

DATASHEET

Description

The 9DBU0241 is a member of IDT's 1.5V Ultra-Low-Power (ULP) PCIe family. It has integrated output terminations providing Zo=100ohms for direct connection to 100ohm transmission lines. The device has 2 output enables for clock management.

Recommended Application

1.5V PCIe Gen1-2-3 Zero-Delay/Fan-out Buffer (ZDB/FOB)

Output Features

 2 – 1-167MHz Low-Power (LP) HCSL DIF pairs w/Zo=100Ω

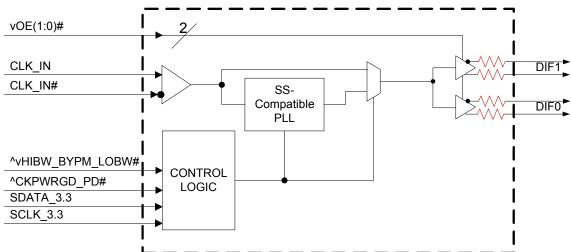
Key Specifications

- DIF cycle-to-cycle jitter <50ps
- DIF output-to-output skew <50ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- DIF bypass mode additive phase jitter is <300fs rms for PCle Gen3
- DIF bypass mode additive phase jitter <350fs rms for 12k-20MHz

Features/Benefits

- Direct connection to 100Ω transmission lines; saves 8 resistors compared to standard HCSL outputs
- 35mW typical power consumption in PLL mode; eliminates thermal concerns
- Spread Spectrum (SS) compatible; allows SS for EMI reduction
- OE# pins; support DIF power management
- HCSL-compatible differential input; can be driven by common clock sources
- SMBus-selectable features; optimize signal integrity to application
 - slew rate for each output
 - differential output amplitude
- Pin/SMBus selectable PLL bandwidth and PLL Bypass; optimize PLL to application
- Outputs blocked until PLL is locked; clean system start-up
- Device contains default configuration; SMBus interface not required for device control
- 3.3V tolerant SMBus interface works with legacy controllers
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

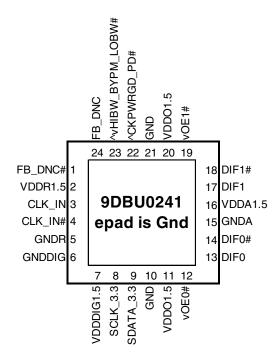
Block Diagram



1



Pin Configuration



24-pin VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor
 ^v prefix indicates internal 120KOhm pull up AND pull down resistor (biased to VDD/2)
 v prefix indicates internal 120KOhm pull down resistor

SMBus Address Selection Table

Address	+ Read/Write bit
1101101	X

Power Management Table

CKPWRGD PD#	CLK_IN	SMBus	OEx# Pin	DIF	x	PLL
CKFWKGD_FD#	CLK_IN	OEx bit	OLX# FIII	True O/P	Comp. O/P	FLL
0	X	X	X	Low	Low	Off
1	Running	0	Х	Low	Low	On ¹
1	Running	1	0	Running	Running	On ¹
1	Running	1	1	Low	Low	On ¹

^{1.} If Bypass mode is selected, the PLL will be off, and outputs will be running.

Power Connections

Pin Numb	Pin Number					
VDD	GND	Description				
2	5	Input receiver analog				
7	6	Digital Power				
11,20	10,21	DIF outputs				
16	15	PLL Analog				

Note: epad on this device is not electrically connected to the die. It should be connected to ground for best thermal performance.

