

# X28HC64

64k, 8k x 8-Bit 5 Volt, Byte Alterable EEPROM

FN8109  
Rev 4.00  
June 27, 2016

The **X28HC64** is an 8k x 8 EEPROM, fabricated with Intersil's proprietary, high performance, floating gate CMOS technology. Like all Intersil programmable nonvolatile memories, the X28HC64 is a 5V only device. It features the JEDEC approved pinout for byte-wide memories, compatible with industry standard RAMs.

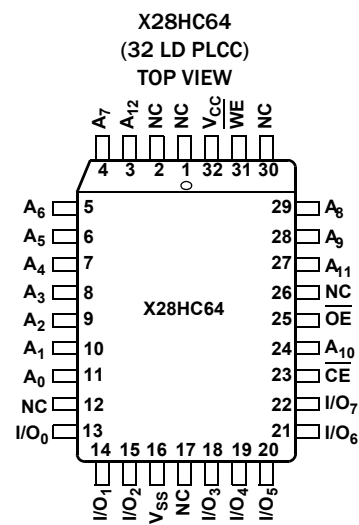
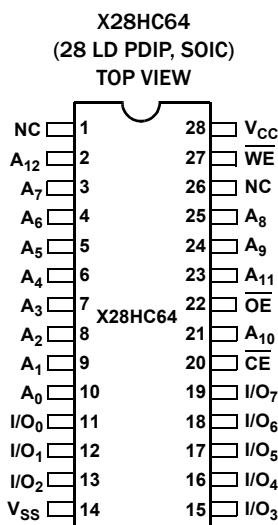
The X28HC64 supports a 64-byte page write operation, effectively providing a 32μs/byte write cycle, and enabling the entire memory to be typically written in 0.25 seconds. The X28HC64 also features DATA Polling and Toggle Bit Polling, two methods providing early end of write detection. In addition, the X28HC64 includes a user-optional software data protection mode that further enhances Intersil's hardware write protect capability.

Intersil EEPROMs are designed and tested for applications requiring extended endurance. Inherent data retention is greater than 100 years.

## Features

- 70ns access time
- Simple byte and page write
  - Single 5V supply
  - No external high voltages or  $V_{PP}$  control circuits
  - Self-timed
  - No erase before write
  - No complex programming algorithms
  - No overerase problem
- Low power CMOS
  - 40mA active current maximum
- 200μA standby current maximum
- Fast write cycle times
  - 64-byte page write operation
  - Byte or page write cycle: 2ms typical
  - Complete memory rewrite: 0.25s typical
  - Effective byte write cycle time: 32μs typical
- Software data protection
- End of write detection
  - DATA polling
  - Toggle bit
- High reliability
  - Endurance: 100,000 cycles
  - Data retention: 100 years
- JEDEC approved byte-wide pinout
- Pb-free available (RoHS compliant)

## Pin Configurations



## Ordering Information

| PART NUMBER   | PART MARKING     | TEMPERATURE RANGE (°C) | ACCESS TIME (ns) | PACKAGE                               | PKG. DWG. # |
|---|------------------|------------------------|------------------|---------------------------------------|-------------|
| X28HC64J-70 ( <a href="#">Notes 1, 6</a> )<br>(No longer available, recommended replacement: X28HC64JZ-70)      | X28HC64J-70 CY   | 0 to +70               | 70               | 32 Ld PLCC                            | N32.45x55   |
| X28HC64JIZ-70 ( <a href="#">Notes 1, 4, 6</a> )   | X28HC64JI-70 ZCY | -40 to +85             |                  | 32 Ld PLCC (RoHS Compliant)           | N32.45x55   |
| X28HC64JZ-70 ( <a href="#">Notes 1, 4, 6</a> )  | X28HC64J-70 ZCY  | 0 to +70               |                  | 32 Ld PLCC (RoHS Compliant)           | N32.45x55   |
| X28HC64SIZ-70 ( <a href="#">Notes 4, 6</a> )  | X28HC64SI-70 CYZ | -40 to +85             |                  | 28 Ld SOIC (300 mil) (RoHS Compliant) | M28.3       |
| X28HC64SZ-70 ( <a href="#">Notes 4, 6</a> )   | X28HC64S-70 CYZ  | 0 to +70               |                  | 28 Ld SOIC (300 mil) (RoHS Compliant) | M28.3       |
| X28HC64J-90 ( <a href="#">Notes 1, 6</a> )<br>(No longer available, recommended replacement: X28HC64JIZ-90)     | X28HC64J-90 CY   | 0 to +70               | 90               | 32 Ld PLCC                            | N32.45x55   |
| X28HC64JI-90 ( <a href="#">Notes 1, 3, 6</a> )<br>(No longer available, recommended replacement: X28HC64JIZ-90) | X28HC64JI-90 CY  | -40 to +85             |                  | 32 Ld PLCC                            | N32.45x55   |
| X28HC64JIZ-90 ( <a href="#">Notes 1, 4, 6</a> )   | X28HC64JI-90 ZCY | -40 to +85             |                  | 32 Ld PLCC (RoHS Compliant)           | N32.45x55   |
| X28HC64PIZ-90 ( <a href="#">Notes 4, 5</a> )  | X28HC64PI-90 CYZ | -40 to +85             |                  | 28 Ld PDIP (RoHS Compliant)           | E28.6       |
| X28HC64PZ-90 ( <a href="#">Notes 4, 5</a> )   | X28HC64P-90 CYZ  | 0 to +70               |                  | 28 Ld PDIP (RoHS Compliant)           | E28.6       |
| X28HC64J-12 ( <a href="#">Notes 1, 6</a> )<br>(No longer available, recommended replacement: X28HC64JZ-12)      | X28HC64J-12 CY   | 0 to +70               | 120              | 32 Ld PLCC                            | N32.45x55   |
| X28HC64JI-12 ( <a href="#">Notes 1, 6</a> )<br>(No longer available, recommended replacement: X28HC64JIZ-12)    | X28HC64JI-12 CY  | -40 to +85             |                  | 32 Ld PLCC                            | N32.45x55   |
| X28HC64JIZ-12 ( <a href="#">Notes 1, 4, 6</a> )   | X28HC64JI-12 ZCY | -40 to +85             |                  | 32 Ld PLCC (RoHS Compliant)           | N32.45x55   |
| X28HC64JZ-12* ( <a href="#">Notes 1, 4, 6</a> )   | X28HC64J-12 ZCY  | 0 to +70               |                  | 32 Ld PLCC (RoHS Compliant)           | N32.45x55   |
| X28HC64PIZ-12 ( <a href="#">Notes 4, 5</a> )  | X28HC64PI-12 CYZ | -40 to +85             |                  | 28 Ld PDIP (RoHS Compliant)           | E28.6       |
| X28HC64PZ-12 ( <a href="#">Notes 4, 5</a> )   | X28HC64P-12 CYZ  | 0 to +70               |                  | 28 Ld PDIP (RoHS Compliant)           | E28.6       |
| X28HC64SIZ-12 ( <a href="#">Notes 2, 4, 6</a> )   | X28HC64SI-12 CYZ | -40 to +85             |                  | 28 Ld SOIC (300 mil) (RoHS Compliant) | M28.3       |
| X28HC64SZ-12 ( <a href="#">Notes 4, 6</a> )   | X28HC64S-12 CYZ  | 0 to +70               |                  | 28 Ld SOIC (300 mil) (RoHS Compliant) | M28.3       |
|   |                  |                        |                  |                                       |             |

### NOTES:

1. Add "T1" suffix for 750 unit tape and reel option.
2. Add "T1" suffix for 1000 unit tape and reel option.
3. Add "T2" suffix for 750 unit tape and reel option.
4. These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and 100% matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.
5. Pb-free PDIPs can be used for through hole wave solder processing only. They are not intended for use in Reflow solder processing applications.
6. For Moisture Sensitivity Level (MSL), please see product information page for [X28HC64](#). For more information on MSL, please see tech brief [TB363](#).

