz Offset from Carrier		-146		dBc/Hz
$\phi_N(10M)$		10MHz Offset from Carrier		-150.5		dBc/Hz
$\phi_N(\infty)$		Noise Floor (≥ 30 MHz from Carrier)		-153		dBc/Hz
-	Spurious Signals Due to PFD Frequency	f _{PFD} = 50MHz; RF_OUT _A = 2.2GHz		-74		dBc

Table 15B. RF_OUT_[A:B] Phase Noise and Jitter Characteristics, $V_{DDX} = V_{DDA} = 3.3V \pm 5\%$, $T_A = -40^\circ C$ to $85^\circ C$ ^{1 2} (Continued)

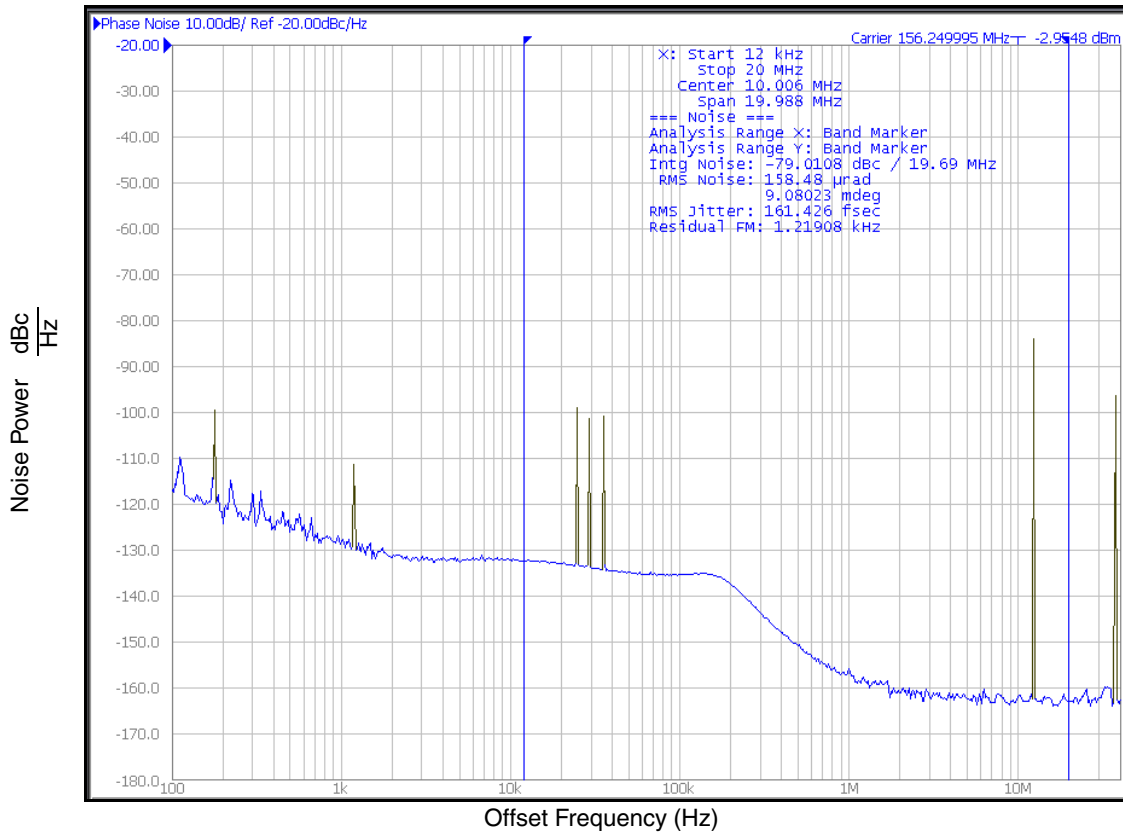
-	In-Band Phase Noise	3kHz from 2GHz Carrier		-107		dBc/Hz
$\varphi_N(1/f)$	Normalized 1/f Noise ³	10kHz Offset; Normalized to 1GHz		-115		dBc/Hz
Harmonics	$f_{RF_OUT} = f_{VCO}/1 = 2.2GHz$	$2^{nd} / 3^{rd}$		-40/ -38		dB
	$f_{RF_OUT} = f_{VCO}/2 = 1.1GHz$	$2^{nd} / 3^{rd}$		-47/ -15		dB
	$f_{RF_OUT} = f_{VCO}/32 = 100MHz$	$2^{nd} / 3^{rd}$		-64/ -10		dB
	$f_{RF_OUT} = f_{VCO}/64 = 34.375MHz$	$2^{nd} / 3^{rd}$		-53/ -15		dB

NOTE 1. V_{DDX} denotes V_{DD} , V_{CP} , V_{DD_SD} , V_{VCO} .