PLL Operating Mode

		Byte1 [7:6]	Byte1 [4:3]
HiBW_BypM_LoBW#	MODE	Readback	Control
0	PLL Lo BW	00	00
M	Bypass	01	01
1	PLL Hi BW	11	11



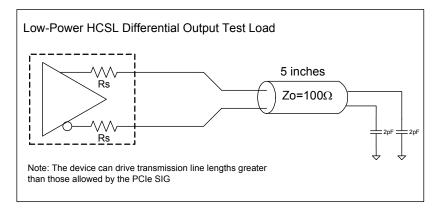
Pin Descriptions

Pin#	Pin Name	Pin Type	Description
1	FB_DNC#	DNC	Complement clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not connect anything to this pin.
2	VDDR1.5	PWR	1.5V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.
3	CLK_IN	IN	True Input for differential reference clock.
4	CLK_IN#	IN	Complementary Input for differential reference clock.
5	GNDR	GND	Analog Ground pin for the differential input (receiver)
6	GNDDIG	GND	Ground pin for digital circuitry
7	VDDDIG1.5	PWR	1.5V digital power (dirty power)
8	SCLK_3.3	IN	Clock pin of SMBus circuitry, 3.3V tolerant.
9	SDATA_3.3	I/O	Data pin for SMBus circuitry, 3.3V tolerant.
10	GND	GND	Ground pin.
11	VDDO1.5	PWR	Power supply for outputs, nominally 1.5V.
12	vOE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
13	DIF0	OUT	Differential true clock output
14	DIF0#	OUT	Differential Complementary clock output
15	GNDA	GND	Ground pin for the PLL core.
16	VDDA1.5	PWR	1.5V power for the PLL core.
17	DIF1	OUT	Differential true clock output
18	DIF1#	OUT	Differential Complementary clock output
19	vOE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
20	VDDO1.5	PWR	Power supply for outputs, nominally 1.5V.
21	GND	GND	Ground pin.
22	^CKPWRGD_PD#	IN	Input notifies device to sample latched inputs and start up on first high assertion. Low enters Power Down Mode, subsequent high assertions exit Power Down Mode. This pin has internal pull-up resistor.
23	^vHIBW_BYPM_LOBW#	LATCHED IN	Trilevel input to select High BW, Bypass or Low BW mode. See PLL Operating Mode Table for Details.
24	FB_DNC	DNC	True clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not connect anything to this pin.
25	ePad	GND	Connect epad to ground.

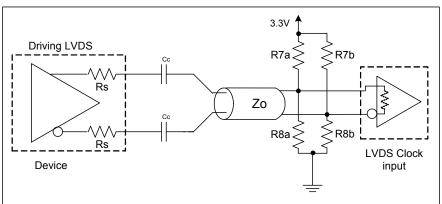
NOTE: DNC indicates Do Not Connect anything to this pin.



Test Loads



Driving LVDS



Driving LVDS inputs

	,	Value	
	Receiver has Receiver does not		
Component	termination	have termination	Note
R7a, R7b	10K ohm	140 ohm	
R8a, R8b	5.6K ohm	75 ohm	
Cc	0.1 uF	0.1 uF	
Vcm	1.2 volts	1.2 volts	



Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9DBU0241. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx		-0.5		2	V	1,2
Input Voltage	V_{IN}		-0.5		V _{DD} +0.5	٧	1,3
Input High Voltage, SMBus	V_{IHSMB}	SMBus clock and data pins			3.3	V	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	ç	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Clock Input Parameters

TA = T_{AMB}, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

AIVID, TIPE		· · · · · · · · · · · · · · · · · · ·					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input Common Mode Voltage - DIF_IN	V _{COM}	Common Mode Input Voltage	200		725	mV	1
Input Swing - DIF_IN	V _{SWING}	Differential value	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45	50	55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		150	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

³ Not to exceed 2.0V.