## Pin Descriptions

| SYMBOL            | DESCRIPTION  |
|-------------------|--|
| $A_0$ - $A_{12}$  | Address Inputs. The Address inputs select an 8-bit memory location during a read or write operation.                               |
| $I/O_0$ - $I/O_7$ | Data Input/Output. Data is written to or read from the X28HC64 through the I/O pins.   |
| $\overline{WE}$   | Write Enable. The Write Enable input controls the writing of data to the X28HC64.  |
| $\overline{CE}$   | Chip Enable. The Chip Enable input must be LOW to enable all read/write operations. When CE is HIGH, power consumption is reduced. |
| $\overline{OE}$   | Output Enable. The Output Enable input controls the data output buffers and is used to initiate read operations.                   |
| $V_{CC}$          | +5V  |
| $V_{SS}$          | Ground   |
| NC                | No Connect   |

## Block Diagram

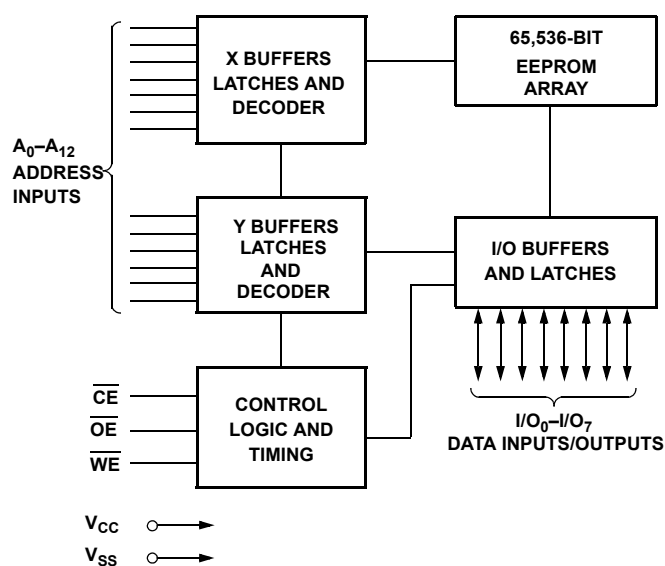


FIGURE 1. BLOCK DIAGRAM

## Device Operation

### Read

Read operations are initiated by both  $\overline{OE}$  and  $\overline{CE}$  LOW. The read operation is terminated by either  $\overline{CE}$  or  $\overline{OE}$  returning HIGH. This two line control architecture eliminates bus contention in a system environment. The data bus will be in a high impedance state when either  $\overline{OE}$  or  $\overline{CE}$  is HIGH.

### Write

Write operations are initiated when both  $\overline{CE}$  and  $\overline{WE}$  are LOW and  $\overline{OE}$  is HIGH. The X28HC64 supports both a  $\overline{CE}$  and  $\overline{WE}$  controlled write cycle. That is, the address is latched by the falling edge of either  $\overline{CE}$  or  $\overline{WE}$ , whichever occurs last. Similarly, the data is latched internally by the rising edge of either  $\overline{CE}$  or  $\overline{WE}$ , whichever occurs first. A byte write operation, once initiated, will automatically continue to completion, typically within 2ms.

### Page Write Operation

The page write feature of the X28HC64 allows the entire memory to be written in 0.25 seconds. Page write allows two to sixty-four bytes of data to be consecutively written to the X28HC64 prior to the commencement of the internal programming cycle. The host can fetch data from another device within the system during a page write operation (change the source address), but the page address ( $A_6$  through  $A_{12}$ ) for each subsequent valid write cycle to the part during this operation must be the same as the initial page address.

The page write mode can be initiated during any write operation. Following the initial byte write cycle, the host can write an additional one to sixty-three bytes in the same manner. Each successive byte load cycle, started by the  $\overline{WE}$  HIGH to LOW transition, must begin within 100 $\mu$ s of the falling edge of the preceding  $\overline{WE}$ . If a subsequent  $\overline{WE}$  HIGH to LOW transition is not detected within 100 $\mu$ s, the internal automatic programming cycle will commence. There is no page write window limitation. Effectively the page write window is infinitely wide, so long as the host continues to access the device within the byte load cycle time of 100 $\mu$ s.

### Write Operation Status Bits

The X28HC64 provides the user two write operation status bits. These can be used to optimize a system write cycle time. The status bits are mapped onto the I/O bus as shown in Figure 2.

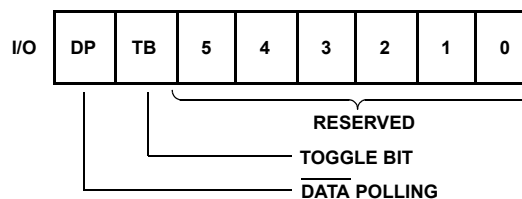


FIGURE 2. STATUS BIT ASSIGNMENT

**DATA Polling (I/O<sub>7</sub>)**

The X28HC64 features  $\overline{\text{DATA}}$  Polling as a method to indicate to the host system that the byte write or page write cycle has completed.  $\overline{\text{DATA}}$  Polling allows a simple bit test operation to determine the status of the X28HC64, eliminating additional interrupt inputs or external hardware. During the internal programming cycle, any attempt to read the last byte written will

produce the complement of that data on I/O<sub>7</sub> (i.e., write data = 0xxx xxxx, read data = 1xxx xxxx). Once the programming cycle is complete, I/O<sub>7</sub> will reflect true data.

$\overline{\text{DATA}}$  Polling can effectively reduce the time for writing to the X28HC64. The timing diagram in [Figure 3](#) illustrates the sequence of events on the bus. The software flow diagram in [Figure 4](#) illustrates one method of implementing the routine.

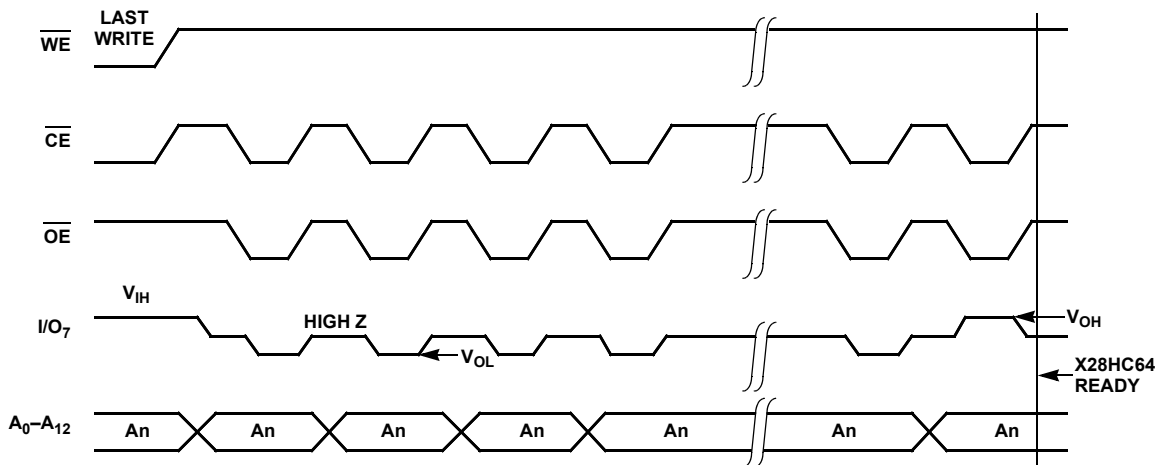


FIGURE 3.  $\overline{\text{DATA}}$  POLLING BUS SEQUENCE

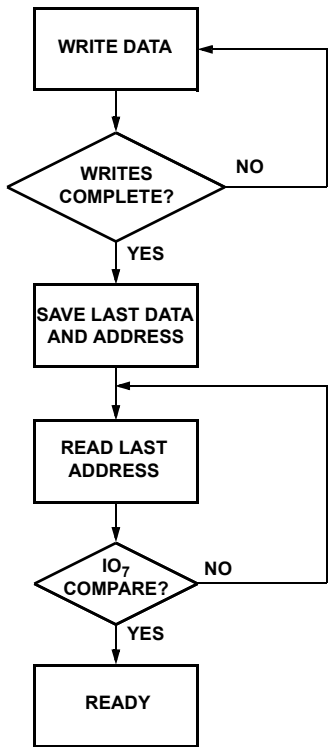


FIGURE 4.  $\overline{\text{DATA}}$  POLLING SOFTWARE FLOW

## Toggle Bit (I/O<sub>6</sub>)

The X28HC64 also provides another method for determining when the internal write cycle is complete. During the internal programming cycle I/O<sub>6</sub> will toggle from HIGH to LOW and LOW to HIGH on subsequent attempts to read the device. When the internal cycle is complete, the toggling will cease and the device will be accessible for additional read or write operations.

The Toggle Bit can eliminate the chore of saving and fetching the last address and data in order to implement DATA Polling. This can be especially helpful in an array comprised of multiple X28HC64 memories that is frequently updated. Toggle Bit Polling can also provide a method for status checking in multiprocessor applications. The timing diagram in [Figure 5](#) illustrates the sequence of events on the bus. The software flow diagram in [Figure 6](#) illustrates a method for polling the Toggle Bit.