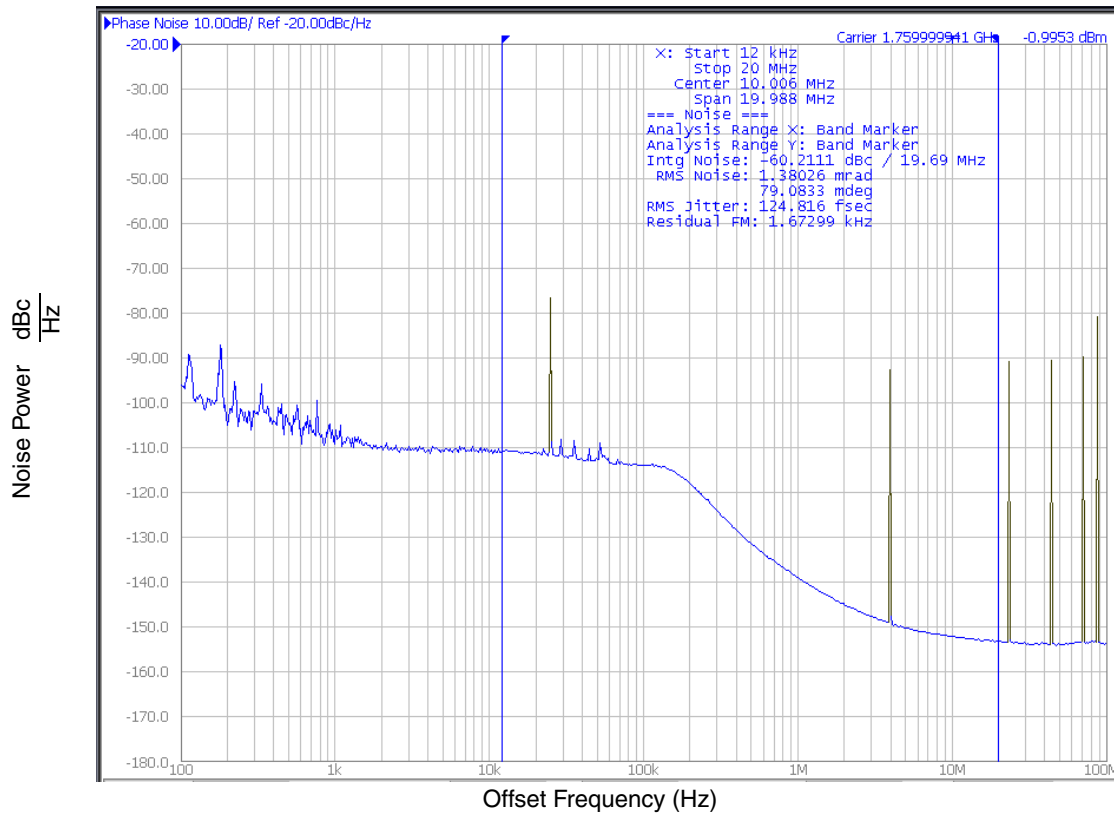
NOTE 2. RF_OUT_A output power setting = +2dBm.

NOTE 3. $\varphi_N(1/f) = \varphi_N(RF_OUT) - 10 \text{ Log}(10kHz/f) - 10 \text{ Log}(f_{RF_OUT}/1GHz)$ where $\varphi_N(1/f)$ is the 1/f noise contribution at an RF_OUT frequency (f_{RF_OUT}) and at a frequency offset f .

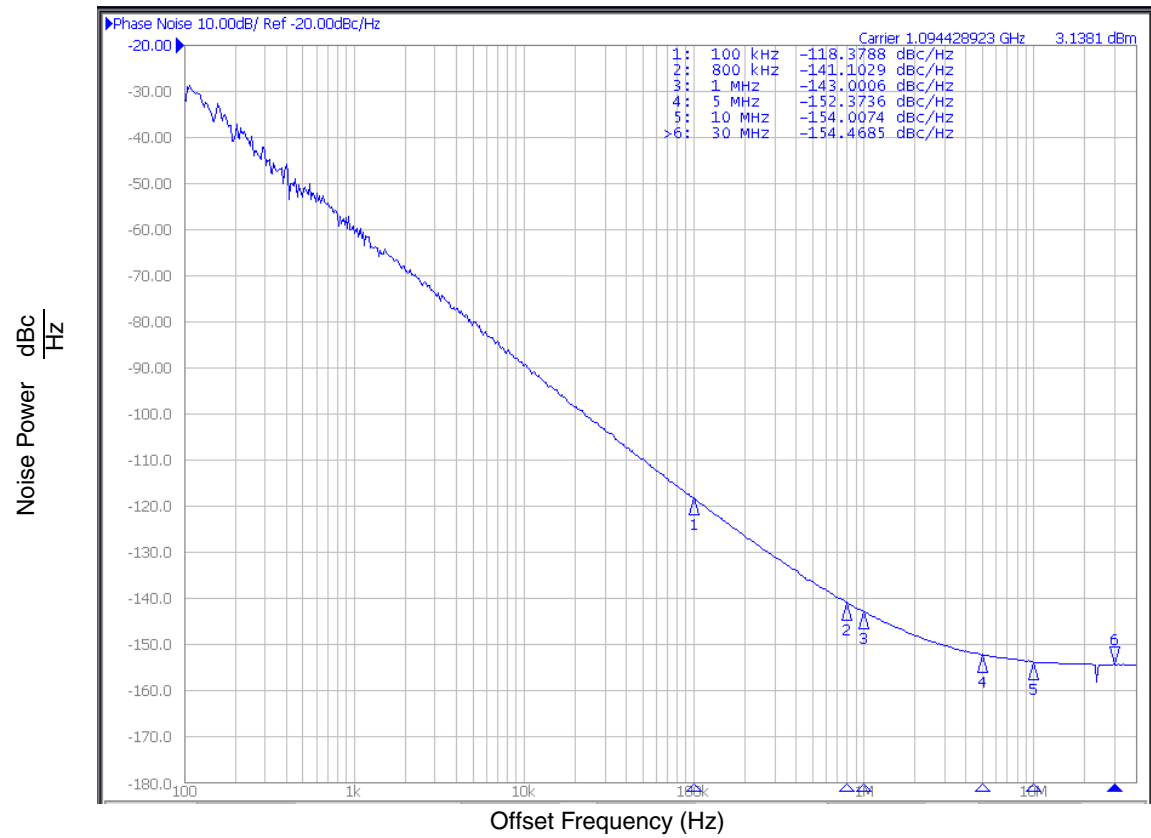
Phase Noise at 156.25MHz (3.3V)