² Slew rate measured through +/-75mV window centered around differential zero



Electrical Characteristics-Input/Supply/Common Parameters-Normal Operating Conditions

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx	Supply voltage for core and analog	1.425	1.5	1.575	V	
Ambient Operating	T _{AMB}	Commmercial range	0	25	70	°C	1
Temperature		Industrial range	-40	25	85	°C	1
Input High Voltage	V_{IH}	Single-ended inputs, except SMBus	0.75 V _{DD}		$V_{DD} + 0.3$	V	
Input Mid Voltage	V_{IM}	Single-ended tri-level inputs ('_tri' suffix)	$0.4~V_{DD}$		0.6 V _{DD}	V	
Input Low Voltage	V_{IL}	Single-ended inputs, except SMBus	-0.3		0.25 V _{DD}	V	
	I_{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	
Input Current	I _{INP}	Single-ended inputs $V_{IN} = 0 \text{ V}$; Inputs with internal pull-up resistors	-200		200	uA	
	_	V _{IN} = VDD; Inputs with internal pull-down resistors					
Input Frequency	F_{ibyp}	Bypass mode	1		167	MHz	2
	F_{ipII}	100MHz PLL mode	20	100.00	110	MHz	2
Pin Inductance	L_{pin}				7	nH	1
	C _{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C _{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	pF	1,5
	C _{OUT}	Output pin capacitance			6	pF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock			1	ms	1,2
Input SS Modulation Frequency PCIe	f _{MODINPCle}	Allowable Frequency for PCIe Applications (Triangular Modulation)	30		33	kHz	
Input SS Modulation Frequency non-PCIe	f _{MODIN}	Allowable Frequency for non-PCle Applications (Triangular Modulation)	0		66	kHz	
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of single-ended control inputs			5	ns	2
Trise	t _R	Rise time of single-ended control inputs			5	ns	2
SMBus Input Low Voltage	V_{ILSMB}				0.6	V	
SMBus Input High Voltage	V_{IHSMB}	$V_{DDSMB} = 3.3V$, see note 4 for $V_{DDSMB} < 3.3V$	2.1		3.3	V	4
SMBus Output Low Voltage	V_{OLSMB}	@ I _{PULLUP}			0.4	V	
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	
Nominal Bus Voltage	$V_{\rm DDSMB}$	Bus Voltage	1.425		3.3	V	
SCLK/SDATA Rise Time	t _{RSMB}	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f _{MAXSMB}	Maximum SMBus operating frequency			400	kHz	6

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

 $^{^4}$ For $V_{\text{DDSMB}} < 3.3 V, \ V_{\text{IHSMB}} >= 0.8 x V_{\text{DDSMB}}$

⁵DIF_IN input

⁶The differential input clock must be running for the SMBus to be active



Electrical Characteristics-DIF Low-Power HCSL Outputs

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETERSYMBOLCONDITIONSMINTYPMAXUNITSNOTESSlew ratedV/dtScope averaging on, fast setting (100MHz)12.43.5V/ns1,2,3Slew rate matchingΔdV/dtScope averaging on, slow setting (100MHz)0.71.72.5V/ns1,2,3Slew rate matchingΔdV/dtSlew rate matching, Scope averaging on920%1,2,4Voltage HighVHIGHStatistical measurement on single-ended signal using oscilloscope math function. (Scope averaging on)6307508507Voltage LowVLOWaveraging on)-150261507Max VoltageVmaxMeasurement on single ended signal using7631150mV7	7		-					
Slew rate matching dV/dt Scope averaging on, slow setting (100MHz) 0.7 1.7 2.5 V/ns 1,2,3 Slew rate matching	PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate matching	Slow rote	dV/dt	Scope averaging on, fast setting (100MHz)	1	2.4	3.5	V/ns	1,2,3
Voltage High Voltage Low Volt	Siew rate	dV/dt	Scope averaging on, slow setting (100MHz)	0.7	1.7	2.5	V/ns	1,2,3
Voltage Low V _{LOW} using oscilloscope math function. (Scope averaging on) -150 26 150 7 Max Voltage Vmax Measurement on single ended signal using 763 1150 7	Slew rate matching	∆dV/dt	Slew rate matching, Scope averaging on		9	20	%	1,2,4
Voltage Low V _{LOW} averaging on) -150 26 150 7 Max Voltage Vmax Measurement on single ended signal using 763 1150 7	Voltage High	V_{HIGH}		630	750	850	m\/	7
Max Voltage Vmax Measurement on single ended signal using 763 1150 7	Voltage Low	V_{LOW}		-150	26	150	1117	7
	Max Voltage	Vmax	Measurement on single ended signal using		763	1150	mV	7
Min Voltage Vmin absolute value. (Scope averaging off) -300 22 7	Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	22] '''V	7
VswingVswingScope averaging off3001448mV1,2	Vswing	Vswing	Scope averaging off	300	1448		mV	1,2
Crossing Voltage (abs) Vcross_abs Scope averaging off 250 390 550 mV 1,5	Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	390	550	mV	1,5
Crossing Voltage (var) Δ-Vcross Scope averaging off 11 140 mV 1,6	Crossing Voltage (var)	Δ-Vcross	Scope averaging off		11	140	mV	1,6