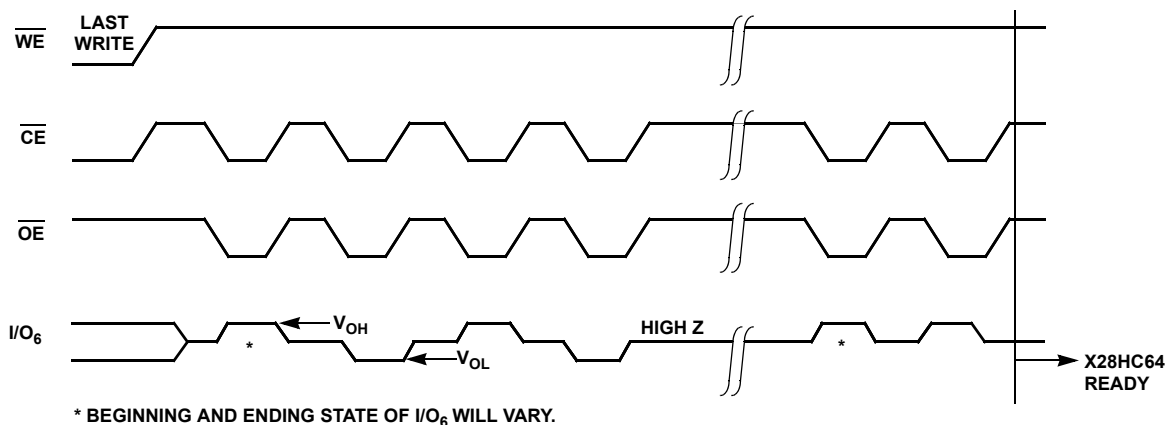


FIGURE 5. TOGGLE BIT BUS SEQUENCE

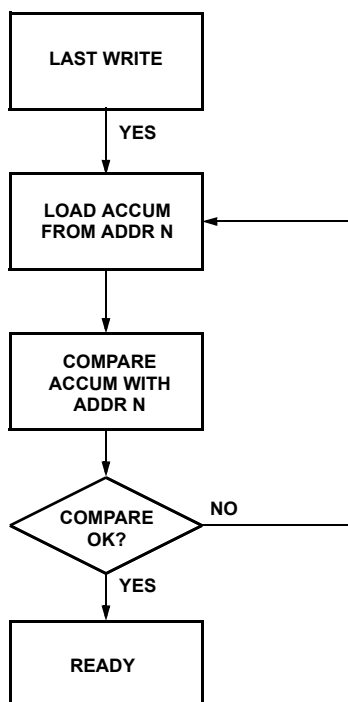


FIGURE 6. TOGGLE BIT SOFTWARE FLOW

## Hardware Data Protection

The X28HC64 provides two hardware features that protect nonvolatile data from inadvertent writes.

- **Default  $V_{CC}$  Sense**—All write functions are inhibited when  $V_{CC}$  is 3V typically.
- **Write Inhibit**—Holding either  $\overline{OE}$  LOW,  $\overline{WE}$  HIGH, or  $\overline{CE}$  HIGH will prevent an inadvertent write cycle during power-up and power-down, maintaining data integrity.

## Software Data Protection

The X28HC64 offers a software controlled data protection feature. The X28HC64 is shipped from Intersil with the software data protection NOT ENABLED; that is, the device will be in the standard operating mode. In this mode data should be protected during power-up/power-down operations through the use of external circuits. The host would then have open read and write access of the device once  $V_{CC}$  was stable.

The X28HC64 can be automatically protected during power-up and power-down without the need for external circuits by employing the software data protection feature. The internal software data protection circuit is enabled after the first write operation utilizing the software algorithm. This circuit is

nonvolatile and will remain set for the life of the device, unless the reset command is issued.

Once the software protection is enabled, the X28HC64 is also protected from inadvertent and accidental writes in the powered-up state. That is, the software algorithm must be issued prior to writing additional data to the device.

### Software Algorithm

Selecting the software data protection mode requires the host system to precede data write operations by a series of three write operations to three specific addresses. Refer to [Figures 7](#) and [8](#) for the sequence. The 3-byte sequence opens the page write window, enabling the host to write from 1 to 64 bytes of data. Once the page load cycle has been completed, the device will automatically be returned to the data protected state.

Regardless of whether the device has previously been protected or not, once the software data protection algorithm is used, the X28HC64 will automatically disable further writes unless another command is issued to deactivate it. If no further commands are issued, the X28HC64 will be write protected during power-down and after any subsequent power-up.

**Note:** Once initiated, the sequence of write operations should not be interrupted.

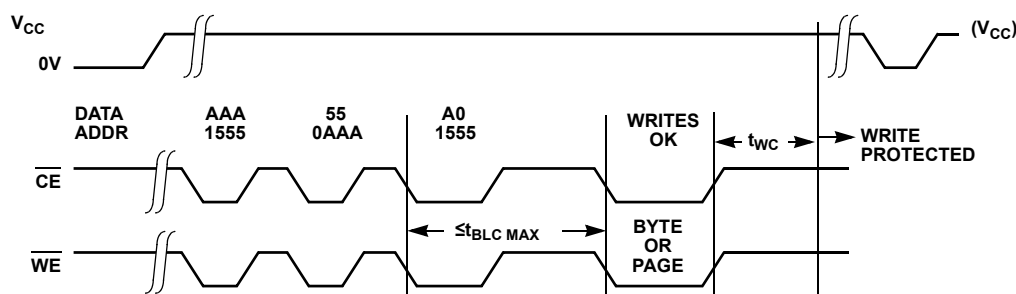


FIGURE 7. TIMING SEQUENCE—BYTE OR PAGE WRITE

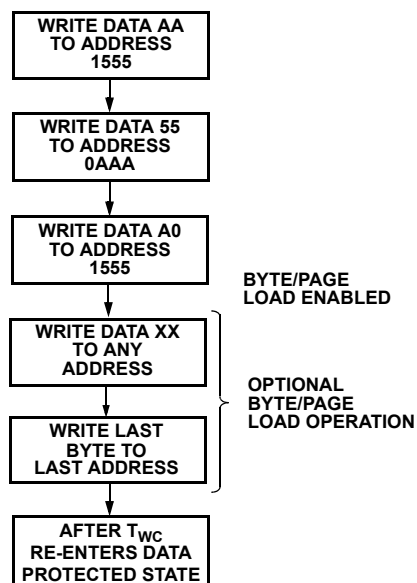


FIGURE 8. WRITE SEQUENCE FOR SOFTWARE DATA PROTECTION

## Resetting Software Data Protection

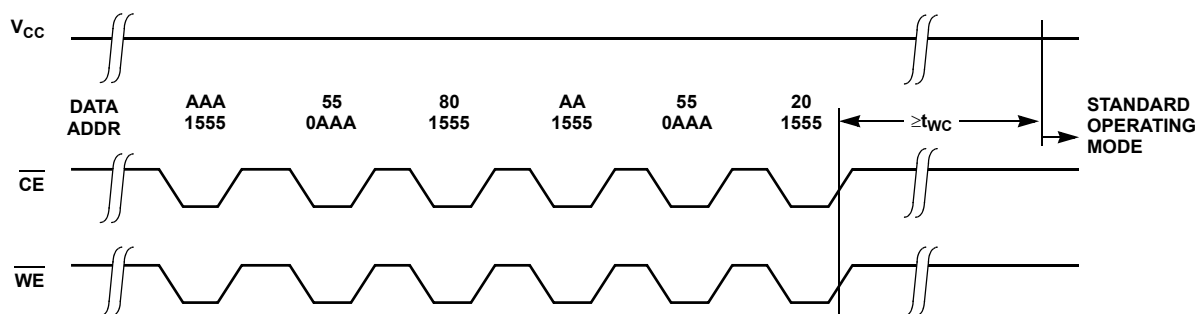


FIGURE 9. RESET SOFTWARE DATA PROTECTION TIMING SEQUENCE

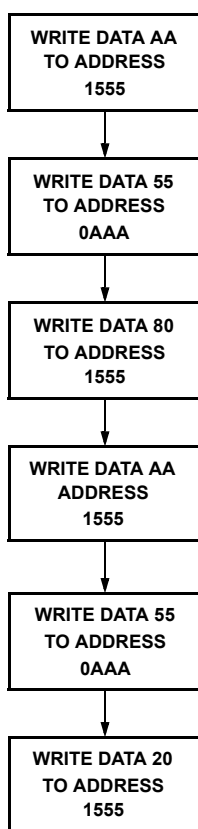


FIGURE 10. SOFTWARE SEQUENCE TO DEACTIVATE SOFTWARE DATA PROTECTION

In the event the user wants to deactivate the software data protection feature for testing or reprogramming in an EEPROM programmer, the following six step algorithm will reset the internal protection circuit. After  $t_{WC}$ , the X28HC64 will be in standard operating mode.