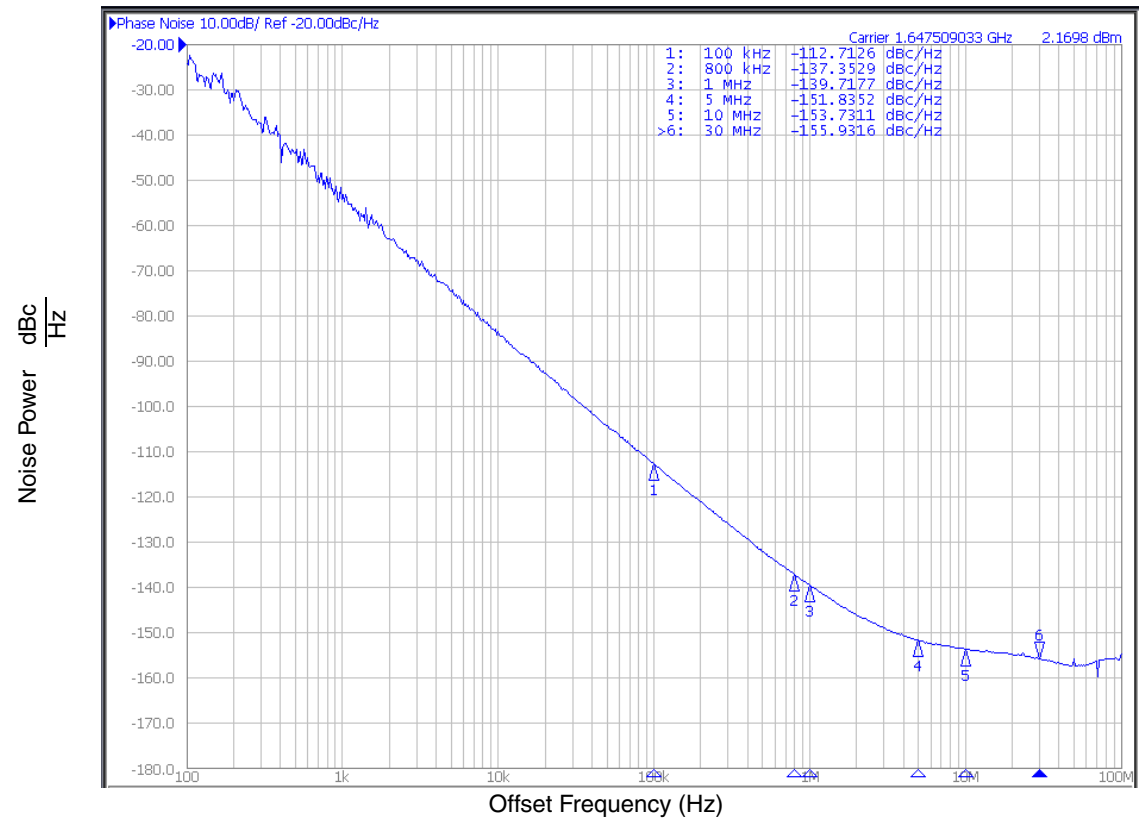
Phase Noise at 1.76GHz (3.3V)



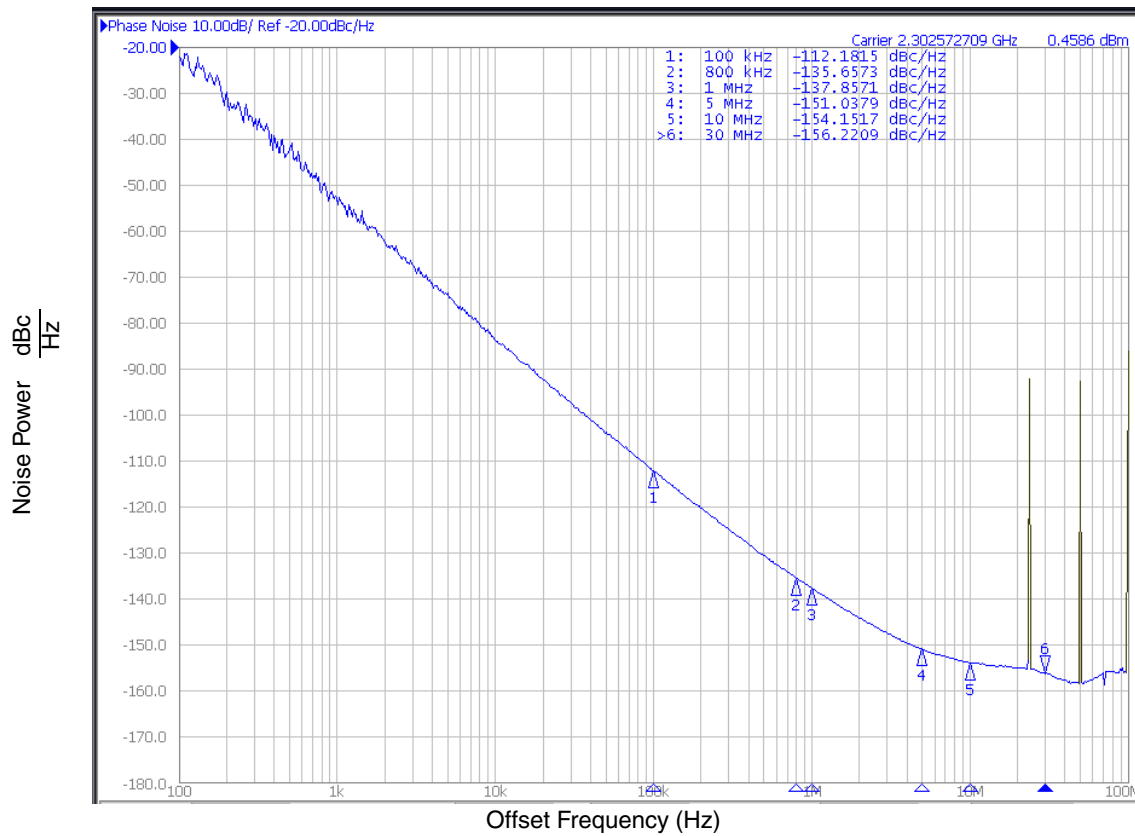
Phase Noise Performance (Open Loop) at 1.1GHz (3.3V)