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Current Consumption

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
	I _{DDR}	VDDR @100MHz		3	6	mA	1
Operating Supply Current	I _{DDDIG}	VDDIG, All outputs @100MHz		0.125	0.25	mA	1
	I _{DDAO}	VDDA+VDDO, PLL Mode, All outputs @100MHz		13	17	mA	1
Powerdown Current	I _{DDRPD}	VDDR, CKPWRGD_PD# = 0		0.1	0.3	mA	1,2,3
	I _{DDDIGPD}	VDDDIG, CKPWRGD_PD# = 0		0.1	0.2	mA	1,2
	I _{DDAOPD}	VDDA+VDDO, CKPWRGD_PD# = 0		0.7	1	mA	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

 $^{^6}$ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

⁷ At default SMBus settings.

² Input clock stopped.

³ In bypass mode, the PLL is off and IDDAO is ~50% of this value.



Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

Alvido, Caleler, Carrange	p	peration conditions, coe real Leads for Leading of					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
PLL Bandwidth	BW	-3dB point in High BW Mode (100MHz)	2.3	3.6	4.7	MHz	1,5
PLL Bandwidth	DW	-3dB point in Low BW Mode (100MHz)	1	1.6	2.5	MHz	1,5
PLL Jitter Peaking	t _{JPEAK}	Peak Pass band Gain (100MHz)		1.3	2.5	dB	1
Duty Cycle	t _{DC}	Measured differentially, PLL Mode	45	50	55	%	1
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-1.5	-1.1	0	%	1,3
Ckow Input to Output	t _{pdBYP}	Bypass Mode, V _T = 50%	3400	4301	5200	ps	1
Skew, Input to Output	t _{pdPLL}	PLL Mode V _T = 50%	0	50	150	ps	1,4
Skew, Output to Output	t _{sk3}	V _T = 50%		37	50	ps	1,4
Jitter, Cycle to cycle	+.	PLL mode		24	50	ps	1,2
Jitter, Cycle to cycle	t _{jcyc-cyc}	Additive Jitter in Bypass Mode		0.1	5	ps	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Phase Jitter Parameters

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

						INDUSTRY		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	LIMIT	UNITS	Notes
	t _{jphPCleG1}	PCIe Gen 1		30	58	86	ps (p-p)	1,2,3,5
	t	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.9	1.4	3	ps (rms)	1,2,3,5
Phase Jitter, PLL Mode	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		2.1	2.6	3.1	ps (rms)	1,2,3,5
That offer, I LE Wode	t _{jphPCleG3Com}	PCIe Gen 3 Common Clock Architecture (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.5	0.6	1	ps (rms)	1,2,3,5
	t _{jphPCleG3SRn}	PCIe Gen 3 Separate Reference No Spread (SRnS) (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.5	0.6	0.7	ps (rms)	1,2,3,5
	t _{iphPCleG1}	PCIe Gen 1		0.1	5	N/A	ps (p-p)	1,2,3,5
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.1	0.5	N/A	ps (rms)	1,2,3,4, 5
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.1	0.3	N/A	ps (rms)	1,2,3,4
Additive Phase Jitter, Bypass Mode	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.2	0.3	N/A	ps (rms)	1,2,3,4
by pass would	t _{jph125M0}	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		200	300	N/A	fs (rms)	1,6
	t _{jph125M1}	125MHz, 12KHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		313	350	N/A	fs (rms)	1,6