Note: Once initiated, the sequence of write operations should not be interrupted.

## System Considerations

Because the X28HC64 is frequently used in large memory arrays, it is provided with a two-line control architecture for both read and write operations. Proper usage can provide the lowest possible power dissipation, and eliminate the possibility of contention where multiple I/O pins share the same bus.

To gain the most benefit, it is recommended that  $\overline{CE}$  be decoded from the address bus, and be used as the primary device selection input. Both  $\overline{OE}$  and  $\overline{WE}$  would then be common among all devices in the array. For a read operation, this assures that all deselected devices are in their standby mode, and that only the selected device(s) is/are outputting data on the bus.

Because the X28HC64 has two power modes, standby and active, proper decoupling of the memory array is of prime

concern. Enabling  $\overline{CE}$  will cause transient current spikes. The magnitude of these spikes is dependent on the output capacitive loading of the I/Os. Therefore, the larger the array sharing a common bus, the larger the transient spikes. The voltage peaks associated with the current transients can be suppressed by the proper selection and placement of decoupling capacitors. As a minimum, it is recommended that a 0.1 $\mu$ F high frequency ceramic capacitor be used between  $V_{CC}$  and  $V_{SS}$  at each device. Depending on the size of the array, the value of the capacitor may have to be larger.

In addition, it is recommended that a 4.7 $\mu$ F electrolytic bulk capacitor be placed between  $V_{CC}$  and  $V_{SS}$  for each eight devices employed in the array. This bulk capacitor is employed to overcome the voltage droop caused by the inductive effects of the PC board traces.

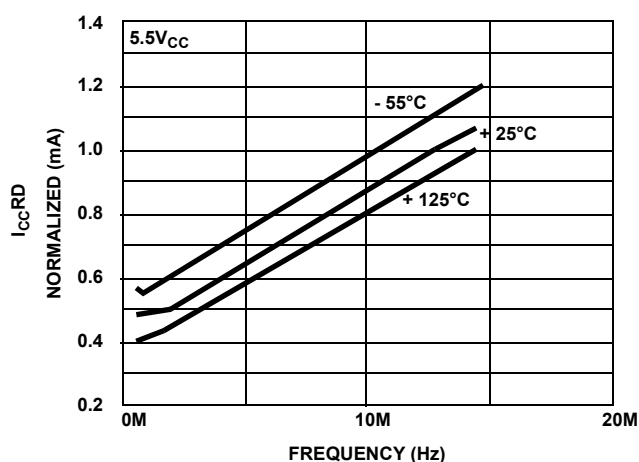


FIGURE 11. NORMALIZED  $I_{CC(RD)}$  BY TEMPERATURE OVER FREQUENCY DATA PROTECTION

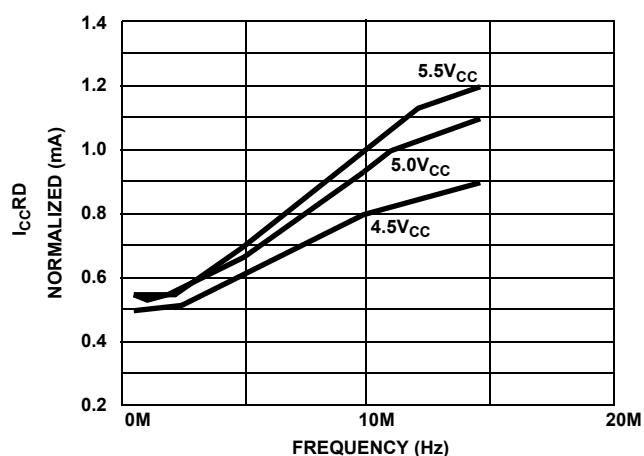


FIGURE 12. NORMALIZED  $I_{CC(RD)}$  AT 25% OVER THE  $V_{CC}$  RANGE AND FREQUENCY

## Absolute Maximum Ratings

|   |                 |
|---|-----------------|
| Temperature Under Bias                      |                 |
| X28HC64                                     | -10°C to +85°C  |
| X28HC64I                                    | -65°C to +135°C |
| Storage Temperature                         |                 |
|   | -65°C to +150°C |
| Voltage on any Pin with Respect to $V_{SS}$ |                 |
|   | -1V to +7V      |
| DC Output Current                           |                 |
|   | 5mA             |

## Thermal Information

| Thermal Resistance (Typical)   | $\theta_{JA}$ (°C/W)      | $\theta_{JC}$ (°C/W) |
|--|---------------------------|----------------------|
| 32 Ld PLCC Package ( <a href="#">Notes 7, 9</a> ) . . . . .              | 41                        | 19                   |
| 28 Ld SOIC Package ( <a href="#">Notes 7, 9</a> ) . . . . .              | 46                        | 19                   |
| 28 Ld PDIP Package ( <a href="#">Notes 8, 9</a> ) . . . . .              | 53                        | 21                   |
| Pb-Free Reflow Profile . . . . .   | see <a href="#">TB493</a> |                      |
| *Pb-free PDIPs can be used for through hole wave solder processing only. |                           |                      |
| They are not intended for use in Reflow solder processing applications.  |                           |                      |

## Recommended Operating Conditions

|                              |                |
|------------------------------|----------------|
| Commercial Temperature Range | 0°C to +70°C   |
| Industrial Temperature Range | -40°C to +85°C |
| Supply Voltage Range         |                |
| X28HC64                      | 5V ±10%        |

**CAUTION:** Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

### NOTES:

- $\theta_{JA}$  is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief [TB379](#) for details.
- $\theta_{JA}$  is measured with the component mounted on a low effective thermal conductivity test board in free air. See Tech Brief [TB379](#) for details.
- For  $\theta_{JC}$ , the "case temp" location is taken at the package top center.

## DC Electrical Specifications

 Over recommended operating conditions, unless otherwise specified.

| PARAMETER                                | SYMBOL    | TEST CONDITIONS   | MIN<br>(Note 10) | TYP<br>(Note 11) | MAX<br>(Note 10) | UNIT |
|--|-----------|---|------------------|------------------|------------------|------|
| $V_{CC}$ Current (Active) (TTL Inputs)   | $I_{CC}$  | $\overline{CE} = \overline{OE} = V_{IL}$ , $\overline{WE} = V_{IH}$ , All I/O's = open, address inputs = TTL levels at $f = 10\text{MHz}$ |                  | 15               | 40               | mA   |
| $V_{CC}$ Current (Standby) (TTL Inputs)  | $I_{SB1}$ | $\overline{CE} = V_{IH}$ , $\overline{OE} = V_{IL}$ , All I/O's = open, other inputs = $V_{IH}$   |                  | 1                | 2                | mA   |
| $V_{CC}$ Current (Standby) (CMOS Inputs) | $I_{SB2}$ | $\overline{CE} = V_{CC} - 0.3V$ , $\overline{OE} = GND$ , All I/O's = open, other inputs = $V_{CC} - 0.3V$                                |                  | 100              | 200              | μA   |
| Input Leakage Current                    | $I_{LI}$  | $V_{IN} = V_{SS}$ to $V_{CC}$   |                  |                  | ±10              | μA   |
| Output Leakage Current                   | $I_{LO}$  | $V_{OUT} = V_{SS}$ to $V_{CC}$ , $\overline{CE} = V_{IH}$   |                  |                  | ±10              | μA   |
| Input LOW Voltage (Note 12)              | $V_{IL}$  |   | -1               |                  | 0.8              | V    |
| Input HIGH Voltage (Note 12)             | $V_{IH}$  |   | 2                |                  | $V_{CC} + 1$     | V    |
| Output LOW Voltage                       | $V_{OL}$  | $I_{OL} = 5\text{mA}$   |                  |                  | 0.4              | V    |
| Output HIGH Voltage                      | $V_{OH}$  | $I_{OH} = -5\text{mA}$  | 2.4              |                  |                  | V    |

### NOTES:

- Parameters with MIN and/or MAX limits are 100% tested at +25°C, unless otherwise specified. Temperature limits established by characterization and are not production tested.
- Typical values are for  $T_A = +25^\circ\text{C}$  and nominal supply voltage.
- $V_{IL}$  minimum and  $V_{IH}$  maximum are for reference only and are not tested.