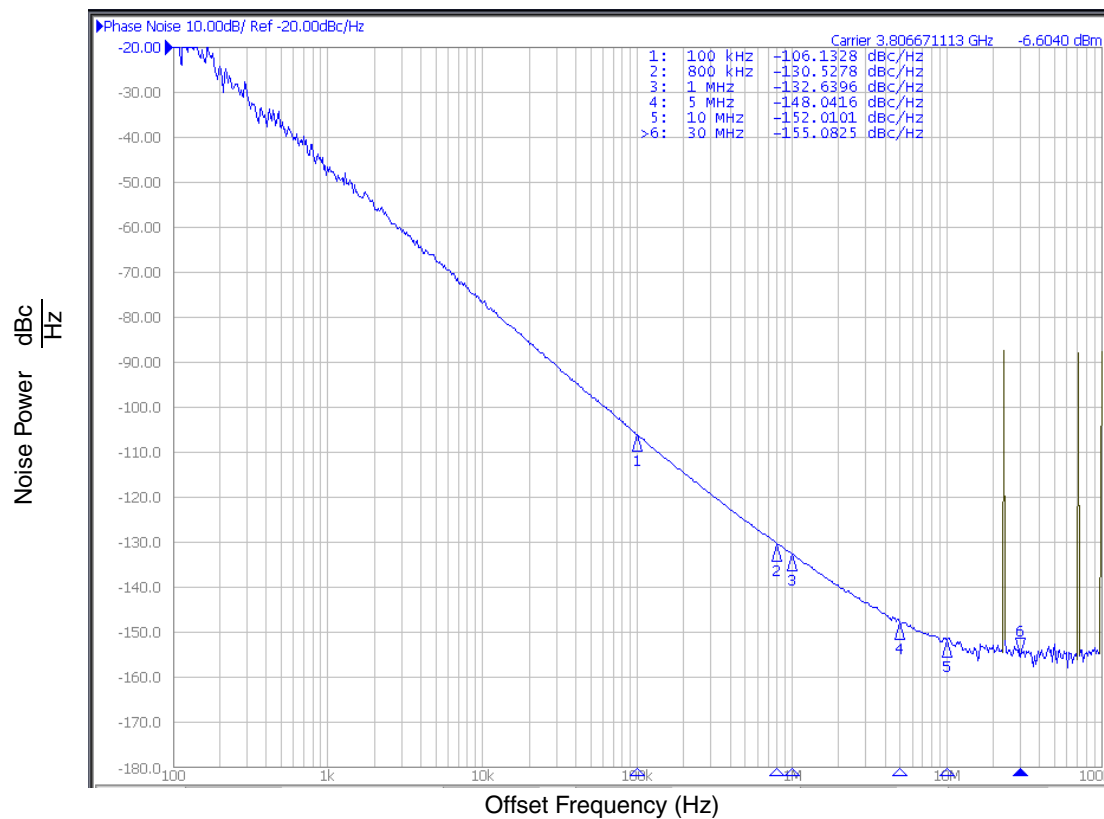
Phase Noise Performance (Open Loop) at 1.65GHz (3.3V)



Phase Noise Performance (Open Loop) at 2.3GHz (3.3V)



Phase Noise Performance (Open Loop) at 3.8GHz (3.3V)



Applications Information

Loop Filter Calculations

2nd Order Loop Filter

This section helps design a 2nd order loop filter for 8V97051. A general 2nd order loop filter is shown in [Figure 11, Typical 2nd Order Loop Filter](#). Step-by-step calculations to determine Rz, Cz and Cp values for a desired loop bandwidth are described below. Required parameters are provided. A spreadsheet for calculating the loop filter values is also available.

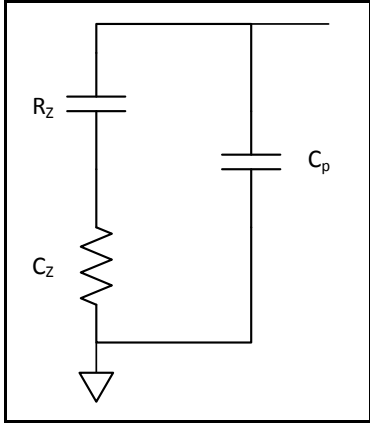


Figure 11. Typical 2nd Order Loop Filter

1. Determine desired loop bandwidth f_c .
2. Calculate Rz:

$$R_z = \frac{2 * \pi * f_c * N}{I_{cp} * K_{vco}}$$

Where,

Icp is charge pump current. Icp is programmable from 310μA to 5mA.

N is effective feedback divider. N must be programmed into the following value.

$$N = \frac{F_{vco}}{F_{pd}}$$

Fvco is VCO frequency.

VCO frequency range: 2200MHz to 4400MHz

Fpd is phase detector input frequency.

$$F_{pd} = \frac{F_{ref}}{P_v}$$

F_ref is reference clock (REF_IN) input frequency.

Pv is overall pre-divider setting.

Kvco is VCO gain. Kvco = 40MHz/V

3. Calculate Cz:

$$C_z = \frac{\alpha}{2 * \pi * f_c * R_z}$$

Where,

$\alpha = f_c / f_z$, user can determine an α number.
 $\alpha > 6$ is recommended.

fz is frequency at zero.

4. Calculate Cp:

$$C_p = \frac{C_z}{\alpha * \beta}$$

Where,

$\beta = f_p / f_c$, user can determine β number.
 $\beta > 4$ is recommended.

fp is frequency at pole.

5. Verify Phase Margin (PM)

$$PM = \arctan \left(\frac{b - 1}{2 * \sqrt{b}} \right)$$

Where,

$$b = 1 + \frac{C_z}{C_p}$$

The phase margin (PM) should be greater than 50°.

A spreadsheet for calculating the loop filter component values is provided. To use the spreadsheet, the user simply enters the following parameters:

f_c , F_{ref} , P_v , I_{cp} , F_{VCO} , α and β .

The spreadsheet will provide the component values, Rz, Cz and Cp as the result. The spreadsheet also calculates the maximum phase margin for verification.

3rd Order Loop Filter

This section helps design a 3rd order loop filter for 8V97051. A general 3rd order loop filter is shown in [Figure 12, Typical 3rd Order Loop Filter](#).

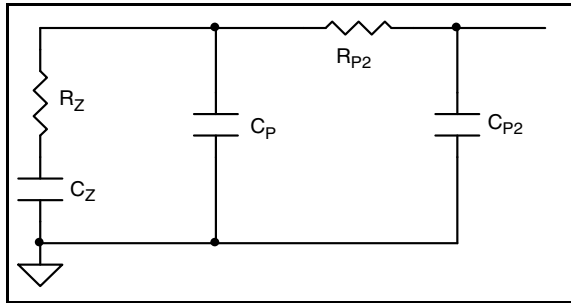


Figure 12. Typical 3rd Order Loop Filter

The R_Z , C_Z and C_P can be calculated as 2nd order loop filter. The following equation help determine the 3rd order loop filter R_{P2} and C_{P2} .

