GEARTOOTH SPEED SENSOR GS1012 Series



Description

The GS1012 series gear tooth sensors are Hall Effect devices designed for use in applications where ferrous edge detection or near zero speed sensing (without power up recognition) is needed.

Features and Benefits

- Immune to rotational alignment
- ESD resistant to 4kV (contact discharge)
- Mating connector: Delphi 12162280 and 12162279
- Discrete wire version: 20awg, tin plated polyolefin insulation.

Applications

- Exercise equipment
- Food processing equipment
- Speedometer





Dimensions mm

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Mechanical Specifications

Airgrap	Application dependent
Maximum Installation Torque	50 in-lbs (for a ¼ - 20 Hex Cap screw)

Electrical Specifications

Operating Voltage Range	5 - 24 VDC
Supply Voltage	5 - 24 VDC
Supply Current	6 mA max
Output Saturation Voltage	400 mV max
Output Current	20 mA max
Operating Temperature	-40° to +125°C
Storage Temperature Range	-40° to +125°C
Output Rise time	5µS
Output Fall time	5µS
Electrostatic Discharge Immunity	+3kV indirect contact, +4kV direct contact
Electric Field Radiated Immunity	At 10V/m (using 80% amplitude modulation @ 1kHz) from 26Mz to 1000 MHz
Electrical Fast Transient Test	+2kV on DC power supply
Immunity to Magnetic Fields	SAE J1113-22 (600 microT AC field; 5Hz to 2kHz; .2mT & 1mT DC field)
Conducted Immunity Test	Injected with 10Vrms from 150kHz to 80 MHz
Dielectric Withstand Voltage	MIL-STD-202F, Method 301 1000V applied for a minimum of one minute.
Insulation Resistance	MIL-STD-202F, Method 302, Test Condition B 500V applied for one minute.

Water Immersion	MIL-STD 202F, Method 104, Test Condition A
Salt Spray	MIL-STD-202F, Method 101, Test Condition B
Sinusoidal Vibration	MIL-STD-202F Method 204, Test Condition C from 55-2000 Hz
Random Vibration	MIL-STD-20F Method 214, Test Condition IC
Mechanical Shock	18 shocks at 50g's 11ms per Mil Std 202F

Recommended external pull-up resistor:



Open Collector Sinking Block Diagram





Specifications subject to change without notice.

For best results, we recommend targets made from low carbon cold rolled steel. Other factors that influence sensor performance include geartooth height and width, space between teeth, shape of the teeth and thickness of the target. As a general guideline, consider a target with the following minimum parameters:

		Distance	
Tooth Height	Tooth Width	Between Teeth	Target Thickness
.200"	.100"	.400"	.250"

Contact

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