## Endurance and Data Retention

 The endurance and data retention specifications are established by characterization and are not production tested.

| PARAMETER         | MIN     | MAX | UNIT   |
|-------------------|---------|-----|--------|
| Minimum Endurance | 100,000 |     | Cycles |
| Data Retention    | 100     |     | Years  |

## Power-Up Timing

| PARAMETER                             | SYMBOL    | TYP<br>(Note 11) | UNIT          |
|---------------------------------------|-----------|------------------|---------------|
| Power-Up to Read Operation (Note 13)  | $t_{PUR}$ | 100              | $\mu\text{s}$ |
| Power-Up to Write Operation (Note 13) | $t_{PUW}$ | 5                | ms            |

## Capacitance $T_A = +25^\circ\text{C}$ , $f = 1\text{MHz}$ , $V_{CC} = 5\text{V}$

| PARAMETER                          | SYMBOL    | TEST CONDITIONS       | MAX | UNIT |
|------------------------------------|-----------|-----------------------|-----|------|
| Input/output Capacitance (Note 13) | $C_{I/O}$ | $V_{I/O} = 0\text{V}$ | 10  | pF   |
| Input Capacitance (Note 13)        | $C_{IN}$  | $V_{IN} = 0\text{V}$  | 6   | pF   |

NOTE:

13. This parameter is periodically sampled and not 100% tested.





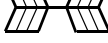
TABLE 1. AC CONDITIONS OF TEST

|                                |          |
|--------------------------------|----------|
| Input Pulse Levels             | 0V to 3V |
| Input Rise and Fall Times      | 5ns      |
| Input and Output Timing Levels | 1.5V     |

TABLE 2. MODE SELECTION

| $\overline{\text{CE}}$ | $\overline{\text{OE}}$ | $\overline{\text{WE}}$ | MODE                      | I/O       | POWER   |
|------------------------|------------------------|------------------------|---------------------------|-----------|---------|
| L                      | L                      | H                      | Read                      | $D_{OUT}$ | Active  |
| L                      | H                      | L                      | Write                     | $D_{IN}$  | Active  |
| H                      | X                      | X                      | Standby and write inhibit | High Z    | Standby |
| X                      | L                      | X                      | Write inhibit             | -         | -       |
| X                      | X                      | H                      | Write inhibit             | -         | -       |

## Symbol Table

| WAVEFORM   | INPUTS                      | OUTPUTS                       |
|--|-----------------------------|-------------------------------|
|    | Must be steady              | Will be steady                |
|    | May change from LOW to HIGH | Will change from LOW to HIGH  |
|    | May change from HIGH to LOW | Will change from HIGH to LOW  |
|  | Don't Care: Changes Allowed | Changing: State Not Known     |
|  | N/A                         | Center Line is High Impedance |

## Equivalent AC Load Circuits

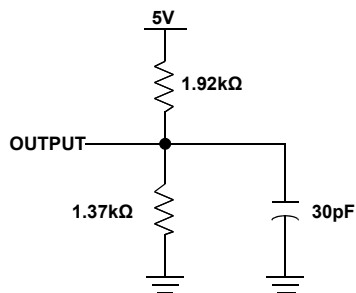


FIGURE 13. EQUIVALENT AC LOAD CIRCUITS

## AC Electrical Specifications

### Read Cycle Limits

Over the recommended operating conditions unless otherwise specified.

| PARAMETER                                       | SYMBOL    | X28HC64-70       |                  | X28HC64-90       |                  | X28HC64-12       |                  | UNIT |
|---|-----------|------------------|------------------|------------------|------------------|------------------|------------------|------|
|   |           | MIN<br>(Note 10) | MAX<br>(Note 10) | MIN<br>(Note 10) | MAX<br>(Note 10) | MIN<br>(Note 10) | MAX<br>(Note 10) |      |
| Read Cycle Time                                 | $t_{RC}$  | 70               |                  | 90               |                  | 120              |                  | ns   |
| Chip Enable Access Time                         | $t_{CE}$  |                  | 70               |                  | 90               |                  | 120              | ns   |
| Address Access Time                             | $t_{AA}$  |                  | 70               |                  | 90               |                  | 120              | ns   |
| Output Enable Access Time                       | $t_{OE}$  |                  | 35               |                  | 40               |                  | 50               | ns   |
| $\overline{CE}$ LOW to Active Output (Note 14)  | $t_{LZ}$  | 0                |                  | 0                |                  | 0                |                  | ns   |
| $\overline{OE}$ LOW to Active Output (Note 14)  | $t_{OLZ}$ | 0                |                  | 0                |                  | 0                |                  | ns   |
| $\overline{CE}$ HIGH to High Z Output (Note 14) | $t_{HZ}$  |                  | 30               |                  | 30               |                  | 30               | ns   |
| $\overline{OE}$ HIGH to High Z Output (Note 14) | $t_{OHZ}$ |                  | 30               |                  | 30               |                  | 30               | ns   |
| Output Hold from Address Change                 | $t_{OH}$  | 0                |                  | 0                |                  | 0                |                  | ns   |

NOTE:

14.  $t_{LZ}$  minimum,  $t_{HZ}$ ,  $t_{OLZ}$  minimum, and  $t_{OHZ}$  are periodically sampled and not 100% tested.  $t_{HZ}$  maximum and  $t_{OHZ}$  maximum are measured from the point when  $\overline{CE}$  or  $\overline{OE}$  return HIGH (whichever occurs first) to the time when the outputs are no longer driven.

### Read Cycle

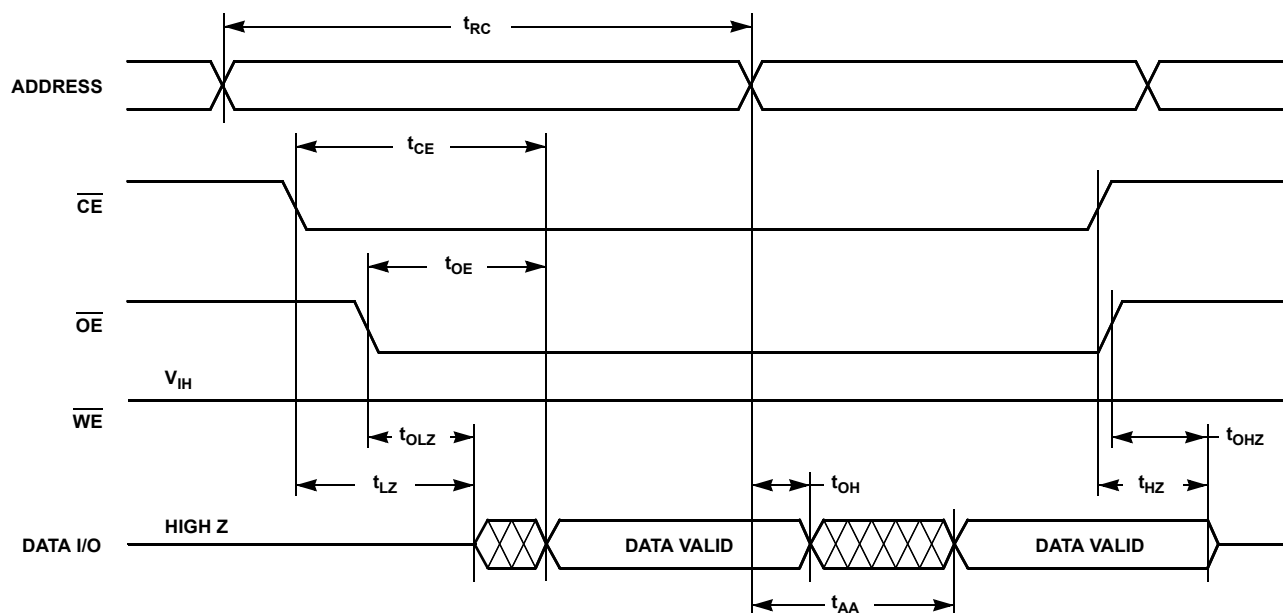


FIGURE 14. READ CYCLE

## Write Cycle Limits

| PARAMETER                               | SYMBOL    | MIN<br>(Note 10) | TYP<br>(Note 11) | MAX<br>(Note 10) | UNIT    |
|---|-----------|------------------|------------------|------------------|---------|
| Write Cycle Time (Note 15)              | $t_{WC}$  |                  | 2                | 5                | ms      |
| Address Set-Up Time                     | $t_{AS}$  | 0                |                  |                  | ns      |
| Address Hold Time                       | $t_{AH}$  | 50               |                  |                  | ns      |
| Write Set-Up Time                       | $t_{CS}$  | 0                |                  |                  | ns      |
| Write Hold Time                         | $t_{CH}$  | 0                |                  |                  | ns      |
| $\overline{CE}$ Pulse Width             | $t_{CW}$  | 50               |                  |                  | ns      |
| $\overline{OE}$ High Set-Up Time        | $t_{OES}$ | 0                |                  |                  | ns      |
| $\overline{OE}$ High Hold Time          | $t_{OEH}$ | 0                |                  |                  | ns      |
| $\overline{WE}$ Pulse Width             | $t_{WP}$  | 50               |                  |                  | ns      |
| $\overline{WE}$ HIGH Recovery (Note 16) | $t_{WPH}$ | 50               |                  |                  | ns      |
| Data Valid (Note 16)                    | $t_{DV}$  |                  |                  | 1                | $\mu$ s |
| Data Setup                              | $t_{DS}$  | 50               |                  |                  | ns      |
| Data Hold                               | $t_{DH}$  | 0                |                  |                  | ns      |
| Delay to Next Write (Note 16)           | $t_{DW}$  | 10               |                  |                  | $\mu$ s |
| Byte Load Cycle                         | $t_{BLC}$ | 0.15             |                  | 100              | $\mu$ s |

### NOTES:

15.  $t_{WC}$  is the minimum cycle time to be allowed from the system perspective unless polling techniques are used. It is the maximum time the device requires to automatically complete the internal write operation.