Pick an R_{P2} value. $R_{P2} \sim 1.5 \times R_Z$ is suggested.

$$C_{P2} = \frac{R_Z * C_P}{R_{P2} * \gamma}$$

Where,

γ is ratio between the 1st pole frequency and the 2nd pole frequency.
 $\gamma > 4$ is recommended.

Recommendations for Unused Input and Output Pins

Inputs:

LVCMOS Control Pins

All control Pins have internal pullup and pulldown resistors; additional resistance is not required but can be added for additional protection. A 1k Ω resistor can be used.

Outputs:

Output Pins

The unused output can be left floating and disabled.

Schematic Example

Figure 13A and Figure 13B show general application schematic examples for the 8V97051.

For power rails, bypass capacitors must be provided to all power supply pins. Suggest at least one bypass capacitor per power pin. Value can be ranged from 0.01uF or 0.1uF. Mix values of bypass capacitor can help filtering wider range of power supply noise.

The 8V97051 input is high impedance. The input termination depends on the driver type termination requirements. In these examples, the 8V97051 REF_IN input is terminated with a matched load termination. For transmission line with characteristic impedance $Z_0 = 50\Omega$, the termination resistor R8 is 50Ω . The input is self bias to proper DC offset after the AC coupling.

The loop filter values can be calculated to meet the loop bandwidth requirement. Please refer to the Loop Filter section for detail calculation. For fast lock mode, the loop filter can be configured as Fast Lock Loop Filter Option 1 or Fast Lock Loop Filter Option 2 shown in Figure 13A.

Fast Lock Loop Filter Option 1 is Parallel Resistor Configuration. For normal operating mode, only R5 is active and $R5 = R_s$, where R_s is the resistor value for normal operating mode loop bandwidth. In fast lock mode, the combination of R4 in parallel with R5 is active. For example, in normal operation mode, if the charge pump current is set at 0000 (ICP = 310uA), then, in fast lock mode, the loop bandwidth is set larger by increasing the charge pump current to ICP~5mA (ICP

setting = 1111 or 16 times the normal charge pump current). The combination of the R4 and R5 in parallel is $1/4 * R_s$.

Fast Lock Loop Filter Option 2 is Series Resistor Configuration. For normal operating mode, both R6 and R7 are active and $R6 + R7 = R_s$. For fast lock mode, only R6 is active. For example, in normal operation mode, if the charge pump current is set at 0000 (ICP = 310uA), then, in fast lock mode, the loop bandwidth is set larger by increasing the charge pump current to ICP~5mA (ICP setting = 1111 or 16 times the normal charge pump current). The sum of R6 and R7 equals to R_s , i.e. $R6 + R7 = R_s$. $R6 = 1/4 * R_s$ and $R7 = 3/4 * R_s$.

The 8V97051 output pull-up loading can be resistors or inductors. The pull up resistor value is typically 50Ω . Resistor pull up loading covers wide range of output frequencies. For inductor pull up loading, the inductor value is frequency dependent. One inductor value cannot cover all the output frequency range. This example shows the $L = 3.9nF$ that is suitable for approximately 2GHz operating frequency. The output can also drive single ended LO input. Figure 13B shows an example of 8V97051 output driving single ended LO input of the mixer through an LC balun. The LC balun component values are frequency dependent. These values can be adjusted to optimize the performance. Single ended LO receiver input also can tap to one side of the differential driver using resistor loading or inductor loading. For single ended LO input, both sides of the differential driver still need to be loaded with pull up. The output power level can also be adjusted further through programming.