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

⁴ All outputs at default slew rate

⁵ The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

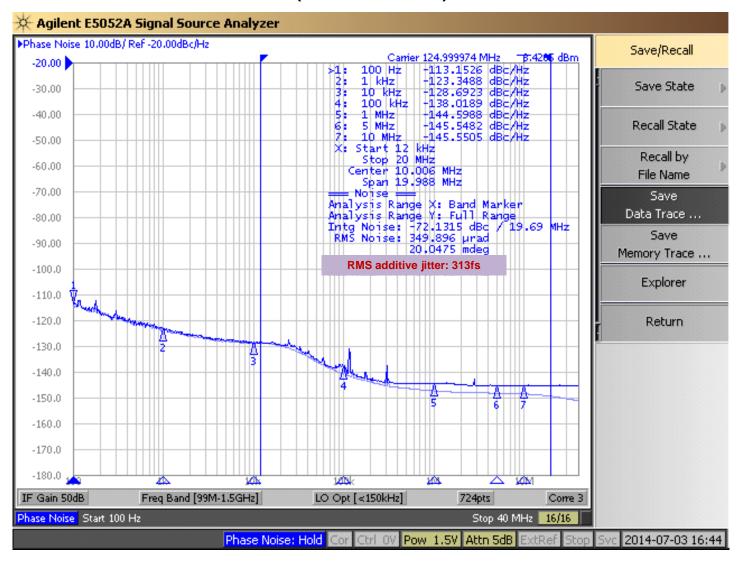
⁴ For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

⁵ Driven by 9FGU0831 or equivalent

⁶ Rohde&Schartz SMA100



Additive Phase Jitter Plot: 125M (12kHz to 20MHz)





General SMBus Serial Interface Information

How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

	Index Block Write Operation						
Controll	er (Host)		IDT (Slave/Receiver)				
Т	starT bit						
Slave A	Address						
WR	WRite						
			ACK				
Beginning	g Byte = N						
			ACK				
Data Byte	Count = X						
			ACK				
Beginnin	ig Byte N						
			ACK				
0		×					
0		X Byte	0				
0		е	0				
			0				
Byte N	+ X - 1						
			ACK				
Р	stoP bit						

Note: SMBus Address is Latched on SADR pin.

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

	Index Block F	Read C	peration
Cor	ntroller (Host)		IDT (Slave/Receiver)
Т	starT bit		
SI	ave Address		
WR	WRite		
			ACK
Begi	nning Byte = N		
			ACK
RT	Repeat starT		
SI	ave Address		
RD	ReaD		
			ACK
			Data Byte Count=X
	ACK		
			Beginning Byte N
	ACK		
		<u>e</u>	0
	0	X Byte	0
	0	×	0
	0		
			Byte N + X - 1
N	Not acknowledge		
Р	stoP bit		



SMBus Table: Output Enable Register ¹

Byte 0	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6		Reserved				1
Bit 5	DIF OE1	Output Enable	RW	Low/Low	Enabled	1
Bit 4		Reserved				1
Bit 3	DIF OE0	Output Enable	RW	Low/Low	Enabled	1
Bit 2		Reserved				1
Bit 1	Reserved					
Bit 0		Reserved				1

^{1.} A low on these bits will overide the OE# pin and force the differential output Low/Low