16.  $t_{WPH}$  and  $t_{DW}$  are periodically sampled and not 100% tested.

## $\overline{WE}$ Controlled Write Cycle

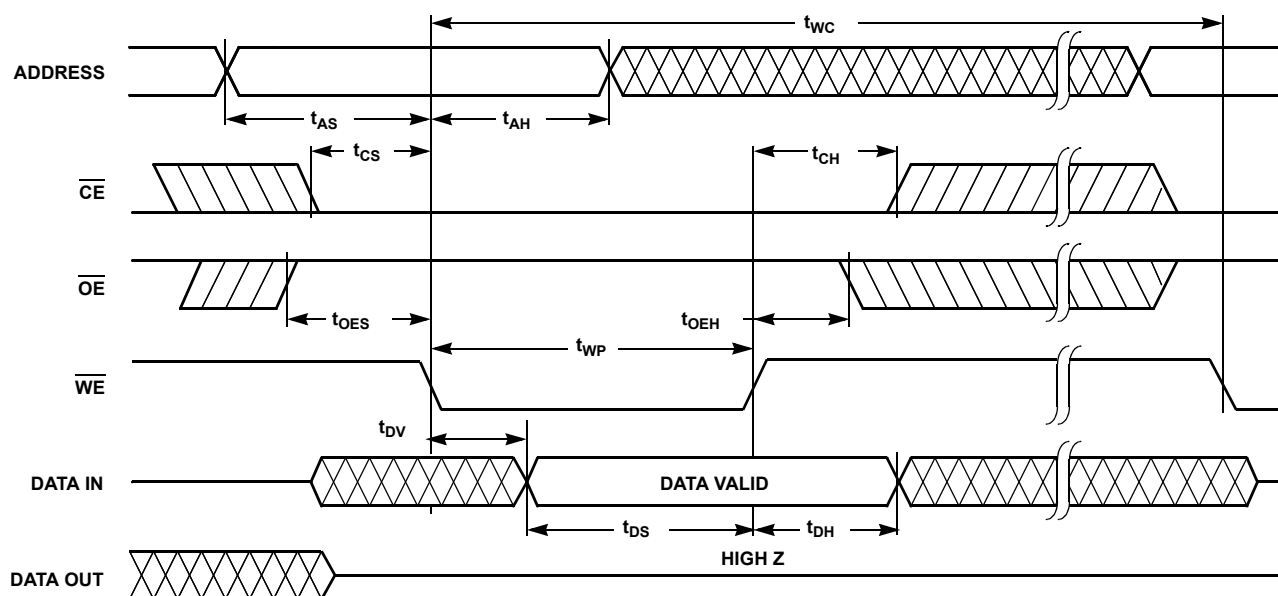
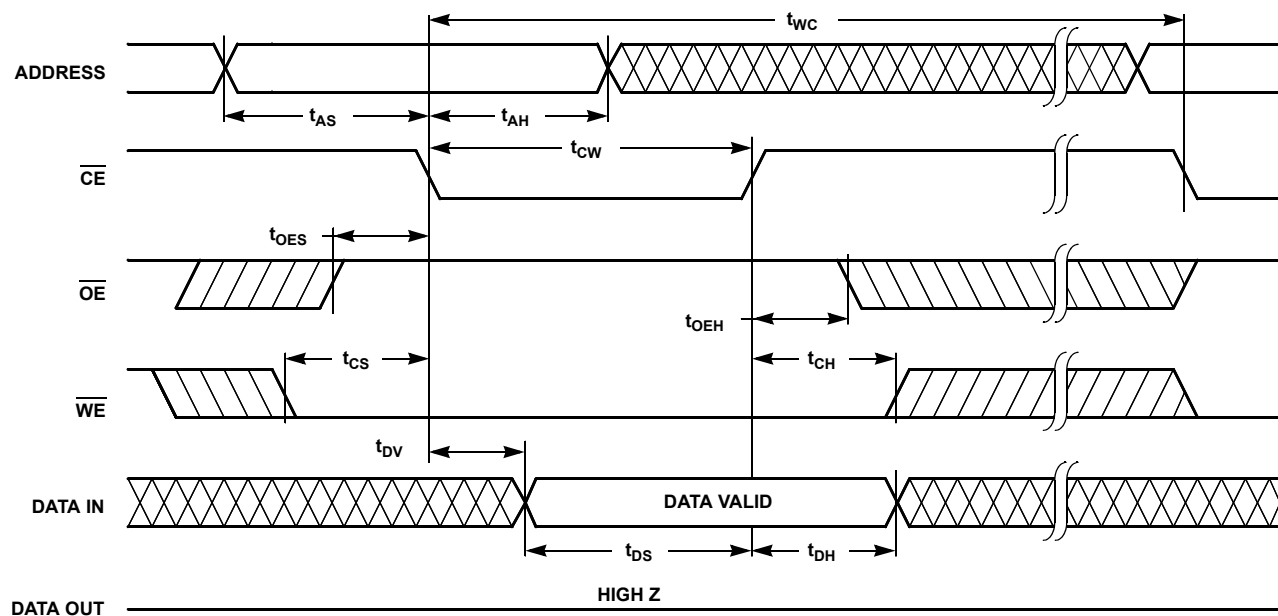
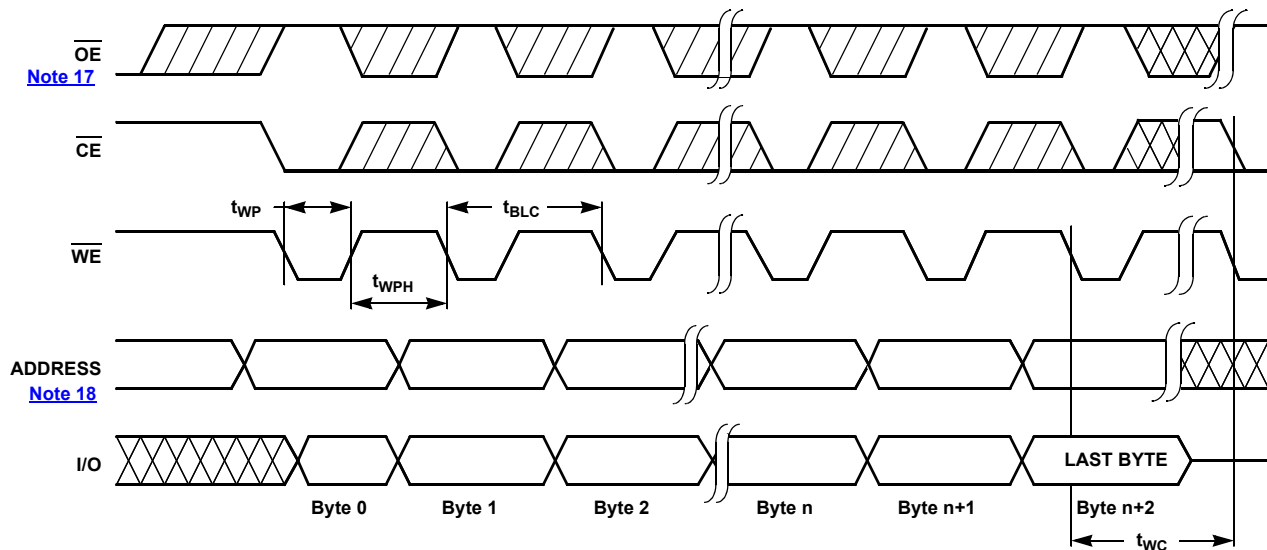


FIGURE 15.  $\overline{WE}$  CONTROLLED WRITE CYCLE

FIGURE 16.  $\overline{\text{CE}}$  CONTROLLED WRITE CYCLE

\*For each successive write within the page write operation,  $A_6$ – $A_{12}$  should be the same or writes to an unknown address could occur.