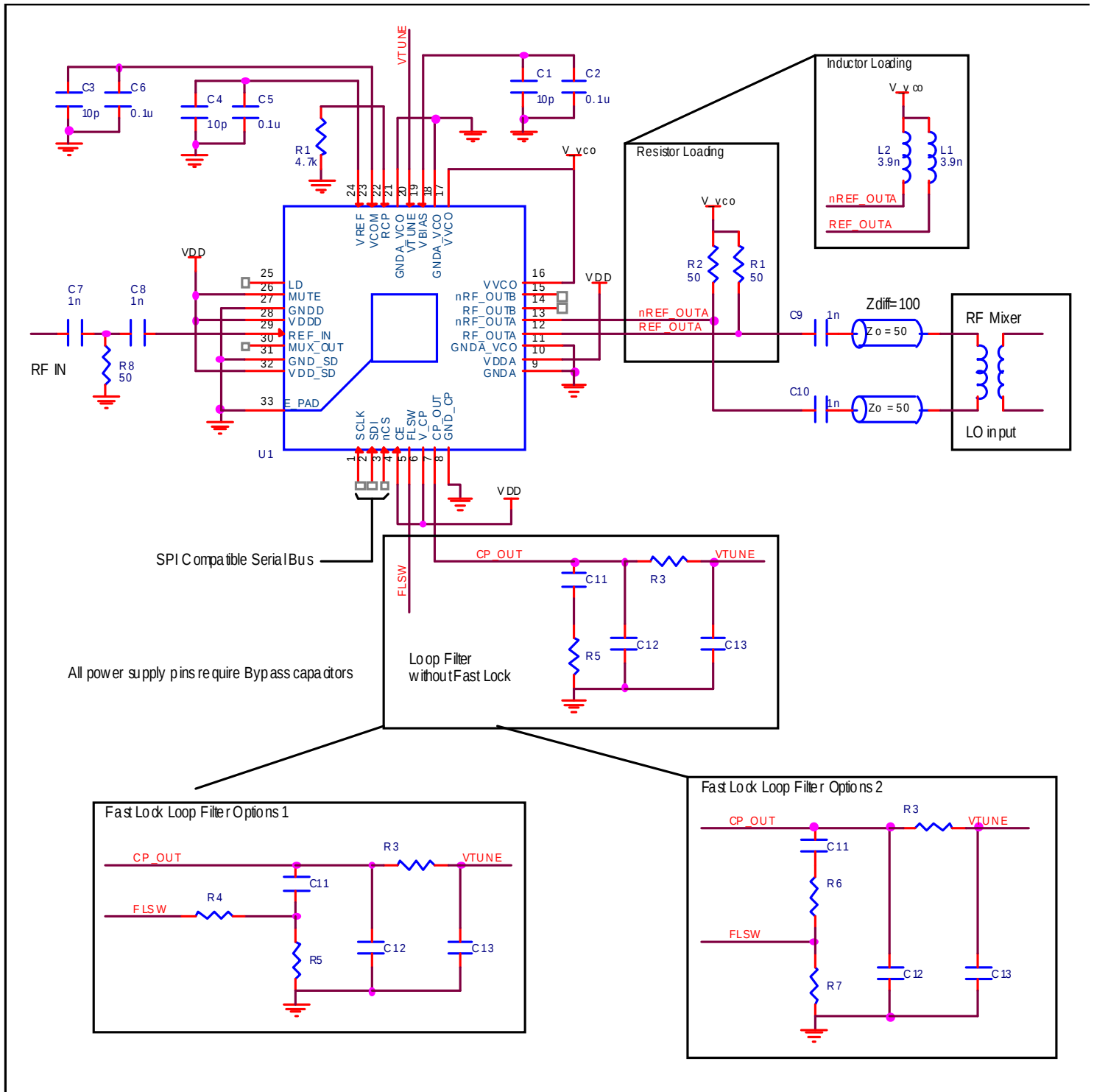


Figure 13A. An 8V97051 General Application Schematic Example

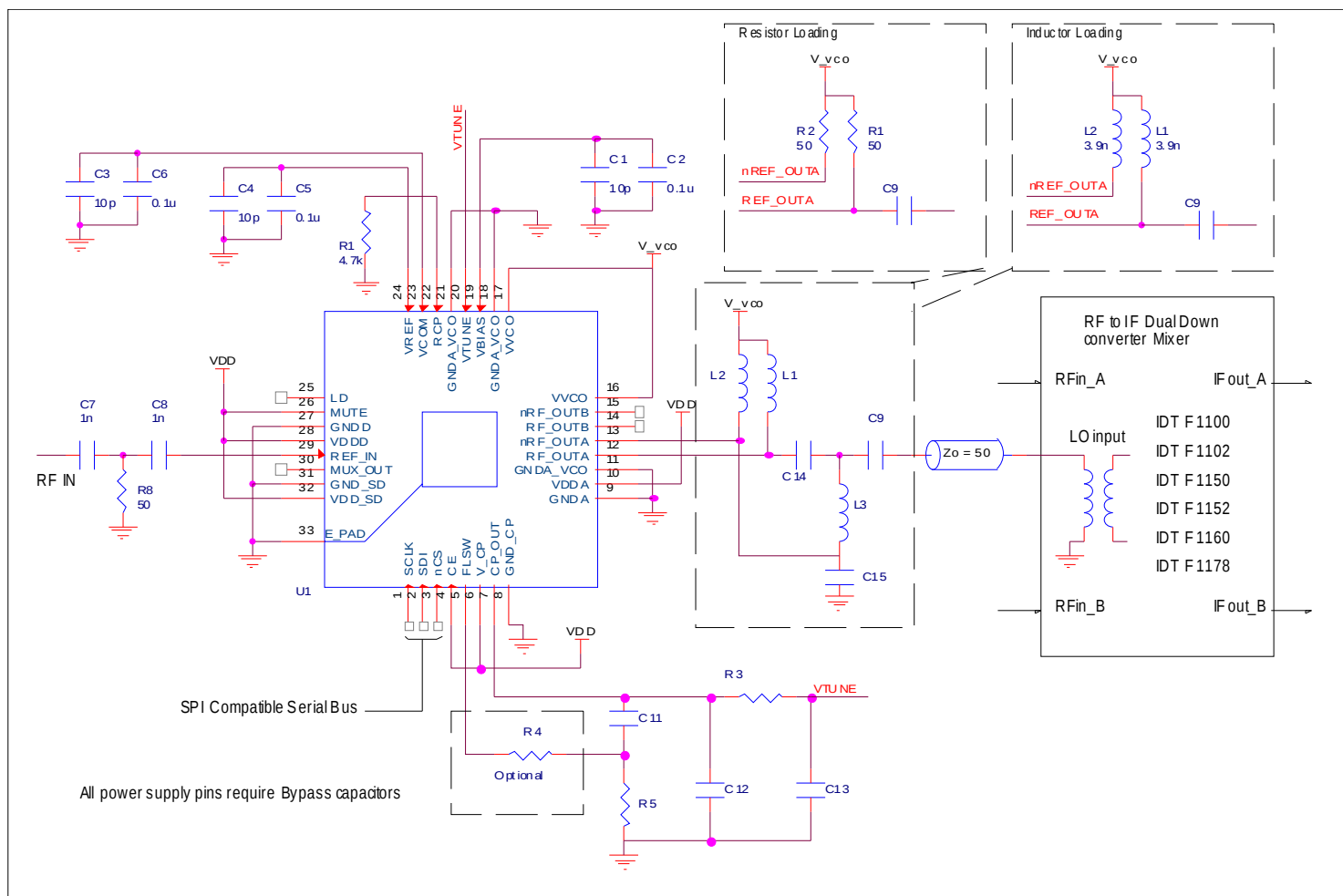


Figure 13B. Schematic Example for Driving Single Ended Mixer

Power Considerations

The 8V97051 device was designed and characterized to operate within the ambient industrial temperature range of -40°C to +85°C. The ambient temperature represents the temperature around the device, not the junction temperature. When using the device in extreme cases, such as maximum operating frequency and high ambient temperature, external air flow may be required in order to ensure a safe and reliable junction temperature. Extreme care must be taken to avoid exceeding 125°C junction temperature. The power calculation example below was generated using a typical configuration. For many applications, the power consumption can vary depending on configuration. Please contact IDT technical support for any concerns on calculating the power dissipation for your own specific configuration.