SMBus Table: PLL Operating Mode and Output Amplitude Control Register

Byte 1	Name	Control Function	Туре	0 1		Default
Bit 7	PLLMODERB1	PLL Mode Readback Bit 1	R	See PLL Operating Mode Table		Latch
Bit 6	PLLMODERB0	PLL Mode Readback Bit 0	R	Gee i LL Operai	ing wode rable	Latch
Bit 5	PLLMODE SWCNTRL	Enable SW control of PLL Mode	RW	Values in B1[7:6]	Values in B1[4:3]	0
ысэ	I LEWIODE_SWONTKE	Lilable 3W Control of LE Mode	1744	set PLL Mode	set PLL Mode	U
Bit 4	PLLMODE1	PLL Mode Control Bit 1	RW ¹	See PLL Operat	ing Mode Table	0
Bit 3	PLLMODE0	PLL Mode Control Bit 0	RW ¹	See FLL Operai	ing wode rable	0
Bit 2		Reserved	Reserved			
Bit 1	AMPLITUDE 1	Controls Output Amplitude	RW	00 = 0.55V	01 = 0.65V	1
Bit 0	AMPLITUDE 0	Controls Cutput Amplitude	RW	10= 0.75V	11 = 0.85V	0

^{1.} B1[5] must be set to a 1 for these bits to have any effect on the part.

SMBus Table: DIF Slew Rate Control Register

Byte 2	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6		Reserved				1
Bit 5	SLEWRATESEL DIF1	Slew Rate Selection	RW	Slow Setting	Fast Setting	1
Bit 4		Reserved				1
Bit 3	SLEWRATESEL DIF0	Slew Rate Selection	RW	Slow Setting	Fast Setting	1
Bit 2	Reserved					1
Bit 1	Reserved					1
Bit 0		Reserved				1

SMBus Table: FB Slew Rate Control Register

Byte 3	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6		Reserved				1
Bit 5		Reserved				0
Bit 4		Reserved				0
Bit 3		Reserved				0
Bit 2	Reserved					
Bit 1	Reserved					1
Bit 0	SLEWRATESEL FB	Adjust Slew Rate of FB	RW	Slow Setting	Fast Setting	1

Byte 4 is Reserved and reads back 'hFF



SMBus Table: Revision and Vendor ID Register

Byte 5	Name	Control Function	Туре	0	1	Default
Bit 7	RID3		R			0
Bit 6	RID2	Revision ID	R	A rev = 0000	0	
Bit 5	RID1	TREVISION ID	R	A lev -	- 0000	0
Bit 4	RID0		R			0
Bit 3	VID3		R			0
Bit 2	VID2	VENDOR ID	R	0001	– IDT	0
Bit 1	VID1	VENDORID	ID R 0001 = ID	יטו –	0	
Bit 0	VID0		R			1

SMBus Table: Device Type/Device ID

Byte 6	Name	Control Function	Туре	0	1	Default
Bit 7	Device Type1	Doving Type	R	00 = FGx, 01 =	DBx ZDB/FOB,	0
Bit 6	Device Type0	Device Type	R	10 = DMx, 1	1= DBx FOB	1
Bit 5	Device ID5		R			0
Bit 4	Device ID4	7	R			0
Bit 3	Device ID3	Device ID	R	000100 bina	ny or 02 hov	0
Bit 2	Device ID2	Device ID	R	000100 billa	ry or oz nex	0
Bit 1	Device ID1		R			1
Bit 0	Device ID0		R			0

SMBus Table: Byte Count Register

Byte 7	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				0
Bit 6		Reserved				0
Bit 5		Reserved				0
Bit 4	BC4		RW			0
Bit 3	BC3]	RW	Writing to this regist	er will configure how	1
Bit 2	BC2	Byte Count Programming	RW	many bytes will be r	ead back, default is	0
Bit 1	BC1		RW	= 8 b	ytes.	0
Bit 0	BC0		RW			0



Marking Diagrams





Notes:

- 1. "LOT" is the lot sequence number.
- 2. YYWW is the last two digits of the year and week that the part was assembled.
- 3. Line 2: truncated part number
- 4. "L" denotes RoHS compliant package.
- 5. "I" denotes industrial temperature range device.