FIGURE 17. PAGE WRITE CYCLE

## NOTES:

17. Between successive byte writes within a page write operation,  $\overline{\text{OE}}$  can be strobed LOW: e.g. this can be done with  $\overline{\text{CE}}$  and  $\overline{\text{WE}}$  HIGH to fetch data from another memory device within the system for the next write; or with  $\overline{\text{WE}}$  HIGH and  $\overline{\text{CE}}$  LOW effectively performing a polling operation.
18. The timings shown above are unique to page write operations. Individual byte load operations within the page write must conform to either the  $\overline{\text{CE}}$  or  $\overline{\text{WE}}$  controlled write cycle timing.

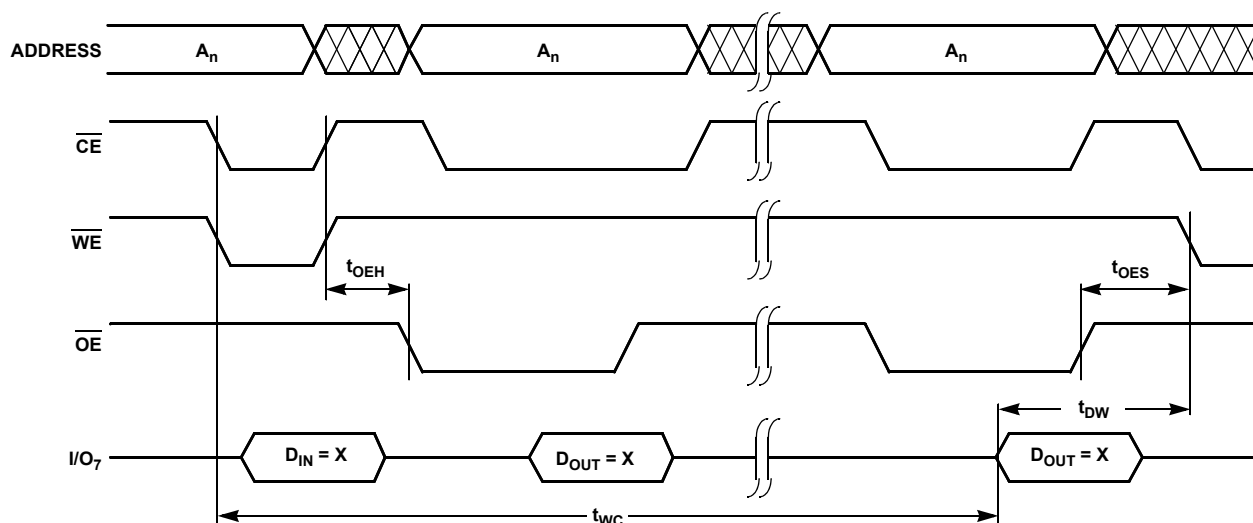
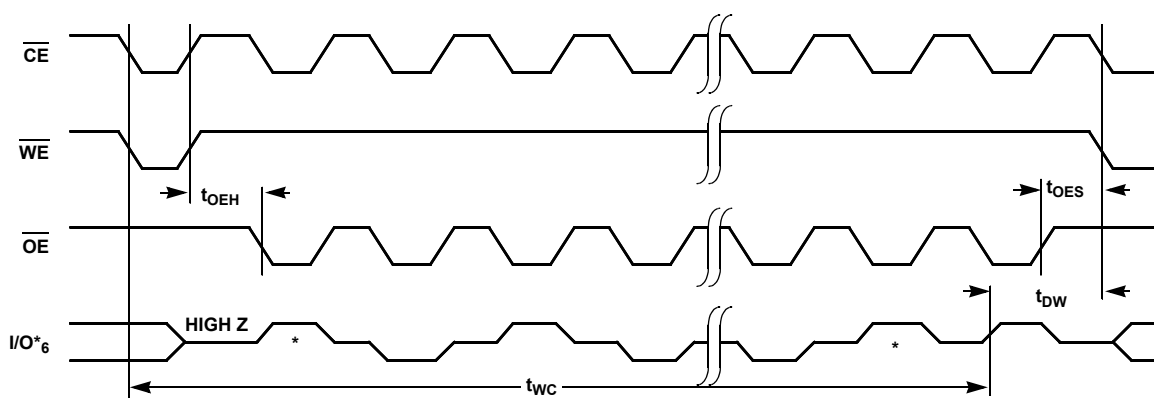


FIGURE 18. DATA POLLING TIMING DIAGRAM (Note 19)



\* I/O<sub>6</sub> beginning and ending state will vary, depending upon actual t<sub>WC</sub>.

FIGURE 19. TOGGLE BIT TIMING DIAGRAM (Note 19)

## NOTE:

19. Polling operations are by definition read cycles and are therefore subject to read cycle timings.

## Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

| DATE            | REVISION | CHANGE  |
|-----------------|----------|---|
| June 27, 2016   | FN8109.4 | Updated entire datasheet applying Intersil's new standards.<br>Updated the Ordering Information table by adding Note 2, updated other tape and reel notes, updated all of the part marking and added Note 6.<br>Added Thermal Information (Theta JA, Theta JC, and applicable notes) on page 9.<br>Added "The endurance and data retention specifications are established by characterization and are not production tested" to the "Endurance and Data Retention" table. |
| August 18, 2015 | FN8109.3 | - Updated Ordering Information Table on page 2.<br>- Added Revision History and About Intersil sections.<br>- Updated POD M28.3 to latest revision changes are as follow:<br>Added land pattern.  |

## About Intersil

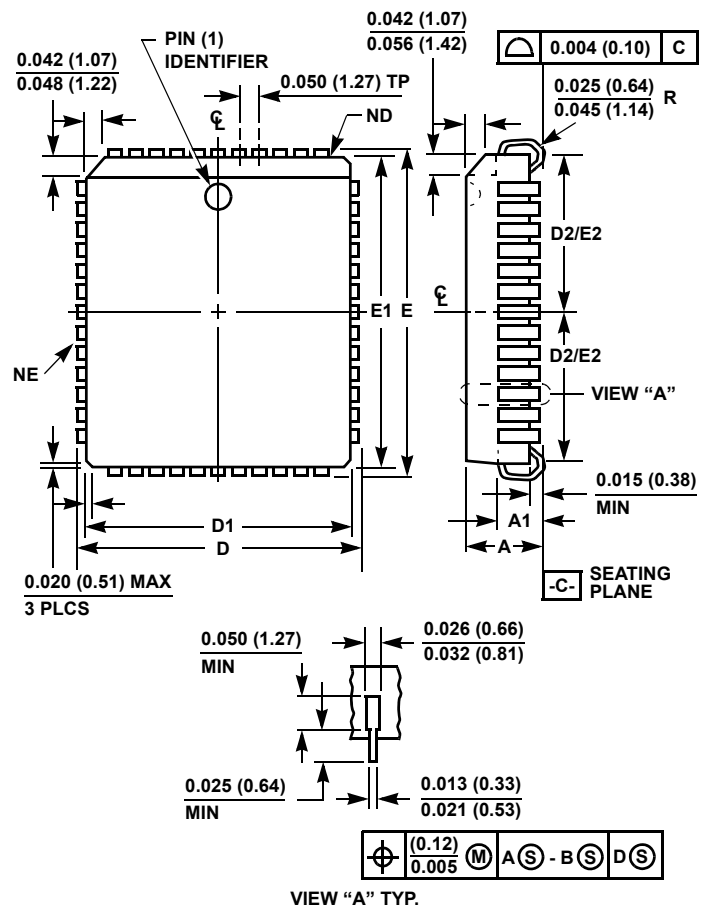
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You may report errors or suggestions for improving this datasheet by visiting [www.intersil.com/ask](http://www.intersil.com/ask).