1. Power Dissipation.

The total power dissipation for the 8V97051 is the sum of the core power plus the power dissipation in the output driver. The following is the power dissipation for $V_{DD} = 3.3V$, which gives typical results.

NOTE: Please refer to "Section 3. Calculations and Equations." for details on calculating power dissipation in the load.

- Power (core) = $V_{DD} * (I_{DDA} + I_{VCO} + I_{CP} + I_{DD_SD} + I_{DDD}) = 3.3V * (10mA + 50mA + 24mA + 6mA + 0.5mA) = \mathbf{298.7mW}$
- Power (outputs) = **33.71mW/Loaded Output pair**
The total power is $2 * 33.71mW = \mathbf{67.42mW}$

Total Power (with two outputs active) = $298.7mW + 67.4mW = \mathbf{366.07mW}$

2. Junction Temperature.

Junction temperature, T_j , is the temperature at the junction of the bond wire and bond pad, and directly affects the reliability of the device. The maximum recommended junction temperature is 125°C. Limiting the internal transistor junction temperature, T_j , to 125°C ensures that the bond wire and bond pad temperature remains below 125°C.

The equation for T_j is as follows: $T_j = \theta_{JA} * Pd_total + T_A$

T_j = Junction Temperature

θ_{JA} = Junction-to-Ambient Thermal Resistance

Pd_total = Total Device Power Dissipation (example calculation is in section 1 above)

T_A = Ambient Temperature

In order to calculate junction temperature, the appropriate junction-to-ambient thermal resistance θ_{JA} must be used. Assuming no air flow and a multi-layer board, the appropriate value is 34.34°C/W per Table 16 below.

Therefore, T_j for an ambient temperature of 85°C with all outputs active is:

$$85^{\circ}C + 0.366W * 34.34^{\circ}C/W = 97.6^{\circ}C. \text{ This is well below the limit of } 125^{\circ}C.$$

This calculation is only an example. T_j will obviously vary depending on the number of loaded outputs, supply voltage, air flow and the type of board (multi-layer).

Table 16. Thermal Resistance θ_{JA} for 32 Lead VFQFN, Forced Convection

θ_{JA} by Velocity			
Meters per Second	0	1	2
Multi-Layer PCB, JEDEC Standard Test Boards	34.34°C/W	30.7°C/W	29.12°C/W

3. Calculations and Equations.

The purpose of this section is to calculate the power dissipation for the open drain driver output pair. The open drain output circuit and termination are shown in Figure 14.

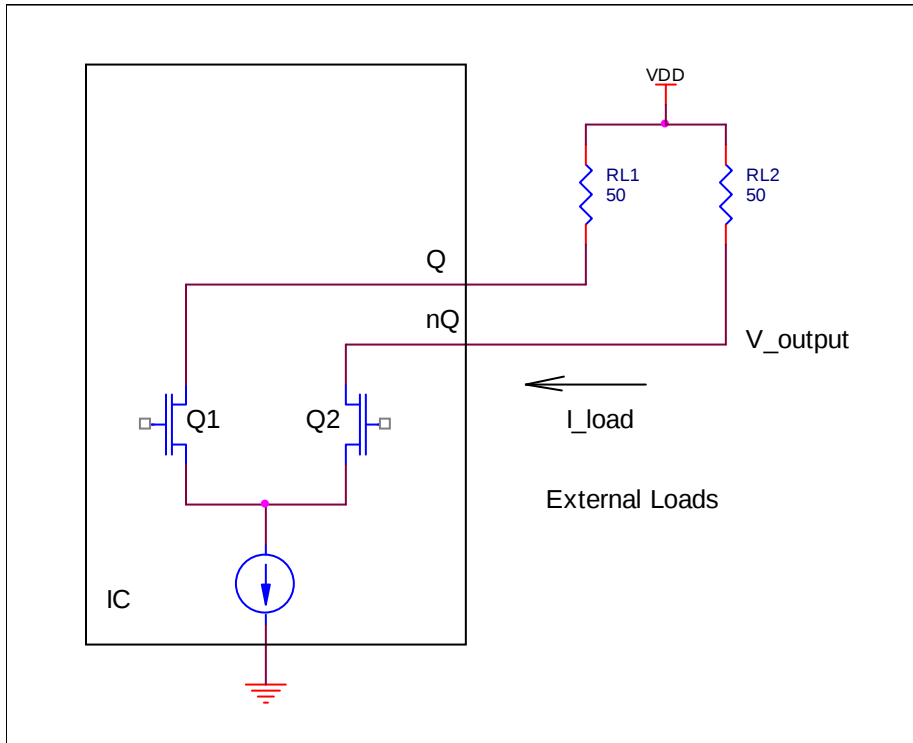


Figure 14. Open Drain Driver Circuit and Termination

To calculate typical power dissipation due to the load, use the following equations.

Power dissipation when the output driver is logic LOW:

$$\begin{aligned}
 Pd_L &= I_{Load} * V_{Output} \\
 &= (V_{OUT_MAX} / R_L) * (V_{DD} - V_{OUT_MAX}) \\
 &= (600mV / 50\Omega) * (3.3V - 600mV) \\
 &= 32.4mW
 \end{aligned}$$

Power dissipation when the output driver is logic HIGH:

$$\begin{aligned}
 Pd_H &= I_{Load} * V_{Output} \\
 &= (0.02V / 50\Omega) * (3.3V - 0.02V) \\
 &= 1.31mW
 \end{aligned}$$

Total Power Dissipation per output pair = $Pd_H + Pd_L = 33.71mW$

Reliability Information

Table 17A. θ_{JA} vs. Air Flow Table for a 32 lead VFQFN

θ_{JA} vs. Air Flow			
Meters per Second	0	1	2
Multi-Layer PCB, JEDEC Standard Test Boards	34.34°C/W	30.7°C/W	29.12°C/W