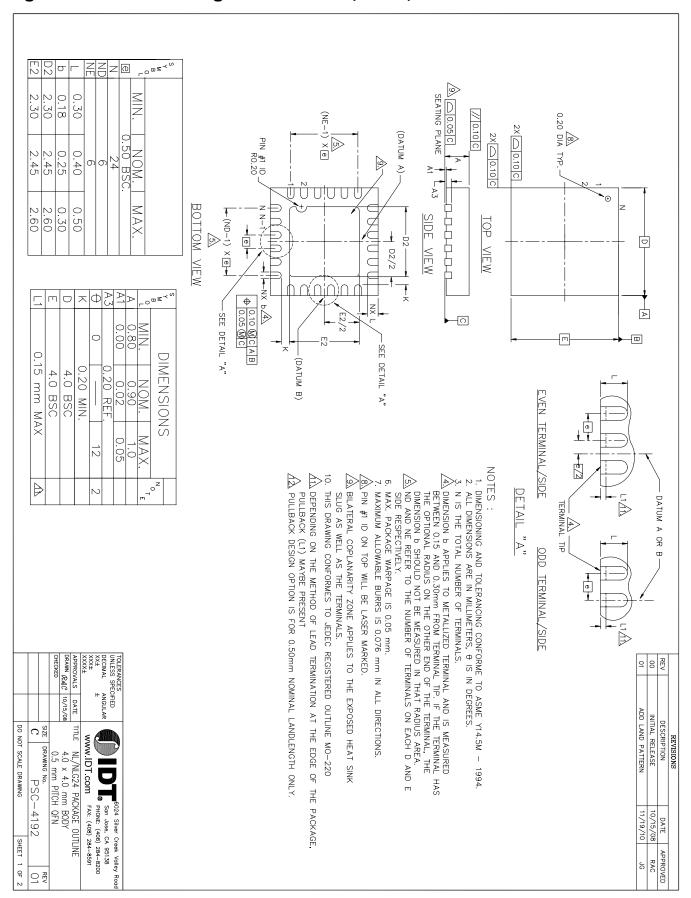
Thermal Characteristics

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
	Θ _{JC}	Junction to Case		62	°C/W	1
	Θ_{Jb}	Junction to Base		5.4	°C/W	1
Thermal Resistance	Θ_{JA0}	Junction to Air, still air	NLG20	50	°C/W	1
Theimai nesistance	Θ _{JA1}	Junction to Air, 1 m/s air flow	NLG24	43	°C/W	1
	Θ_{JA3}	Junction to Air, 3 m/s air flow		39	°C/W	1
	Θ _{JA5}	Junction to Air, 5 m/s air flow		38	°C/W	1