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## Plastic Leaded Chip Carrier Packages (PLCC)



### N32.45x55 (JEDEC MS-016AE ISSUE A) 32 LEAD PLASTIC LEADED CHIP CARRIER PACKAGE

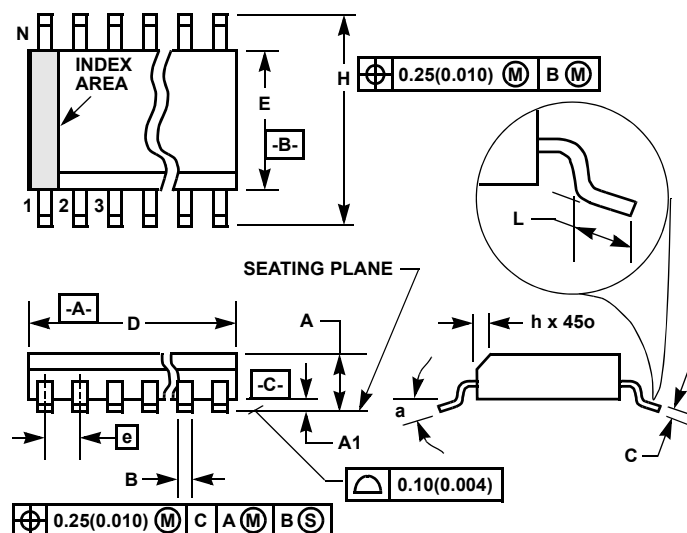
| SYMBOL | INCHES |       | MILLIMETERS |       | NOTES |
|--------|--------|-------|-------------|-------|-------|
|        | MIN    | MAX   | MIN         | MAX   |       |
| A      | 0.125  | 0.140 | 3.18        | 3.55  | -     |
| A1     | 0.060  | 0.095 | 1.53        | 2.41  | -     |
| D      | 0.485  | 0.495 | 12.32       | 12.57 | -     |
| D1     | 0.447  | 0.453 | 11.36       | 11.50 | 3     |
| D2     | 0.188  | 0.223 | 4.78        | 5.66  | 4, 5  |
| E      | 0.585  | 0.595 | 14.86       | 15.11 | -     |
| E1     | 0.547  | 0.553 | 13.90       | 14.04 | 3     |
| E2     | 0.238  | 0.273 | 6.05        | 6.93  | 4, 5  |
| N      | 28     |       | 28          |       | 6     |
| ND     | 7      |       | 7           |       | 7     |
| NE     | 9      |       | 9           |       | 7     |

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#### NOTES:

1. Controlling dimension: INCH. Converted millimeter dimensions are not necessarily exact.
2. Dimensions and tolerancing per ANSI Y14.5M-1982.
3. Dimensions D1 and E1 do not include mold protrusions. Allowable mold protrusion is 0.010 inch (0.25mm) per side. Dimensions D1 and E1 include mold mismatch and are measured at the extreme material condition at the body parting line.
4. To be measured at seating plane  $\square$ -C- contact point.
5. Centerline to be determined where center leads exit plastic body.
6. "N" is the number of terminal positions.
7. ND denotes the number of leads on the two short sides of the package, one of which contains pin #1. NE denotes the number of leads on the two long sides of the package.

## Small Outline Plastic Packages (SOIC)



### M28.3 (JEDEC MS-013-AE ISSUE C)

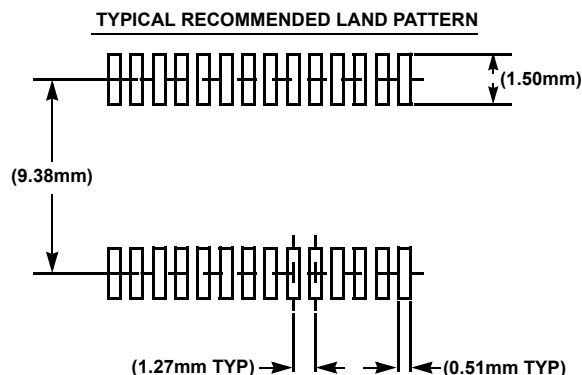
#### 28 LEAD WIDE BODY SMALL OUTLINE PLASTIC PACKAGE

| SYMBOL   | INCHES   |        | MILLIMETERS |       | NOTES |
|----------|----------|--------|-------------|-------|-------|
|          | MIN      | MAX    | MIN         | MAX   |       |
| A        | 0.0926   | 0.1043 | 2.35        | 2.65  | -     |
| A1       | 0.0040   | 0.0118 | 0.10        | 0.30  | -     |
| B        | 0.013    | 0.0200 | 0.33        | 0.51  | 9     |
| C        | 0.0091   | 0.0125 | 0.23        | 0.32  | -     |
| D        | 0.6969   | 0.7125 | 17.70       | 18.10 | 3     |
| E        | 0.2914   | 0.2992 | 7.40        | 7.60  | 4     |
| e        | 0.05 BSC |        | 1.27 BSC    |       | -     |
| H        | 0.394    | 0.419  | 10.00       | 10.65 | -     |
| h        | 0.01     | 0.029  | 0.25        | 0.75  | 5     |
| L        | 0.016    | 0.050  | 0.40        | 1.27  | 6     |
| N        | 28       |        | 28          |       | 7     |
| $\alpha$ | 0°       | 8°     | 0°          | 8°    | -     |

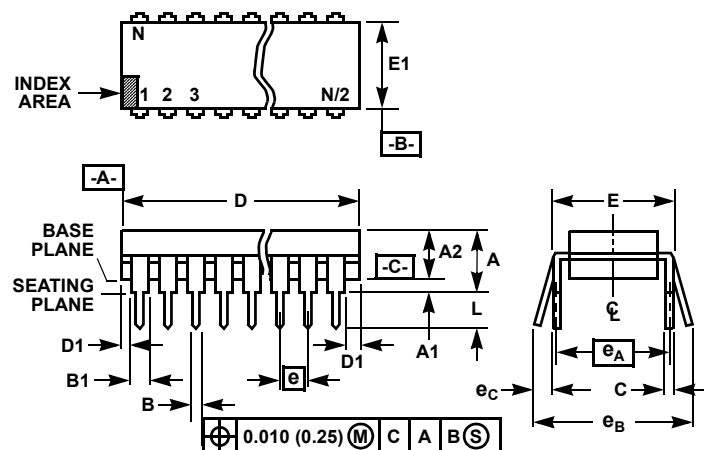
Rev. 1, 1/13

#### NOTES:

1. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication Number 95.
2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
3. Dimension "D" does not include mold flash, protrusions or gate burrs. Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
4. Dimension "E" does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm (0.010 inch) per side.
5. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
6. "L" is the length of terminal for soldering to a substrate.
7. "N" is the number of terminal positions.
8. Terminal numbers are shown for reference only.
9. The lead width "B", as measured 0.36mm (0.014 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61mm (0.024 inch).
10. Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.



## Dual-In-Line Plastic Packages (PDIP)



## NOTES:

1. Controlling Dimensions: INCH. In case of conflict between English and Metric dimensions, the inch dimensions control.
2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
3. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication No. 95.
4. Dimensions A, A1 and L are measured with the package seated in JEDEC seating plane gauge GS-3.
5. D, D1, and E1 dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.010 inch (0.25mm).
6. E and eA are measured with the leads constrained to be perpendicular to datum -C-.
7. eB and eC are measured at the lead tips with the leads unconstrained. eC must be zero or greater.
8. B1 maximum dimensions do not include dambar protrusions. Dambar protrusions shall not exceed 0.010 inch (0.25mm).
9. N is the maximum number of terminal positions.
10. Corner leads (1, N, N/2 and N/2 + 1) for E8.3, E16.3, E18.3, E28.3, E42.6 will have a B1 dimension of 0.030 - 0.045 inch (0.76 - 1.14mm).

**E28.6 (JEDEC MS-011-AB ISSUE B)**  
**28 LEAD DUAL-IN-LINE PLASTIC PACKAGE**

| SYMBOL | INCHES    |       | MILLIMETERS |       | NOTES |
|--------|-----------|-------|-------------|-------|-------|
|        | MIN       | MAX   | MIN         | MAX   |       |
| A      | -         | 0.250 | -           | 6.35  | 4     |
| A1     | 0.015     | -     | 0.39        | -     | 4     |
| A2     | 0.125     | 0.195 | 3.18        | 4.95  | -     |
| B      | 0.014     | 0.022 | 0.356       | 0.558 | -     |
| B1     | 0.030     | 0.070 | 0.77        | 1.77  | 8     |
| C      | 0.008     | 0.015 | 0.204       | 0.381 | -     |
| D      | 1.380     | 1.565 | 35.1        | 39.7  | 5     |
| D1     | 0.005     | -     | 0.13        | -     | 5     |
| E      | 0.600     | 0.625 | 15.24       | 15.87 | 6     |
| E1     | 0.485     | 0.580 | 12.32       | 14.73 | 5     |
| e      | 0.100 BSC |       | 2.54 BSC    |       | -     |
| eA     | 0.600 BSC |       | 15.24 BSC   |       | 6     |
| eB     | -         | 0.700 | -           | 17.78 | 7     |
| L      | 0.115     | 0.200 | 2.93        | 5.08  | 4     |
| N      | 28        |       | 28          |       | 9     |

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