Table 17B. θ_{JB} vs. Air Flow Table for a 32 lead VFQFN

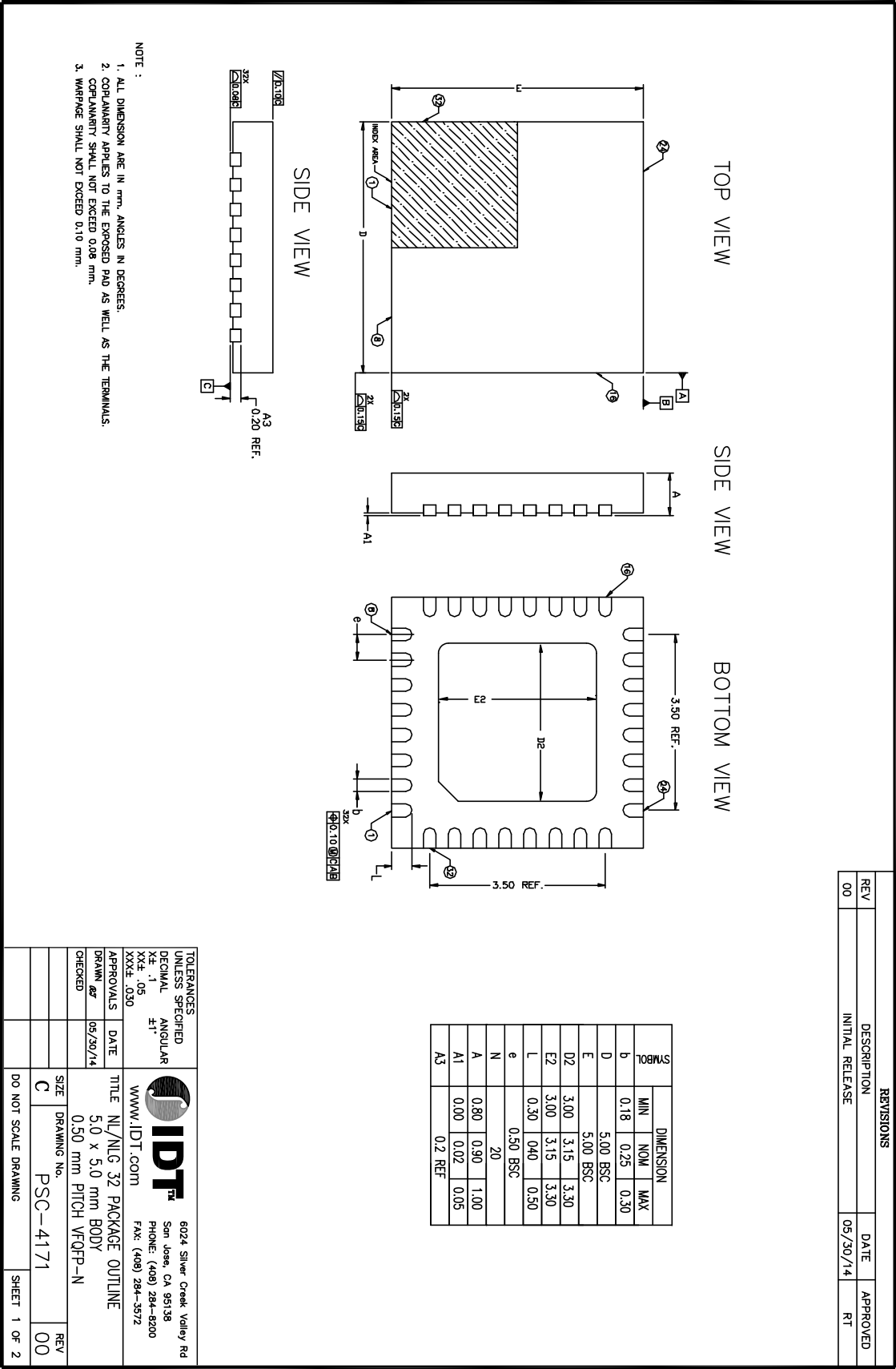
θ_{JB} vs. Air Flow	
Meters per Second	0
Multi-Layer PCB, JEDEC Standard Test Boards	0.472°C/W

NOTE: θ_{JB} is independent of airflow.

Transistor Count

The 8V97051 transistor count is: 409,546

32-Lead VFQFN Package Outline and Package Dimensions



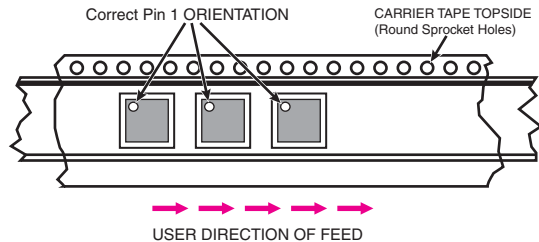
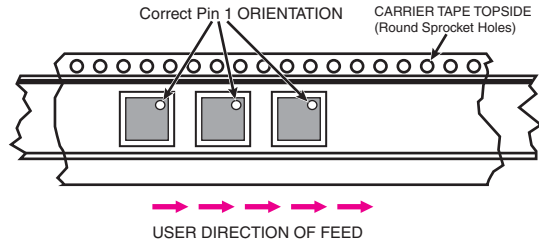
Ordering Information

Table 18. Ordering Information

Part/Order Number	Marking	Package	Shipping Packaging	Temperature
8V97051NLGI	IDT8V97051NLGI	32-lead VFQFN, Lead Free	Tray	-40°C to +85°C
8V97051NLGI8	IDT8V97051NLGI	32-lead VFQFN, Lead Free	Tape & Reel	-40°C to +85°C
8V97051NLGI/W	IDT8V97051NLGI	32-lead VFQFN, Lead Free	Tape & Reel	-40°C to +85°C

NOTE: Parts that are ordered with a "G" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

Table 19. Pin 1 Orientation in Tape and Reel Packaging

Part Number Suffix	Pin 1 Orientation	Illustration
NLGI8	Quadrant 1 (EIA-481-C)	 Correct Pin 1 ORIENTATION CARRIER TAPE TOPSIDE (Round Sprocket Holes) USER DIRECTION OF FEED
NLGI/W	Quadrant 2 (EIA-481-D)	 Correct Pin 1 ORIENTATION CARRIER TAPE TOPSIDE (Round Sprocket Holes) USER DIRECTION OF FEED



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