¹ePad soldered to board

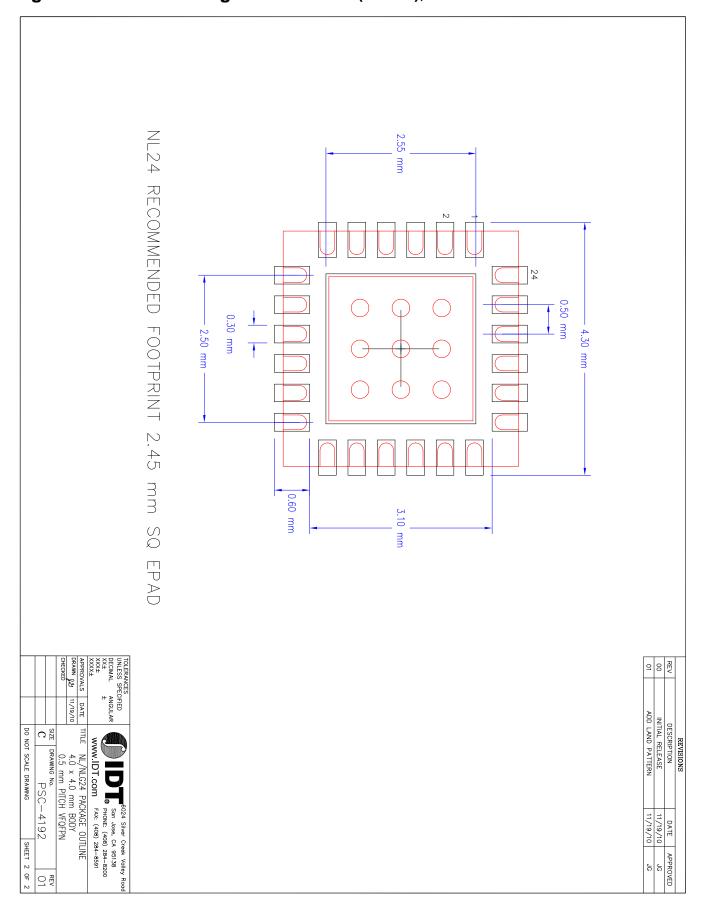


Package Outline and Package Dimensions (NLG24)





Package Outline and Package Dimensions (NLG24), cont.





Ordering Information

Part / Order Number	Shipping Packaging	Package	Temperature
9DBU0241AKLF	Tubes	24-pin VFQFPN	0 to +70° C
9DBU0241AKLFT	Tape and Reel	24-pin VFQFPN	0 to +70° C
9DBU0241AKILF	Tubes	24-pin VFQFPN	-40 to +85° C
9DBU0241AKILFT	Tape and Reel	24-pin VFQFPN	-40 to +85° C

[&]quot;LF" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

Revision History

Rev.	Initiator	Issue Date	Description	Page #
А	RDW	7/14/2014	Updated electrical tables with char data.	Various
			2. Added an additive phase jitter plot.	
			3. Added 12kHz to 20MHz <i>additive</i> phase jitter spec.	
			4. Updated Amplitude control bit descriptions in Byte 1.	
В	RDW	9/19/2014	Updated SMBus Input High/Low parameters conditions, MAX values,	6
			and footnotes.	
С	RDW	4/22/2015	Updated pin out and pin descriptions to show ePad on package	1-5
			connected to ground.	
			2. Updated front page text to standard format for these devices. Added	
			explicit bullet indicated Spread Spectrum compatibility.	
			3. Updated Clock Input Parameters table to be consistent with PCIe	
			Vswing parameter.	
			4. Minor updates to front page text for family consistency.	
			5. Add note about epad to Power Connections table.	

[&]quot;A" is the device revision designator (will not correlate with the datasheet revision).



Corporate Headquarters 6024 Silver Creek Valley Road San Jose, CA 95138 USA

Sales

1-800-345-7015 or 408-284-8200 Fax: 408-284-2775

www.IDT.com

Tech Support

email: clocks@idt.com

DISCLAIMER Integrated Device Technology, Inc. (IDT) and its subsidiaries reserve the right to modify the products and/or specifications described herein at any time and at IDT's sole discretion. All information in this document, including descriptions of product features and performance, is subject to change without notice. Performance specifications and the operating parameters of the described products are determined in the independent state and are not guaranteed to perform the same way when installed in customer products. The information contained herein is provided without representation or warranty of any kind, whether express or implied, including, but not limited to, the suitability of IDT's products for any particular purpose, an implied warranty of merchantability, or non-infringement of the intellectual property rights of others. This document is presented only as a guide and does not convey any license under intellectual property rights of IDT or any third parties.

IDT's products are not intended for use in applications involving extreme environmental conditions or in life support systems or similar devices where the failure or malfunction of an IDT product can be reasonably expected to significantly affect the health or safety of users. Anyone using an IDT product in such a manner does so at their own risk, absent an express, written agreement by IDT.

Integrated Device Technology, IDT and the IDT logo are registered trademarks of IDT. Product specification subject to change without notice. Other trademarks and service marks used herein, including protected names, logos and designs, are the property of IDT or their respective third party owners.

Copyright ©2015 Integrated Device Technology, Inc.. All rights reserved.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

IDT (Integrated Device Technology):

9DBU0241AKLF 9DBU0241AKILF 9DBU0241AKILFT 9DBU0241AKLFT